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# Finite Model Theory <br> Lecture 4: Locality, 1-0, Fixed Points 8 November, 2017 

Foundations of Ontologies and Databases for Information Systems CS5130 (Winter 17/18)

Recap of Lecture 3

What the lecturer happens to see in the audience-sometimes
https://www.youtube.com/watch?v=IQgAuBh1BT0 Owl video

- Finite Model Theory approach
- consider DBs as finite structures
- FOL as query language
- FOL works because
- Though FOL model checking in PSPACE w.r.t. combine complexity
- it is in $A C^{0}$ for data complexity
- Inexpressivity Tools
- Games as basic tool for proving inexpressivity
- Reduction tricks


## End of Recap

## Locality

## Proving Inexpressibility by Locality

- FOL has a fundamental property: locality
- Observation
- Consider a binary query $Q: \operatorname{STRUCT}(\sigma) \longrightarrow \operatorname{STRUC}($ ans $)$ to be defined in FOL
- So, we need a formula $\phi_{Q}$ in two open variables $x, y$
- The way how to describe constraints between $x$ and $y$ is restricted by the number of atoms and elements occurring in $\phi_{Q}$.
- Different (comparable) locality notions
- Bounded number of degrees property (BNDP)
- Gaifman locality
- Hanf locality


## Proving Inexpressibility by Locality

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- Gaifman locality
- Hanf locality


## BNDP

- in $(\mathfrak{G})=$ set of in-degrees of nodes in $\mathfrak{G}$
- $\operatorname{out}(\mathfrak{G})=$ set of out-degrees of nodes in $\mathfrak{G}$
- $\operatorname{degs}(\mathfrak{G})=\operatorname{in}(\mathfrak{G}) \cup \operatorname{out}(\mathfrak{G})$


## Definition

$Q$ has the bounded number of degrees property (BNDP) iff there is $f_{Q}: \mathbb{N} \longrightarrow \mathbb{N}$ s.t. for all graphs $\mathfrak{G}:$
If there is $k \in \mathbb{N}$ s.t. $\max (\operatorname{degs}(\mathfrak{G})) \leq k$, then $|\operatorname{degs}(Q(\mathfrak{G}))| \leq f_{Q}(k)$.

- Intuitively: $Q$ disallowed to arbitrarily increase degrees of nodes


## Theorem

Every FOL query has the BNDP.

## Example: TC on Successor Relation Graph

- $\mathfrak{G}=\left(\left\{a_{0}, \ldots, a_{n}\right\},\left\{E\left(a_{0}, a_{1}\right), \ldots, E\left(a_{n-1}, a_{n}\right)\right\}\right)$
- $\operatorname{in}(\mathfrak{G})=\operatorname{out}(\mathfrak{G})=\{0,1\}$
- $\operatorname{in}(T C(\mathfrak{G}))=\operatorname{out}(T C(\mathfrak{G}))=\{0, \ldots, n-1\}$
$\mathfrak{G}$

$T C(\mathfrak{G})$



## It's (sometimes) sufficient to Consider Graphs Only

## Definition (Gaifman Graph)

For any $\sigma$ structure $\mathfrak{A}$ one can define the Gaifman graph
$\mathfrak{G}=(G, E)$ as follows:

- $G=\operatorname{dom}(\mathfrak{A})$
- There is an edge between two elements $a, b$ of $\mathfrak{A}$ iff they co-occur within a relation of $\mathfrak{A}$, formally:
$(a, b) \in E^{\mathfrak{G}}$ iff $a \neq b$ and there is some ( $n$-ary) relation $R^{\mathfrak{A}}$ and a tuple $a_{1}, \ldots, a_{n}$ such $a, b$ are among those elements and $a_{1}, \ldots, a_{j-1}$ such that $\left(a_{1}, \ldots, a_{n}\right) \in R^{\mathfrak{A}}$
- $d(a, b)=$ distance between two vertices $a, b=$ path of minimal length between $a, b$
 of vertices $\bar{a}$


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- $d(a, b)=$ distance between two vertices $a, b=$ path of minimal length between $a, b$
- $d(\bar{a}, b)=\min _{a_{i} \in \bar{a}}\left\{d\left(a_{i}, b\right)\right\}=$ distance of vertex $b$ from tuple of vertices $\bar{a}$


## Gaifman locality

Gaifman locality defined here on graphs $\mathfrak{G}=(G, E)$ (can be generalized to arbitrary structures with Gaifman graph)

## Gaifman Locality (Intuitively)

An m-ary query $Q$ is Gaifman local iff there is a threshold (radius) $r$ such that for all graphs:
$Q$ cannot distinguish between tuples if their $r$-neighbourhoods in the graph are the same.

## Theorem

Every FOL-definable query is Gaifman local.

## Gaifman Locality

- $\bar{a}=\left(a_{1}, \ldots, a_{n}\right) \in G^{n}$
(vector of elements)
subgraph induced by $B_{r}^{\mathfrak{G}}(\bar{a})$ in the structure ( $G, E, \bar{a}$ )


## Gaifman Locality

- $\bar{a}=\left(a_{1}, \ldots, a_{n}\right) \in G^{n}$
(vector of elements)
- $B_{r}^{\mathfrak{G}}(\bar{a})=\{b \in G \mid d(\bar{a}, b) \leq r\}$
(radius $r$ ball around $\bar{a}$ )


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- $N_{r}^{\mathscr{G}}(\bar{a})$
(r-neighbourhood of $\bar{a}$ ) subgraph induced by $B_{r}^{\mathscr{G}}(\bar{a})$ in the structure $(G, E, \bar{a})$


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## (radius $r$ ball around $\bar{a}$ )

- $N_{r}^{\mathscr{G}}(\bar{a})$ (r-neighbourhood of $\bar{a}$ ) subgraph induced by $B_{r}^{\mathscr{G}}(\bar{a})$ in the structure ( $G, E, \bar{a}$ )
- Note: $(G, E, \bar{a})$ is a graph where some elements (namely that of $\bar{a}$ ) are named by constants: they are fixed
- In $N_{r}^{\mathfrak{G}}(\bar{a})$ the elements $\vec{a}$ have the same names as in ( $G, E, \bar{a}$ ) (say $c_{1}, \ldots c_{n}$ ) and the there is an edge between a pair of elements $B_{r}^{\mathscr{G}}(\bar{a})$ iff there is an edge in $(G, E, \bar{a})$ between them


## Gaifman Locality

- $\bar{a}=\left(a_{1}, \ldots, a_{n}\right) \in G^{n}$
(vector of elements)
- $B_{r}^{\mathfrak{G}}(\bar{a})=\{b \in G \mid d(\bar{a}, b) \leq r\}$
(radius $r$ ball around $\bar{a}$ )
- $N_{r}^{\mathfrak{E}}(\bar{a})$
(r-neighbourhood of $\bar{a}$ )
subgraph induced by $B_{r}^{\mathfrak{B}}(\bar{a})$ in the structure $(G, E, \bar{a})$


## Definition

An $m$-ary query $Q$ (with $m>0$ ) is Gaifman-local iff:
There exists a radius $r$ s.t. for all $\mathfrak{G}$ : If $N_{r}^{\mathfrak{G}}(\bar{a}) \simeq N_{r}^{\mathfrak{G}}(\bar{b})$, then $\bar{a} \in Q(\mathfrak{G})$ exactly when $\bar{b} \in Q(\mathfrak{G})$.

## Example: TC is not Gaifman local



## Proof

- Suppose TC were FOL definable with query $Q$
- Then $Q$ would be Gaifman local with some radius $r$
- $N_{r}^{\mathfrak{G}}((a, b)) \simeq N_{r}^{\mathfrak{G}}((b, a))$
because both subgraphs are disjoint unions of two 2 r-chains
- But $(a, b) \in T C(\mathfrak{G})$ and $(b, a) \notin T C(\mathfrak{G})$, ,


## Hanf locality

## Definition (Hanf locality (informally))

A Boolean query $Q$ is Hanf-local iff there is a threshold (radius) $r$ s.t. any pair of graphs $\mathfrak{G}, \mathfrak{G}^{\prime}$ that can be made pointwise similar w.r.t. $r$-neighbourhoods cannot be told apart by $Q$.

- Have to make precise "pointwise similar"


## Hanf locality

- $\mathfrak{G}=(A, E), \mathfrak{G}^{\prime}=\left(A^{\prime}, E^{\prime}\right)$
- $\mathfrak{G} \rightleftarrows_{r} \mathfrak{G}^{\prime}$ iff there exists bijection $f: A \longrightarrow A^{\prime}$ s.t. for all $a \in A$ : $N_{r}^{\mathfrak{G}}(a) \simeq N_{r}^{\mathfrak{B}^{\prime}}(f(a))$


## Definition (Hanf locality (formal))

A Boolean query $Q$ is Hanf-local iff a radius $r$ exists s.t. for any graphs $\mathfrak{G}, \mathfrak{G}^{\prime}$ with $\mathfrak{G} \rightleftarrows_{r} \mathfrak{G}^{\prime}$ one has $Q(\mathfrak{G})=Q\left(\mathfrak{G}^{\prime}\right)$.

## Theorem

Every FOL definable Boolean query is Hanf-local.

## Example: CONN is not Hanf-local



## Proof

- For contradiction assume CONN is Hanf-local with parameter $r$
- Choose $m>2 r+1$; $f$ an arbitrary bijection of $\mathfrak{G}$ and $\mathfrak{G}^{\prime}$
- $r$-neighbourhood of any a the same: $2 r$-chain with $a$ in the middle
- Hence $\mathfrak{G} \rightleftarrows_{r} \mathfrak{G}^{\prime}$, but: $\mathfrak{G}^{\prime}$ is connected and $\mathfrak{G}$ is not. 4


## Comparison of Locality Notions

Theorem
Hanf local $\vDash$ Gaifmann local $\vDash B N D P$

## Optional Slide: Adding Order

- Many applications have finite models with a linear order $<$
- Locality conditions in its original form not applicable: 1-radius already whole structure
- Consider invariant queries


## Definition

A query $Q$ over ordered structures is invariant iff for all structures $\mathfrak{A}$, all tuples $\bar{b}$ and all linear orders $<_{1},<_{2}$ on $\mathfrak{A}$ :
$\bar{b} \in Q\left(\left(\mathfrak{A},<_{1}\right)\right)$ iff $\bar{b} \in Q\left(\left(\mathfrak{A},<_{2}\right)\right)$
For an invariant $Q$ define $Q_{i n v}$ on arbitrary structures as:
$Q_{\text {inv }}(\mathfrak{A})=Q((\mathfrak{A},<))$ for arbitrarily chosen $<$.
$Q_{\text {inv }}$ called invariant FO-query.

## Theorem

Every invariant FOL query is Gaifman-local (and so has BNDP).

## 0-1 law

## 0-1 law

An inexpressibility tool based on a probabilistic property of FOL queries

## 0-1-law informally

Either almost all finite structures fulfill the property or almost all do not

## Example

Consider the following boolean queries on graphs

- $Q_{1}=\forall x, y E(x, y)$

Almost all graphs do not satisfy $Q_{1}$ (only the complete ones)

- $Q_{2}=\forall x \forall y \exists z E(z, x) \wedge \neg E(z, y)$

Almost all graphs satisfy $Q_{2}$

## Formal definition 0-1 laws

- Here it is important that signature $\sigma$ is relational!!
- $\operatorname{STRUC}(\sigma, n)$ : structures with domain $[n]:=\{0,1, \ldots, n-1\}$ over $\sigma$.
- For a Boolean query $Q$ let

$$
\mu_{n}(Q)=\frac{|\{\mathfrak{A} \in \operatorname{STRUC}(\sigma, n) \mid Q(\mathfrak{A})=\operatorname{true}\}|}{|\operatorname{STRUC}(\sigma, n)|}
$$

- $\mu_{n}(Q)$ is the probability that a randomly chosen structure on $[n]$ satisfies $Q$
- $\mu(Q)=\lim _{n \rightarrow \infty} \mu_{n}(Q)$


## Definition

A logic has the 0-1-law if for every Boolean query $Q$ expressible in it either $\mu(Q)=0$ or $\mu(Q)=1$.

## Inexpressibility with 0-1 laws

## Theorem

FOL has the 0-1-law.

- Helpful for proving inexpressibility of counting properties


## Example (EVEN is not expressible in FOL)

$\mu(E V E N)$ not defined because $\mu_{n}(E V E N)$ alternates between 0 and 1.

Let me add a "footnote" on the general strategy of using the 0-1 law $\odot$
https://www.youtube.com/watch?v=jWinRjU7Kb0 Locally stored video

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Locally stored video
OK, now the real footnote-on the next slide

## Probability and Logic

- The 0-1 law exemplifies a general strategy of using methods for handling uncertainty (probability theory) in order to solve crisp questions (here: FOL expressibility)
- Compare "probabilistic method" as applied to combinatorics
- Also called "Erdös method"
- Take a time to learn about the great Hungarian mathematician Erdös, e.g., from biography "The man who loved only numbers" http://www.nytimes.com/ books/first/h/hoffman-man.html


Beyond FOL

## Counting, Aggregation

- Practical languages s.a. SQL allow counting and aggregation.


## Example (Departments with Average Salary $>100,000$ )

SELECT S1.Dept, AVG(S2.Salary)
FROM S1, S2
WHERE S1.Empl = S2.Empl
GROUP BY S1.Dept
HAVING SUM(S2.Salary) > 1000
Schema: S1(Empl, Dept), S2(Empl,Salary)

- Consider corresponding extensions of FOL
- Some of the tools shown so far still work (when non-ordered structures are considered)


## FOL with counting quantifiers

## Definition (FOL-AllCnt)

FOL-AllCnt is the extension of FOL with counting quantifiers and counting terms:

- $\exists^{\geq i} x \cdot \phi(x)$ : There are at least $i$ elements $x$ fulfilling $\phi$.
- $\forall \bar{x} \cdot \phi(\bar{x})$ : the number of $\bar{x}$ fulfilling $\phi(\bar{x})$.
- Semantics defined w.r.t. 2-sorted FOL structures $\mathfrak{A}=\left(A, \mathbb{N},\left(R^{\mathfrak{A}}\right)_{R \in \sigma}\right.$, Arith $)$
- Second domain (sort) $\mathbb{N}$ is infinite!
- Arith contains (interpreted) arithmetic predicates and functions


## Example

Parity of a unary predicate symbol $U$ can be expressed by the following formula using counting quantifiers:

$$
\exists j \exists i\left((i+i=j) \wedge \exists^{\geq j} x U(x) \wedge \forall k\left(\exists^{\geq k} x U(x) \rightarrow k \leq j\right)\right)
$$

"There is an even number $(j)$ of Us and there are no more than $j$ Us"

## Theorem

FOL +AllCtn queries are Hanf local (and thus Gaifman local and have the BNDP).

## Aggregation

- $\mathcal{F}=$ aggregate function $=$ family of functions $f_{1}, f_{2}, \ldots$ with
- $f_{n}$ maps $n$-element multisets from $\mathbb{Q}$ to elements from $\mathbb{Q}$.
E.g.: $\operatorname{SUM}=\left\{s_{1}, s_{2}, \ldots,\right\}$ with $s_{k}\left(\left\{d_{1}, \ldots, d_{k}\right\}\right)=\sum_{i=1}^{k} d_{i}$


## Definition (FOL-Aggr)

FOL-Aggr same as FOL+AllCnt but with aggregate terms (and $\mathbb{Q}$ instead of $\mathbb{N}$ ).

- Syntax: Terms $t(\bar{x})$ of the form $\operatorname{Aggr}_{F} \bar{y} .\left(\phi(\bar{x}, \bar{y}), t^{\prime}(\bar{x}, \bar{y})\right)$
- Not eh possibility of nesting with term $t^{\prime}$ (as in SQL)
- Semantics over $\mathfrak{A}$ for tuple $\bar{b}$
 (where $B:=\{\bar{c} \mid \mathfrak{A} \models \phi(\bar{b}, \bar{c})\}$ )

Correspondence to SQL:

- $\bar{x}=$ grouping attributes
- $\phi(\bar{x}, \bar{y})=$ HAVING clause


## Locality for FOL+Aggr

## Theorem

FOL-Aggr queries are Hanf-local (and thus Gaifmann-local and have the BNDP).

- If order is added, then locality is lost


## Higher-Order Logics

- Second order logic (SO): Allow quantification over relations
- Vocabulary: FOL vocabulary + predicate variables $X, Y, \ldots$
- Syntax: FOL syntax +
- $X t_{1} \ldots t_{n}$ is a formula (for $n$-ary relation variable $X$ and terms $t_{i}$ )
- If $\phi$ is a formula, then so are $\exists X \phi, \forall X \phi$
- Higher-order quantification adds expressivity, e.g.,
- $\operatorname{EVEN}(\sigma)$ (for any signature $\sigma$, in particualr for $\sigma=\{ \}$ ) expressible. (Exercise)


## Fixed Point Logics (FPLs)

- Reachability queries call for extension of FOL with "iteration" mechanism
- FPLs use a well-behaved self-referential process/bootstrapping
- Fixed points as limits of this process
- Different fixed points may exist
- Different fixed point logics exist (e.g. largest, least)
- Most prominent in DB theory: Datalog


## Example: Compute the Transitive Closure

- $E(x, y)=$ edge of graph $\mathfrak{G}$,
- $R(x, y)=$ transitively closed relation between vertices

$$
\forall x, \forall y R(x, y) \leftrightarrow E(x, y) \vee(\exists z . E(x, z) \wedge R(z, y))
$$

- For all graphs $\mathfrak{G}$ find extension $\mathfrak{G}^{\prime}=\left(\mathfrak{G}, R^{\mathfrak{G}^{\prime}}\right)$ s.t. Ihs and rhs evaluate to the same relation.
- Read equivalence as a iteratively applied rule from right to left

$$
X_{\text {new }}(x, y) \leftarrow \underbrace{E(x, y) \vee\left(\exists z \cdot E(x, z) \wedge X_{\text {old }}(z, y)\right)}_{\phi\left(x, y, X_{\text {old }}\right)}
$$

- Induces a step(-jump)-operator $F$ on the semantical side
- For $X \subseteq G \times G$ :

$$
F: X \mapsto\left\{\left(d_{1}, d_{2}\right) \mid\left(\mathfrak{G}, X, x / d_{1}, y / d_{2}\right) \models \phi(x, y, X)\right\}
$$

- Condition $\left(^{*}\right)$ reread: find fixed point $R$, i.e., $F(R)=R$


## Constructing Least Fixed Points

- Start with extension $\emptyset$ (seed) and proceed iteratively
- Progress schema: $\emptyset, F(\emptyset), F(F(\emptyset)), F^{3}(\emptyset), F^{4}(\emptyset), \ldots$
- In our example
- $X^{0}=$ seed $=\emptyset$
- $X^{1}=E^{\mathfrak{G}}=$ direct edges
- $X^{2}=F\left(X^{1}\right)=X^{1} \cup\left\{(x, y) \mid \exists z \cdot E(x, z) \wedge X^{1}(z, y)\right\}=$ direct edges or paths of length 2
- $R^{\mathfrak{G}^{\prime}}=\bigcup_{i \in \mathbb{N}} X^{i}$
- The fixed point here is the least fixed point.
- Nota bene
- A fixed point may not exist
- There may be many fixed points
- There may not be a least fixed point. (Exercise)


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## Fixed Point Construction Graphically

- Fixed point for $F(x)=\cos (x)$.
- Attractor


[^0]//commons.wikimedia.org/wiki/File:Cosine_fixed_point.svg\#/media/File:Cosine_fixed_point.svg

## Recursive Humor

- Wiki entry Recursive humor. It is not unusual for such books to include a joke entry in their glossary along the lines of: Recursion, see Recursion.[6] [...] An alternative form is the following, from Andrew Plotkin: "If you already know what recursion is, just remember the answer. Otherwise, find someone who is standing closer to Douglas Hofstadter than you are; then ask him or her what recursion is."
Lit: D. Hofstadter. Gödel, Escher, Bach: An Eternal Golden Braid.Vintage Books, 1979.

- Blog Recursively Recursive

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https://recursivelyrecursive.wordpress.com/category/
recursive-humour/page/2/
```


## Datalog

- Developed around 1980s
- Renaissance (not only as proof tool but) as industrially applied tool
- EXPTIME-complete in combined complexity; PTIME-complete data complexity
- Simple evaluation strategy for positive fragment (no negation)
- Negation calls for hierarchical evaluation (stratification)
- Different fragments; optimizations ...


## Datalog

- General Logic Programm: Finite set of rules of the form

$$
\underbrace{\alpha}_{\text {head }} \leftarrow \underbrace{\beta_{1}, \ldots, \beta_{n}}_{\text {body }}
$$

- $\alpha$ atomic formula; $\beta_{i}$ are literals
- Free variables $\forall$ quantified; comma, read as $\wedge$
- Intensional relation: Relation symbol occurring in some head
- Extensional relation: occurring only in body

```
- Datalog program = logic program with
- no function symbols
* no intensional relation negated in body
- Sometimes additionally
    * all free variables in head also in body
    * all variables in negated atoms (or arithmetical expressions
    such as identity) also in non-negated atom in body
* Semantics for datalog programs: by step-operator used in
parallel for intensional relations
```


## Datalog

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- Free variables $\forall$ quantified; comma, read as $\wedge$
- Intensional relation: Relation symbol occurring in some head
- Extensional relation: occurring only in body
- Datalog program $=$ logic program with
- no function symbols
- no intensional relation negated in body
- Sometimes additionally safety constraints:
- all free variables in head also in body
- all variables in negated atoms (or arithmetical expressions such as identity) also in non-negated atom in body
- Semantics for datalog programs: by step-operator used in parallel for intensional relations


## Datalog example: ancestors of Mary

$$
\begin{aligned}
\operatorname{ans}(x) & \leftarrow \operatorname{ancestor}(x, \text { mary }) \\
\text { ancestor }(x, y) & \leftarrow \operatorname{parentOf}(x, y) \\
\text { ancestor }(x, y) & \leftarrow \operatorname{parentOf}(x, z), \text { ancestor }(z, y)
\end{aligned}
$$

In FOL notation:

$$
\begin{array}{r}
\forall x \operatorname{ancestor}(x, \text { mary }) \rightarrow \operatorname{ans}(x) \\
\forall x \forall y \text { parentOf }(x, y) \rightarrow \operatorname{ancestor}(x, y) \\
\forall x, \forall y(\exists z \text { parentOf }(x, z), \operatorname{ancestor}(z, y)) \rightarrow \operatorname{ancestor}(x, y)
\end{array}
$$

## SQL 3 Recursion example

\%Find Mary's ancestors from ParentOf (parent, child)
WITH RECURSIVE Ancestor (anc, desc) AS
( (SELECT parent as anc, child as desc FROM ParentOf) UNION
(SELECT Ancestor.anc, ParentOf.child as desc FROM Ancestor, ParentOf WHERE Ancestor.desc = ParentOf.parent) )
SELECT anc FROM Ancestor WHERE desc = "Mary"

## FOL with Least Fixed Points

- Datalog extends FOL w.r.t. the semantics (subkutane)
- There are different extensions of FOL with fixed point operators available in the syntax
- Example $\exists F O$ (LFP): existential fragment of FOL extended with relation variables and with least fixed point operator $\left[L F P_{\vec{y}, Y} \phi\right]$


## $\exists F O(L F P)$

- Syntax: $F O R M_{\exists F O(L F P)}=$ set of $\exists F O(L F P)$ formulae
- Every second-order atomic formula is in $F O R M_{\exists F O}(L F P)$
- $\neg \phi$ for $\phi$ an atomic FOL formula
- $\phi \wedge \psi \in \operatorname{FORM}_{\exists F O(L F P)}$
- $\phi \vee \psi \in \operatorname{FORM}_{\exists F O(L F P)}$
- $\exists x \phi \in F O R M_{\exists F O(L F P)}$ (only (existential) quantification over first-order variables)
- $\left[L F P_{\vec{x}, X} \phi\right] \vec{t}$
- Semantics
- ...
- $\mathfrak{A} \models\left[L F P_{\vec{x}, X} \phi\right] \vec{t}$ iff
"For $X$ chosen as least fixed point, $\vec{t}$ fulfills $\phi$ in $\mathfrak{A}$ "
- Restriction: $X$ has to occur positively (i.e. after an even number of $\neg$ in $\phi$ )
(Needed to guarantee existence of Ifp)


## Theorem

Existential fragment of $\exists F O(L F P)$ is equivalent to Datalog.

## 0-1 law for Datalog

Theorem
Datalog (without negation and ordering) has the 0-1 law.

- In particular you can not express EVEN
- (Adding negation allows to express EVEN, which does not fulfill 0-1 law)
- In fact a successor relation together with min- and max-predicates is sufficient.



## 0-1 law for Datalog

## Theorem

Datalog (without negation and ordering) has the 0-1 law.

- In particular you can not express EVEN
- (Adding negation allows to express EVEN, which does not fulfill 0-1 law)
- In fact a successor relation together with min- and max-predicates is sufficient.

$$
\begin{aligned}
\operatorname{odd}(x) & \leftarrow \min (x) \\
\operatorname{odd}(x) & \leftarrow S(x, y), \operatorname{even}(y) \\
\operatorname{even}(x) & \leftarrow S(y, x), \operatorname{odd}(y) \\
\text { EVEN } & \leftarrow \max (x), \operatorname{even}(x)
\end{aligned}
$$

## What we Did not Cover

Very many FMT topics were not covered in these two lectures, in particular ...

- Descriptive Complexity
- Algorithmic Model Theory (Infer meta-theorems on algorithmic properties by constraining some input parameters (parameterized complexity) )
- Proving equivalence of languages (using types)


## Descriptive Complexity

- There is a close relationship between complexity classes and logics (queries expressible in a logic)
- Hints to astonishing correspondences between prima facie two different worlds
- The world of representation (what?) and of calculation (how?)
- Results talk about data complexity (!)
- Results mainly for ordered structures


## Fagin lays the foundations

- One of the first insights which founded descriptive complexity goes back to Fagin


## Theorem ( captures NPTIME)

Existential second order logic (SOヨ) captures the class of problems verifiable in polynomial time (NP)
$S O \exists=$ second order logic where second order quantifiers are restricted to $\exists$

## Definition

A logic $\mathcal{L}$ captures a complexity class $\mathcal{C}$ iff for all $\sigma$ with $<\in \sigma$ and classes of structures $K \subseteq \operatorname{STRUC}(\sigma)$ :

$$
K \in \mathcal{C} \text { iff } K \text { is axiomatizable in } \mathcal{L}
$$



The Descriptive World
(Immerman: Descriptive Complexity, ACM SIGACT NEWS, vol. 34, no. 3, 2003, p.5)

## Solutions to Exercise 3 (12 Points)

## Ad Exercise 3.1 (4 Points)

Give at least two aspects of real DBs for which the approach of identifying DBs with finite FOL structures is not sufficient or adequate.

- DBs may have NULL values (but structures are not incomplete). So one has to argue with completions of DBs. (See lecture on data exchange)
- Domain of the structure corresponding to a DB is not explicitly specified
- Natural (as in FOL) vs. active domain semantics (consider only those constants occurring in a DB as potential element of the domain)
- Safety considerations needed for FOL (not the case for relational calculus/SQL)
- One can show: FOL under active domain semantics the same as SQL
- Nonetheless: It means dependency on domain.


## Ad Exercise 3.2 (4 Points)

Argue why the usual restriction in FMT to consider only relational structures (i.e., no function symbols allowed) is not problematic. That is more formally: How can formulae with function symbols be represented by formulae containing only relation symbols (in particular the identity relation)?

- For every $n$-ary functional symbol $f$ introduce $n+1$-ary relation symbol $R_{f}$ and state that $R_{f}$ is a function:

$$
\begin{aligned}
& \forall x_{1}, \ldots \forall x_{n-1} \exists y_{1} R_{f}\left(x_{1}, \ldots, x_{n}, y_{1}\right) \wedge \\
& \forall y_{1}, y_{2} R\left(x_{1}, \ldots, x_{n}, y_{1}\right) \wedge R\left(x_{1}, \ldots, x_{n}, y_{2}\right) \rightarrow y_{1}=y_{2}
\end{aligned}
$$

- Then recursively eliminate all terms by substituting atoms of the form
- $f\left(\vec{t}_{1}\right)=t_{2}$ with $R_{f}\left(\vec{t}_{1}, t_{2}\right)$
- $S\left(f_{1}\left(\vec{t}_{1}\right), \overrightarrow{t_{2}}, \ldots, \vec{t}_{n}\right)$ with $\exists x S\left(x, \vec{t}_{2}, \ldots, \vec{t}_{n}\right) \wedge R_{f}\left(t_{1}, x\right)$ and so on.


## Ad Exercise 3.3 (4 Points): Reduce EVEN $(<)$ to Graph Connectivity

Formalize the reduction query $Q_{\text {red }}:$ LinOrd $\rightarrow$ GRAPH from linear orders to graphs by describing a query formula inducing $Q_{\text {red }}$.


## Ad Exercise 3.3 (4 Points): Reduce EVEN $(<)$ to Graph Connectivity

Formalize the reduction query $Q_{\text {red }}:$ LinOrd $\rightarrow$ GRAPH from linear orders to graphs by describing a query formula inducing $Q_{\text {red }}$.


- Construction of graph from linear order expressible as an FOL query $Q_{\text {red }}:$ LinOrd $\longrightarrow$ GRAPH


## Ad Exercise 3.3 (4 Points)

- Helper formulae
- $\operatorname{succ}(x, y): x<y \wedge \neg \exists z . x<z \wedge z<y$
- last(x): $\neg \exists z . x<z$
- $\operatorname{first}(x): \neg \exists z . z<x$
- Define $Q_{\text {red }}:$ LinOrd $\longrightarrow$ GRAPH as

$$
\begin{aligned}
E(x, y)= & \psi(x, y)= \\
& (\exists z(\operatorname{succ}(x, z) \wedge \operatorname{succ}(z, y))) \vee \\
& (\operatorname{last}(x) \wedge \exists z(\operatorname{first}(z) \wedge \operatorname{succ}(z, y))) \vee \\
& (\exists z(\operatorname{last}(z) \wedge \operatorname{succ}(x, z) \wedge \operatorname{first}(y)))
\end{aligned}
$$

- Assume that CONN is expressible as FOL query $\phi_{\text {conn }}$ over signature $\{E\}$ for graphs.
- Then EVEN $(<)$ would be FOL expressible as:
$\phi_{\text {conn }}[E / \psi]$ z
(Note: $\phi_{\text {conn }}[E / \psi]$ is shorthand for replacing every occurrence of atom $E(u, w)$ by formula $\psi(u, w)$ in $\phi_{\text {conn. }}$.)


## Exercise 4 (16 Points)

## Exercise 4.1 (6 Points)

Use Hanf locality in order to proof that the following boolean queries are not FOL-definable.

1. Is a given graph acyclic?
2. Is a given graph a tree?

## Exercise 4.2 (4 Points)

Show that $\operatorname{EVEN}(\sigma)$ can be defined within second-order logic for any $\sigma$.
Hint: formalize "There is a binary relation which is an equivalence relation having only equivalence classes with exactly two elements" and argue why this shows the axiomatizability.

## Exercise 4.3 (2 Points)

Argue why (in particular within the DB community) one imposes safety conditions for Datalog rules.

## Exercise 4.4 (4 points)

Give examples of general program rules for which

1. No fixed point exists at all (Hint: "This sentence is not true")
2. Has two minimal fixed points (Hint: "The following sentence is false. The previous sentence is false.")

[^0]:    "Cosine fixed point". Licensed under CC BY-SA 3.0 via Wikimedia Commons - https:

