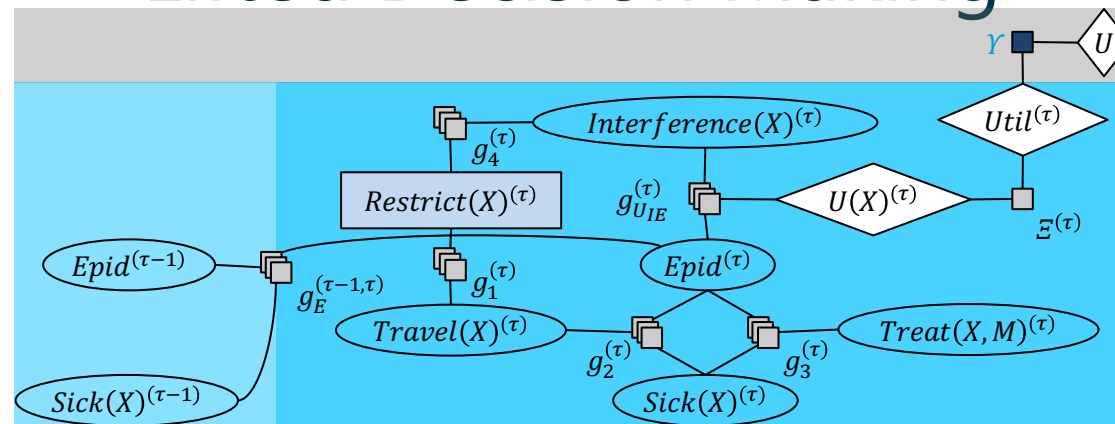


Dynamic Probabilistic Relational Models

Lifted Decision Making



Marcel Gehrke

Contents

1. Introduction

- StaRAI: Agent, context, motivation

2. Foundations

- Logic
- Probability theory
- Probabilistic graphical models (PGMs)

3. Probabilistic Relational Models (PRMs)

- Parfactor models, Markov logic networks
- Semantics, inference tasks

4. Exact Lifted Inference

- Lifted Variable Elimination
- Lifted Junction Tree Algorithm
- First-Order Knowledge Compilation

5. Lifted Sequential Models and Inference

- Parameterised models
- Semantics, inference tasks, algorithm

6. Lifted Decision Making

- Preferences, utility
- Decision-theoretic models, tasks, algorithm

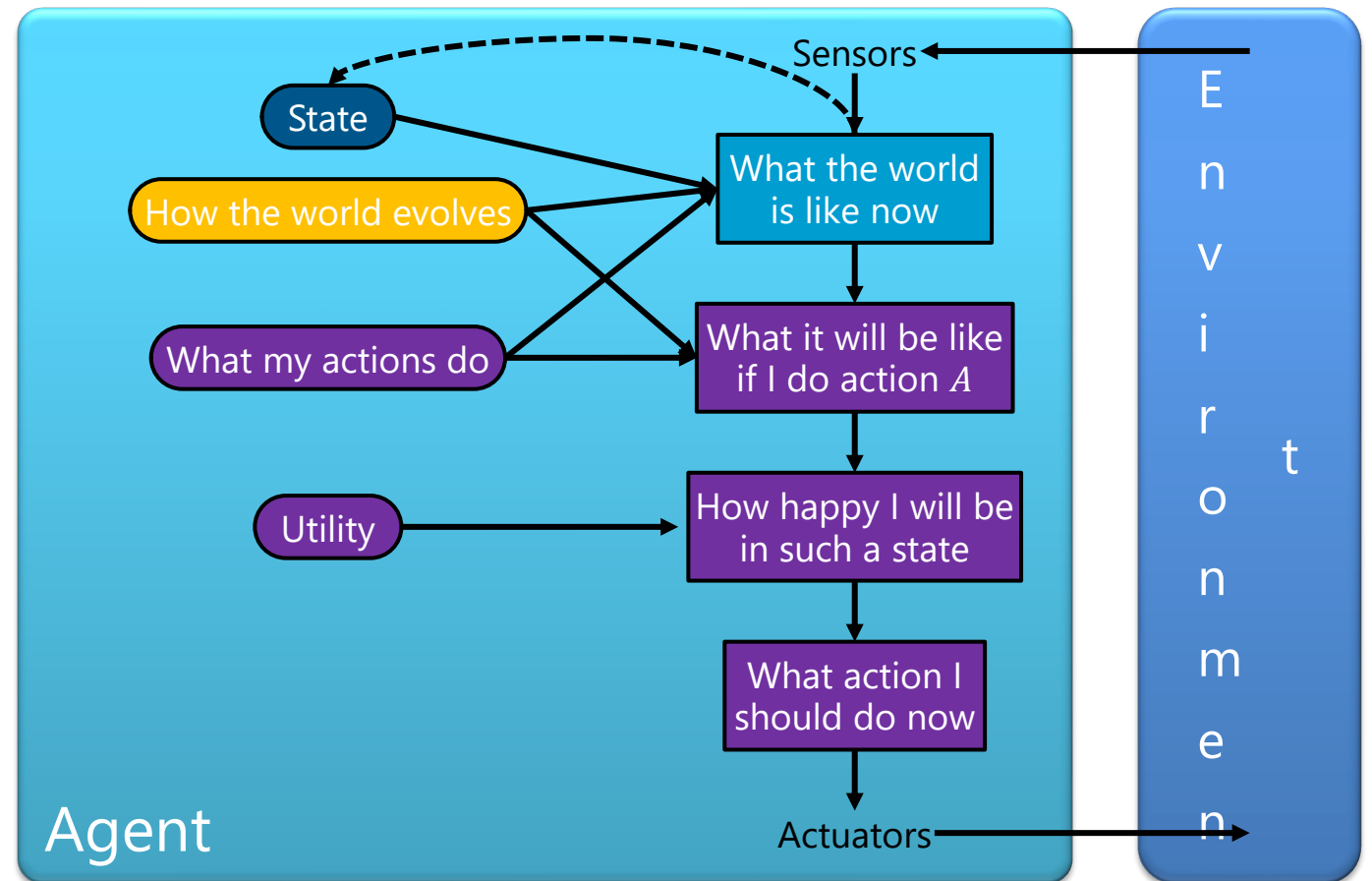
7. Approximate Lifted Inference

8. Lifted Learning

- Parameter learning
- Relation learning
- Approximating symmetries

Contents in this Lecture Related to *Utility-based Agents*

- Further topics
 3. (Episodic) PRMs
 4. Lifted inference (in episodic PRMs)
 5. Lifted sequential PRMs and inference
 6. Lifted decision making
 7. Lifted learning (of episodic PRMs)



Setting

- Agent can perform actions in an environment
 - Episodic, i.e., not sequential, environment
 - Next episode does not depend on the previous episode
 - Or sequential environment
 - Non-deterministic environment
 - Outcomes of actions not unique
 - Associated with probabilities
→ **probabilistic** model
 - Partially observable
 - Latent, i.e., not observable, random variables
- Agent has **preferences** over states / action outcomes
 - Encoded in utility or utility function → **Utility theory**
- “**Decision theory** = Utility theory + Probability theory”
 - Model the world with a probabilistic model
 - Model preferences with a utility (function)
 - Find action that leads to the maximum expected utility, also called decision making

Outline: 7. Lifted Decision Making

A. *Utility theory*

- Preferences, maximum expected utility (MEU) principle
- Utility function, multi-attribute utility theory

B. *Static decision making*

- Modelling, semantics, inference tasks
- Inference algorithm: LVE for MEU as an example

C. *Sequential decision making*

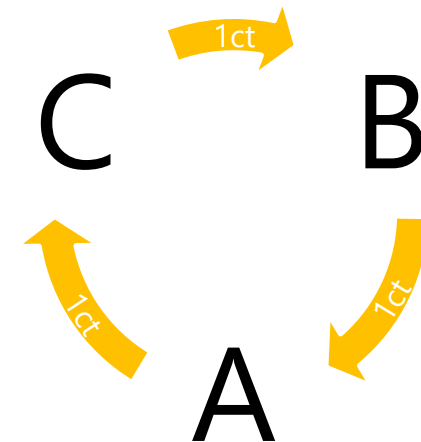
- Modelling, semantics, temporal MEU problem
- Inference algorithm: LDJT for MEU as an example
- Acting

Preferences

- An agent chooses among **prizes** (A, B , etc.) and **lotteries**, i.e., situations with uncertain prizes
 - Outcome of a nondeterministic action is a lottery
- Lottery $L = [p, A; (1 - p), B]$
 - A and B can be lotteries again
 - Prizes are special lotteries: $[1, R; 0, \text{not } R]$
 - More than two outcomes:
 - $L = [p_1, S_1; p_2, S_2; \dots; p_M, S_M], \sum_{i=1}^M p_i = 1$
- Notation
 - $A \succ B$ A preferred to B
 - $A \sim B$ indifference between A and B
 - $A \succeq B$ B not preferred to A

Rational Preferences

- Idea: preferences of a rational agent must obey constraints
 - As prerequisite for reasonable preference relations
- Rational preferences → behaviour describable as maximisation of expected utility
- Violating constraints leads to self-evident irrationality
 - Example
 - An agent with intransitive preferences can be induced to give away all its money
 - If $B \succ C$, then an agent who has C would pay (say) 1 cent to get B
 - If $A \succ B$, then an agent who has B would pay (say) 1 cent to get A
 - If $C \succ A$, then an agent who has A would pay (say) 1 cent to get C



Axioms of Utility Theory

1. Orderability

- $(A \succ B) \vee (A \prec B) \vee (A \sim B)$
 - $\{<, >, \sim\}$ jointly exhaustive, pairwise disjoint

2. Transitivity

- $(A \succ B) \wedge (B \succ C) \Rightarrow (A \succ C)$

3. Continuity

- $A \succ B \succ C \Rightarrow \exists p [p, A; 1 - p, C] \sim B$

4. Substitutability

- $A \sim B \Rightarrow [p, A; 1 - p, C] \sim [p, B; 1 - p, C]$
 - Also holds if replacing \sim with \succ

5. Monotonicity

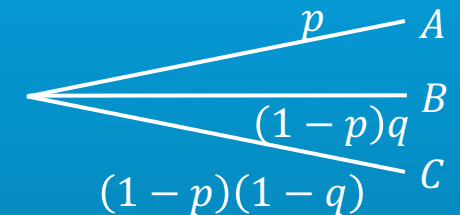
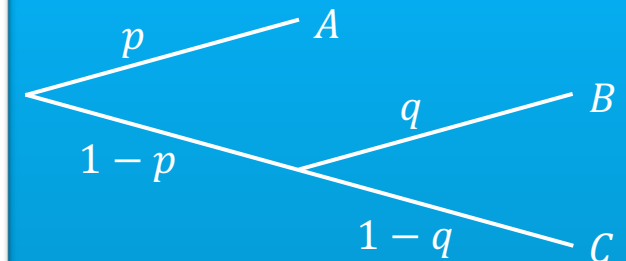
- $A \succ B \Rightarrow (p \geq q \Leftrightarrow [p, A; 1 - p, B] \succeq [q, A; 1 - q, B])$

6. Decomposability

- $[p, A; 1 - p, [q, B; 1 - q, C]] \sim [p, A; (1 - p)q, B; (1 - p)(1 - q), C]$

Decomposability:
There is no fun in gambling.

Equivalent lotteries:



And Then There Was Utility

- Theorem (Ramsey, 1931; von Neumann and Morgenstern, 1944):
 - Given preferences satisfying the constraints, there exists a real-valued function U such that

$$U(A) \geq U(B) \Leftrightarrow A \succeq B$$

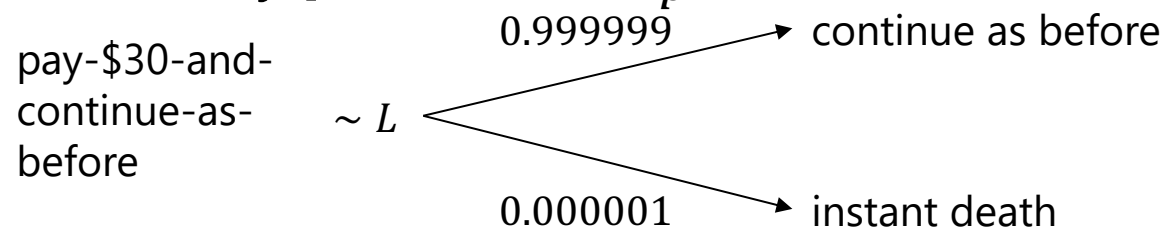
- Existence of a utility function
- Expected utility of a lottery:

$$U([p_1, S_1; \dots; p_M, S_M]) = \sum_{i=1}^M p_i U(S_i)$$

- MEU principle
 - Choose the action that maximises expected utility

Utilities

- Utilities map states to real numbers.
Which numbers?
- Standard approach to assessment of human utilities:
 - Compare a given state A to a standard lottery L_p that has
 - “best possible outcome” \top with probability p
 - “worst possible catastrophe” \perp with probability $(1 - p)$
 - Adjust lottery probability p until $A \sim L_p$



Utility Scales

- **Normalised** utilities: $u_{\top} = 1.0, u_{\perp} = 0.0$
 - Utility of lottery $L \sim$ (pay-\$30-and-continue-as-before): $U(L) = u_{\top} \cdot 0.9999999 + u_{\perp} \cdot 0.0000001 = 0.9999999$
- **Micromorts**: one-millionth chance of death
 - Useful for Russian roulette, paying to reduce product risks, etc.
 - Example for low risk
 - Drive a car for 370km \approx 1 micromort \rightarrow lifespan of a car: 150,000km \approx 400 micromorts
 - Studies showed that many people appear to be willing to pay US\$10,000 for a safer car that halves the risk of death \rightarrow US\$50/micromort
- **QALYs**: quality-adjusted life years
 - Useful for medical decisions involving substantial risk
- In planning: task becomes minimisation of **cost** instead of maximisation of utility

Utility Scales

- Behaviour is **invariant** w.r.t. positive linear transformation

$$U'(r) = k_1 U(r) + k_2$$

- No unique utility function; $U'(r)$ and $U(r)$ yield same behaviour
- With deterministic prizes only (no lottery choices), only **ordinal** utility can be determined, i.e., total order on prizes
 - Ordinal utility function also called **value function**
 - Provides a ranking of alternatives (states), but not a meaningful metric scale (numbers do not matter)
- Note:
An agent can be entirely rational (consistent with MEU) without ever representing or manipulating utilities and probabilities
 - E.g., a lookup table for perfect tic-tac-toe

Multi-attribute Utility Theory

- A given state may have multiple utilities
 - ...because of multiple evaluation criteria
 - ...because of multiple agents (interested parties) with different utility functions
- There are:
 - Cases in which decisions can be made *without* combining the attribute values into a single utility value
 - **Strict dominance**
 - Not this lecture
 - Cases in which the utilities of attribute combinations can be specified very concisely
 - This lecture!

Preference Structure

- To specify the complete utility function $U(r_1, \dots, r_M)$, we need d^M values in the worst case
 - M attributes
 - each attribute with d distinct possible values
 - Worst case meaning: Agent's preferences have no regularity at all
- Supposition in multi-attribute utility theory
 - Preferences of typical agents have much more structure
- Approach
 - Identify regularities in the preference behaviour
 - Use so-called **representation theorems** to show that an agent with a certain kind of preference structure has a utility function

$$U(r_1, \dots, r_M) = \mathcal{E}[f_1(r_1), \dots, f_M(r_M)]$$

- where \mathcal{E} is hopefully a simple function such as *addition*

Preference Independence

- R_1 and R_2 **preferentially independent** (PI) of R_3 iff
 - Preference between $\langle r_1, r_2, r_3 \rangle$ and $\langle r'_1, r'_2, r_3 \rangle$ does not depend on r_3
 - E.g., $\langle \text{Noise}, \text{Cost}, \text{Safety} \rangle$
 - $\langle 20,000 \text{ suffer}, \$4.6 \text{ billion}, 0.06 \text{ deaths/month} \rangle$
 - $\langle 70,000 \text{ suffer}, \$4.2 \text{ billion}, 0.06 \text{ deaths/month} \rangle$
- Theorem (Leontief, 1947)
 - If every pair of attributes is PI of its complement, then every subset of attributes is PI of its complement
 - Called **mutual PI (MPI)**

Preference Independence

- Theorem (Debreu, 1960):
 - MPI $\Rightarrow \exists$ *additive value function*

$$V(r_1, \dots, r_M) = \sum_{i=1}^M V_i(r_i)$$

- Hence assess M single-attribute functions
 - Decomposition of V into a set of summands (additive semantics) similar to
 - Decomposition of P_R into a set of factors (multiplicative semantics)
- Often a good approximation
- Example:

$$V(\text{Noise}, \text{Cost}, \text{Deaths}) = -\text{Noise} \cdot 10^4 - \text{Cost} - \text{Deaths} \cdot 10^{12}$$

Interim Summary

- Preferences
 - Preferences of a rational agent must obey constraints
- Utilities
 - Rational preferences = describable as maximisation of expected utility
 - Utility axioms
 - MEU principle
- Multi-attribute utility theory
 - Preference structure
 - (Mutual) preferential independence

Outline: 7. Lifted Decision Making

A. *Utility theory*

- Preferences, maximum expected utility (MEU) principle
- Utility function, multi-attribute utility theory

B. ***Static decision making***

- Modelling, semantics, inference tasks
- Inference algorithm: LVE for MEU as an example

C. *Sequential decision making*

- Modelling, semantics, temporal MEU problem
- Inference algorithm: LDJT for MEU as an example
- Acting

Decision Networks/Models

- Extend a PGM to handle actions and utilities
 - Decision variables
 - Utility variables
- Also called influence diagrams
- Given a decision model, use an inference method of one's choosing to find actions that lead to the highest expected utility
- Also allows to perform so-called *Value of Information* calculations
 - Is it worth it to spend resources on getting more information (in the form of evidence)?

Decision PRVs

- Decision PRV D

- Range $\text{ran}(D) = \{a_i\}_{i=1}^K$ set of possible actions
 - Actions a_i mutually exclusive (consistent with range definition)
 - Always have to get a value assigned
 - Cannot not make a decision!

- Depicted by a rectangle in a graphical representation
- E.g., travel restrictions for people X : $\text{Restrict}(X)$

- Range values: ban, free

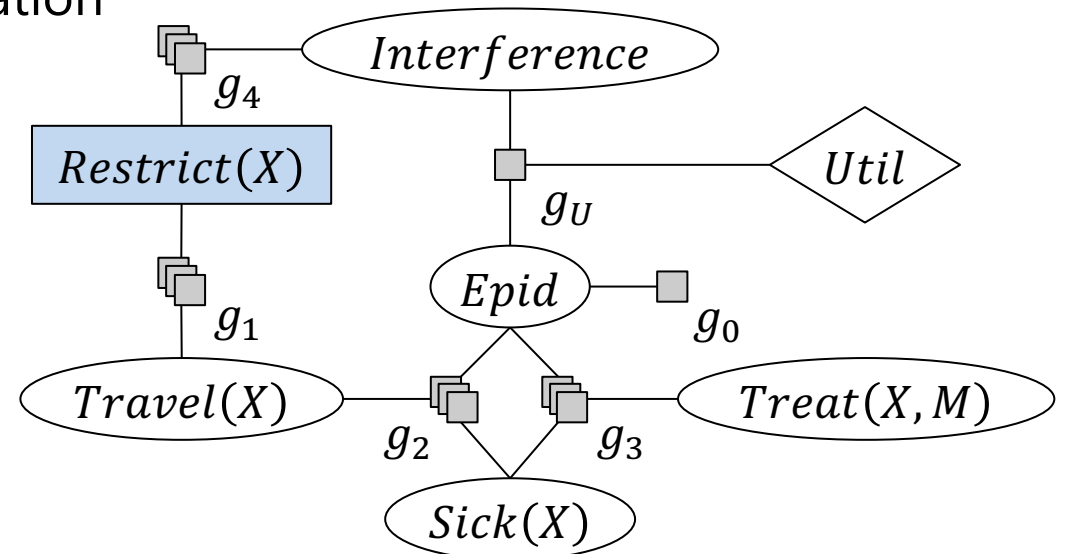
- Set of decision PRVs \mathbf{D} in a model, i.e., $\mathbf{R} = \mathbf{D} \cup \mathbf{V}$

- \mathbf{D} can occur as arguments to any parfactor

- Example:

- $\phi_1(\text{Restrict}(X), \text{Travel}(X))$,
- $\phi_4(\text{Restrict}(X), \text{Interference})$

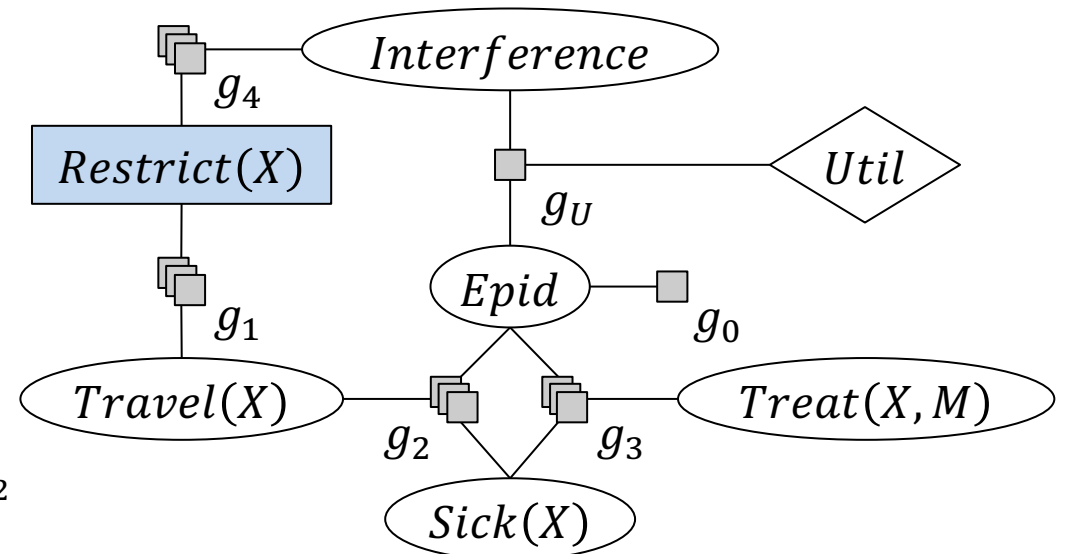
$R(X)$	I	ϕ_4	$R(X)$	$Tl(X)$	ϕ_1
<i>free</i>	<i>false</i>	1	<i>free</i>	<i>false</i>	1
<i>free</i>	<i>true</i>	0	<i>free</i>	<i>true</i>	1
<i>ban</i>	<i>false</i>	0	<i>ban</i>	<i>false</i>	1
<i>ban</i>	<i>true</i>	1	<i>ban</i>	<i>true</i>	0



Utility PRVs & Utility Parfactors

- **Utility PRV U**
 - Range $\text{ran}(U) = \mathbb{R}$
 - Output variable, i.e., gets assigned a value by utility function
 - Depicted by a diamond in a graphical representation
- **Utility parfactor $\phi_U(\mathcal{A})|_C$**
 - Arguments \mathcal{A} a sequence of (decision) PRVs
 - U a utility PRV
 - Function $\phi_U: \times_{i=1}^l \text{ran}(R_i) \mapsto \text{ran}(U)$
 - Tabular representation, additive function, ...
 - Tabular example $\phi_{Util}(Interference, Epid)$
 - Example from slide 18 additive:
 $V(N, C, D) = -Noise \cdot 10^4 - Cost - Deaths \cdot 10^{12}$

I	E	$Util$
<i>false</i>	<i>false</i>	10
<i>false</i>	<i>true</i>	-10
<i>true</i>	<i>false</i>	-20
<i>true</i>	<i>true</i>	-02



Parfactor-based Decision Model

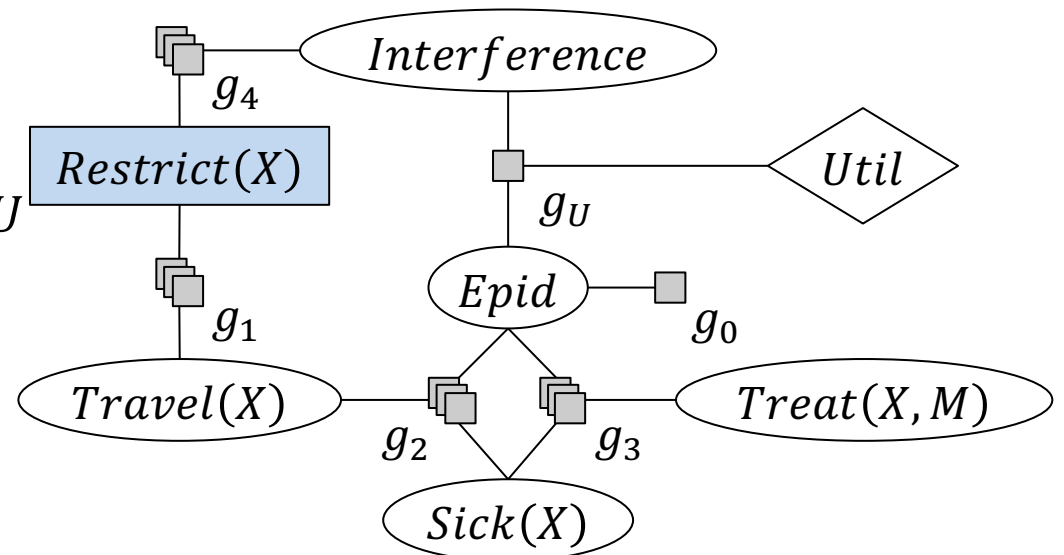
- Decision model = Parfactor model that allows decision PRVs in the arguments of its parfactors as well as utility parfactors
 - For ease of exposition, we start with models with a utility *factor* mapping to a utility *variable*
 - Formally,

$$G = \{g_i\}_{i=1}^n \cup \{g_U\}$$

- g_i parfactors with (decision) PRVs as arguments
- g_U utility factor mapping to a utility variable U
 - $rv(g_U) = \emptyset$ for now

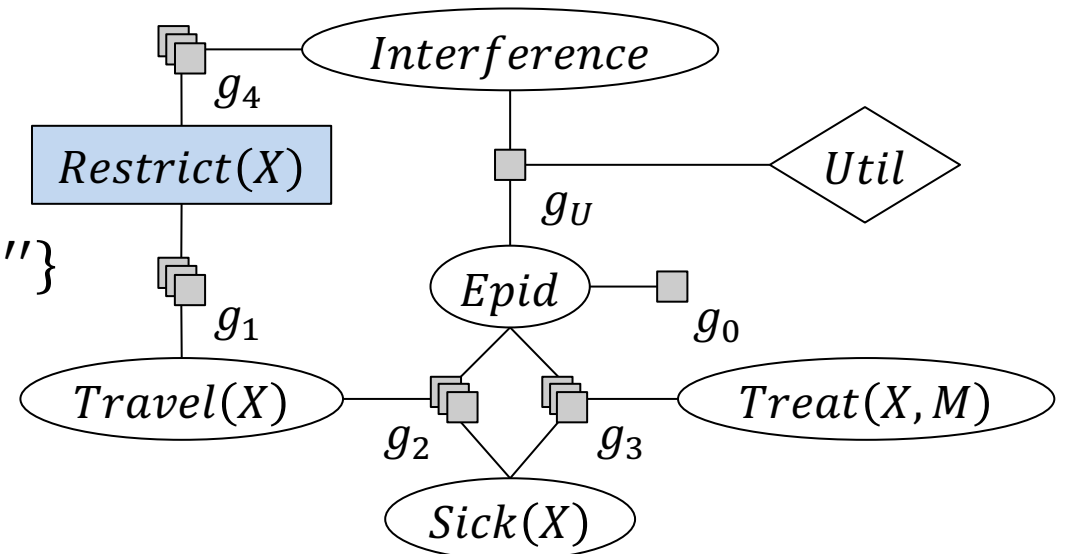
– E.g.,

- $G = \{g_0, g_1, g_2, g_3, g_4, g_U\}$
 - T constraints



Decision Model: Action Assignments

- Let $\mathbf{D} = \{D_1, \dots, D_k\}_{|C}$ be the set of decision PRVs in G with a constraint C for the logical variables in \mathbf{D}
- Then, \mathbf{d} is a compound event for \mathbf{D} that assigns each decision PRV D_i a range value d_i
 - Refer to \mathbf{d} as an **action assignment**
- E.g., without evidence in G ($e = \emptyset$, \top constraints)
 - Action $Restrict(X)$ with range $\{ban, free\}$
 - $\mathbf{d}_1 = \{ban\}$
 - $\mathbf{d}_2 = \{free\}$
 - Given another action D with range $\{d', d'', d'''\}$
 - $\mathbf{d}_1 = \{ban, a'\}$ $\mathbf{d}_4 = \{free, d'\}$
 - $\mathbf{d}_2 = \{ban, a''\}$ $\mathbf{d}_5 = \{free, d''\}$
 - $\mathbf{d}_3 = \{ban, a'''\}$ $\mathbf{d}_6 = \{free, d'''\}$

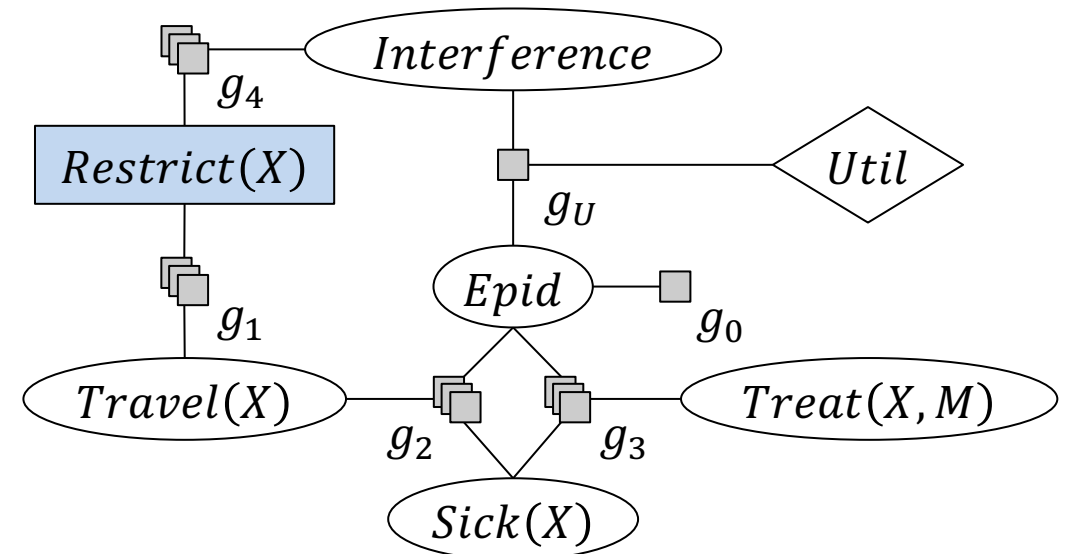


Decision Model: Setting Decisions

- Given a decision model G and an action assignment \mathbf{d}
- Let $G[\mathbf{d}]$ refer to G with \mathbf{d} set, i.e.,

$$G[\mathbf{d}] = \text{absorb}(G, \mathbf{d})$$
 - In each g with decision PRV A_i ,
 - Drop the lines where $A_i \neq a_i$ and the column of A_i
- E.g., set $\mathbf{d}_1 = \{\text{ban}\}$ in $G = \{g_0, g_1, g_2, g_3, g_4, g_U\}$
 - $e = \emptyset$
 - Absorb \mathbf{d}_1 in g_1
 - $G[\mathbf{d}_1] = \{g_0, g'_1, g_2, g_3, g'_4, g_U\}$
 - $g'_1 = \phi'_1(\text{Travel}(X))$
 - $g'_4 = \phi'_4(\text{Interference})$

$R(X)$	I	ϕ_4	$R(X)$	$Tl(X)$	ϕ_1
free	false	1	free	false	1
free	true	0	free	true	1
ban	false	0	ban	false	1
ban	true	1	ban	true	0



Decision Model: Semantics

- **Semantics** of decision model $G = \{g_i\}_{i=1}^n \cup \{g_U\}$
 - Given an action assignment \mathbf{d} for the *grounded* set of decision PRVs $\mathbf{D} = \{D_1, \dots, D_k\}_{|C}$ occurring in G
 - Then, the semantics is given by grounding and building a full joint distribution for the non-utility parfactors

$$P_G[\mathbf{d}] = \frac{1}{Z} \prod_{f \in \text{gr}(G[\mathbf{d}] \setminus \{g_U\})} f$$
$$Z = \sum_{r_1 \in \text{ran}(R_1)} \dots \sum_{r_N \in \text{ran}(R_N)} \prod_{f \in \text{gr}(G[\mathbf{d}] \setminus \{g_U\})} f$$

Semantics *multiplicative* with an inner product and outer sum: Multiply parfactors, then sum out PRVs.
→ Sum-product algorithms

- Utility parfactors irrelevant for probabilistic behaviour

Decision Model: Example

- Decision model

$$G = \{g_0, g_1, g_2, g_3, g_4, g_U\}$$

- T constraints

- G with $\mathbf{d}_1 = \{ban\}$ set

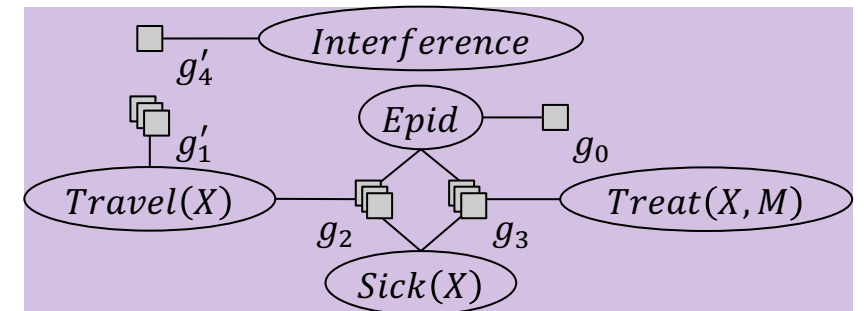
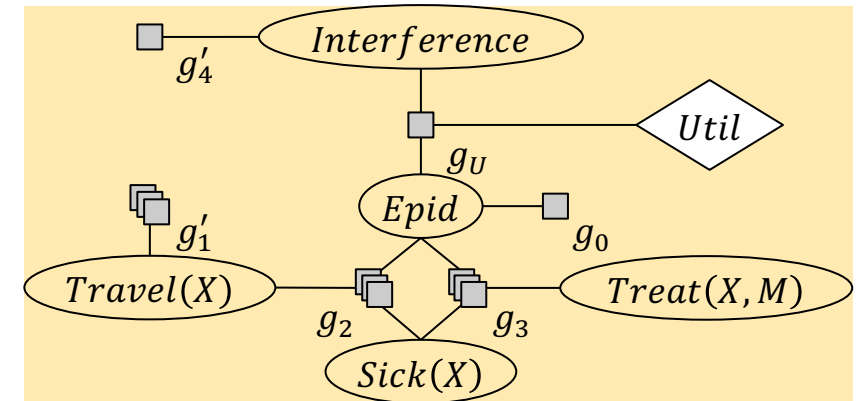
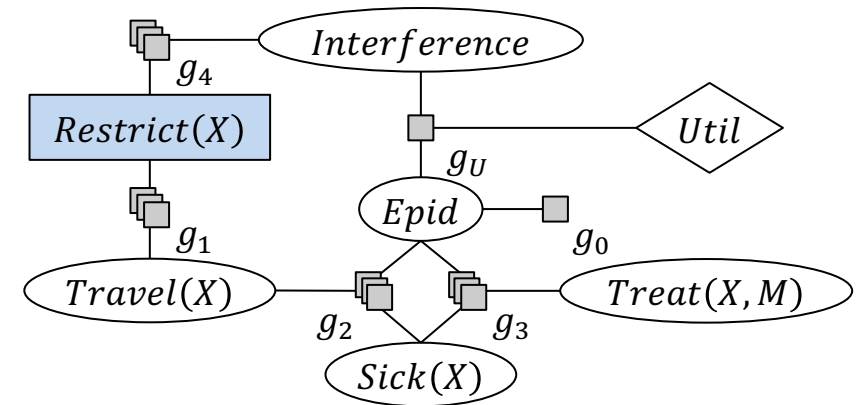
$$G[\mathbf{d}_1] = \{g_0, g'_1, g_2, g_3, g'_4, g_U\}$$

- $g'_1 = \phi'_1(Travel(X))$

- $g'_4 = \phi'_4(Interference)$

- Model relevant for probabilistic query answering:

$$G[\mathbf{d}_1] \setminus \{g_U\} = \{g_0, g'_1, g_2, g_3, g'_4\}$$



Expected Utility Queries

- Given a decision model $G = \{g_i\}_{i=1}^n \cup \{g_U\}$
 - One can ask queries for (conditional) marginal distributions or events as before given an action assignment \mathbf{d} based on the semantics, $P_G[\mathbf{d}]$
 - New query type: query for an **expected utility (EU)**
 - What is the expected utility of making decisions \mathbf{d} in G ?

$$eu(\mathbf{e}, \mathbf{d}) = \sum_{r \in \text{ran}(\text{gr}(\text{rv}(g_U) \setminus \mathbf{E} \setminus \mathbf{D}))} P(\mathbf{r} | \mathbf{e}, \mathbf{d}) \cdot \phi_U(\mathbf{r}, \mathbf{e}, \mathbf{d})$$

- $P(\mathbf{r} | \mathbf{e}, \mathbf{d})$ means that the PRVs not occurring in this expression need to be eliminated accordingly
 - I.e., $\mathbf{V} = \text{rv}(G) \setminus \mathbf{D} \setminus \mathbf{E} \setminus \text{rv}(g_U)$

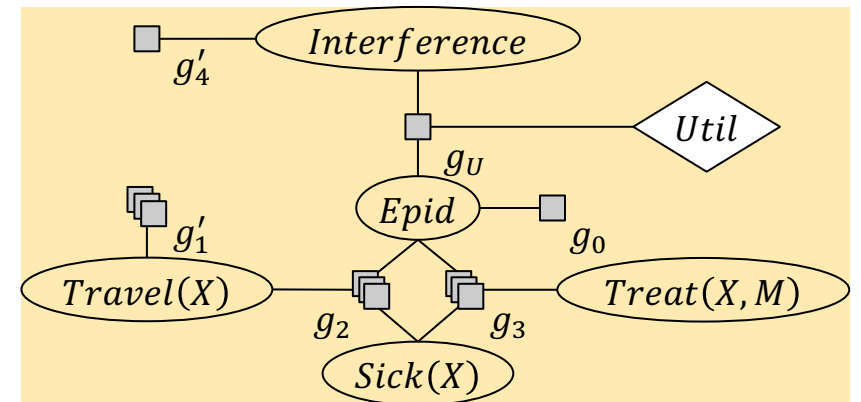
EU Query: Example

- Expected utility of $\mathbf{d}_1 = \{\text{ban}\}$ in $G = \{g_0, g_1, g_2, g_3, g_4, g_U\}$

$$eu(\mathbf{d}_1) = \sum_{i \in \text{ran}(\text{Interference})} \sum_{e \in \text{ran}(\text{Epid})} P(e, i | \mathbf{d}_1) \cdot \phi_U(e, i)$$

- With $e = \emptyset$
- Compute $P(\text{Epid}, \text{Interference} | \mathbf{d}_1)$ in G
 - By computing $P(\text{Epid}, \text{Interference})$ in $G[\mathbf{d}_1]$
 - E.g., using LVE with model

$$G[\mathbf{d}_1] \setminus \{g_U\} = \{g_0, g'_1, g_2, g_3, g'_4\}$$
 - $G[\mathbf{d}_1]$ depicted on the right



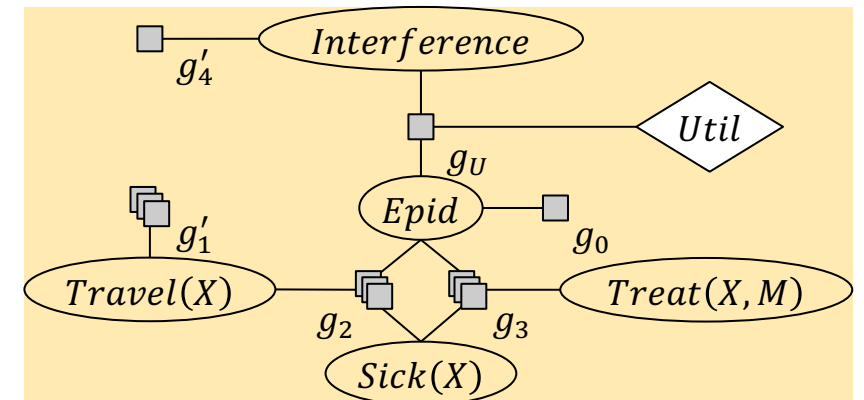
EU Query: Example

- Compute $P(Epid, Interference)$ in $G[\mathbf{d}_1] = \{g_0, g'_1, g_2, g_3, g'_4, g_U\}$
 - Using LVE, eliminate all other PRVs in $G[\mathbf{d}_1]$:
 1. Eliminate $Treat(X, M)$
 2. Eliminate $Travel(X)$
 3. Eliminate $Sick(X)$
 4. Multiply all factors and normalise result
 - Result: $P(Epid, Interference)$ in $G[\mathbf{d}_1]$: $\phi(Epid, Interference)$
 - Corresponds to $P(Epid, Interference | \mathbf{d}_1)$ in G

Parfactors g'_1 and g'_4 would look differently, had we set $\mathbf{d}_2 = \{free\}$.

I	ϕ'_4
false	0
true	1

$Tl(X)$	ϕ'_1
false	1
true	0

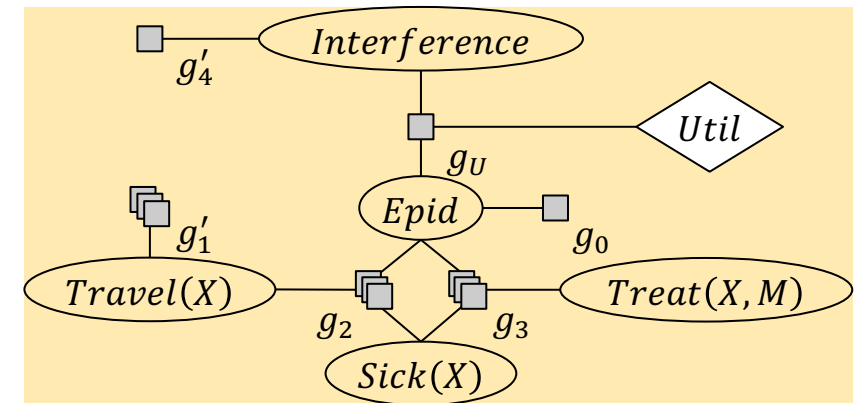


EU Query: Example

- Calculations with $|\text{dom}(M)| = 2, |\text{dom}(X)| = 3$:
 - Sum out $Treat(X, M)$, exponentiate result for M

E	$S(X)$	$Tt(X, M)$	ϕ_3
false	false	false	9
false	false	true	1
false	true	false	5
false	true	true	6
true	false	false	3
true	false	true	4
true	true	false	4
true	true	true	5

E	$S(X)$	ϕ'_3
false	false	$(9 + 1)^2 = 100$
false	true	$(5 + 6)^2 = 121$
true	false	$(3 + 4)^2 = 49$
true	true	$(4 + 5)^2 = 81$



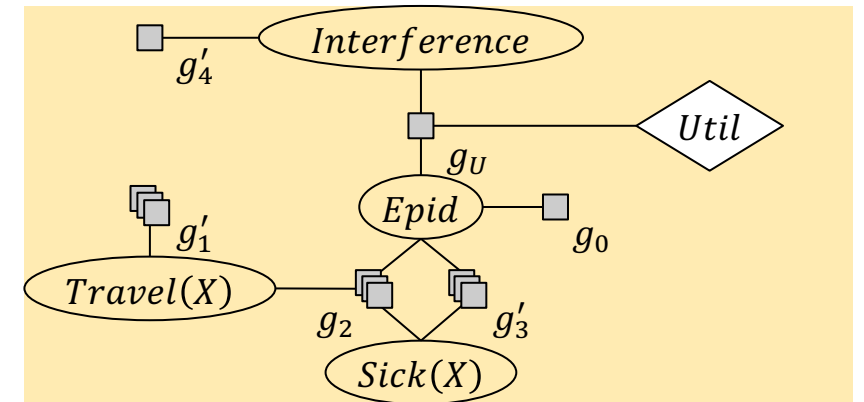
EU Query: Example

- Calculations with $|\text{dom}(M)| = 2, |\text{dom}(X)| = 3$:
 - Multiply g'_1, g_2 , sum out $\text{Travel}(X)$

E	$S(X)$	$Tl(X)$	$\phi_2 \cdot \phi'_1$
false	false	false	$10 \cdot 1 = 10$
false	false	true	$0 \cdot 0 = 0$
false	true	false	$4 \cdot 1 = 4$
false	true	true	$0 \cdot 0 = 0$
true	false	false	$8 \cdot 1 = 8$
true	false	true	$0 \cdot 0 = 0$
true	true	false	$5 \cdot 1 = 5$
true	true	true	$0 \cdot 0 = 0$

E	$S(X)$	ϕ'_{12}
false	false	$10 + 0 = 10$
false	true	$0 + 0 = 0$
true	false	$8 + 0 = 8$
true	true	$0 + 0 = 0$

$\text{Travel}(X)$	ϕ'_1
false	1
true	0



EU Query: Example

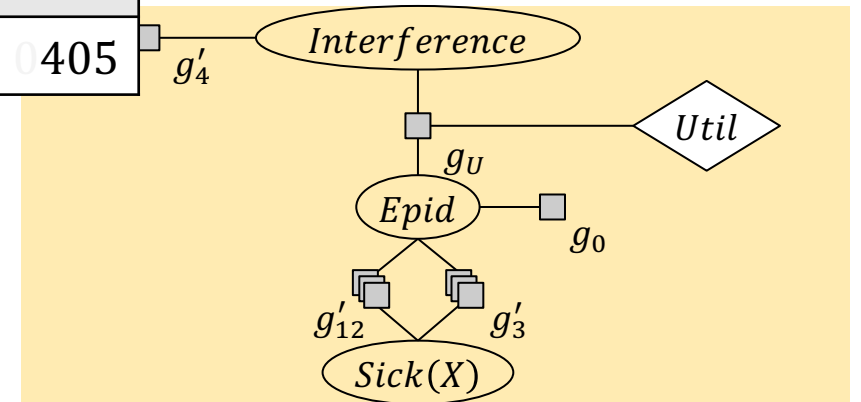
- Calculations with $|\text{dom}(M)| = 2, |\text{dom}(X)| = 3$:
 - Multiply g'_{12}, g'_3 , sum out $Sick(X)$, exponentiate for X

E	$S(X)$	ϕ'_{12}
false	false	10
false	true	4
true	false	8
true	true	5

E	$S(X)$	ϕ'_3
false	false	100
false	true	121
true	false	49
true	true	81

E	$S(X)$	$\phi'_{12} \cdot \phi'_3$
false	false	$10 \cdot 100 = 1000$
false	true	$4 \cdot 121 = 484$
true	false	$8 \cdot 49 = 392$
true	true	$5 \cdot 81 = 405$

E	ϕ'_{123}
false	$(1000 + 484)^3 = 3,268,147,904$
true	$(392 + 405)^3 = 506,261,573$



EU Query: Example

- Calculations with $|\text{dom}(M)| = 2, |\text{dom}(X)| = 3$:
- 3. Multiply g'_{123}, g_0, g'_4 , normalise

E	ϕ'_{123}
<i>false</i>	$(1000 + 484)^3 = 3,268,147,904$
<i>true</i>	$(392 + 405)^3 = 0,506,261,573$

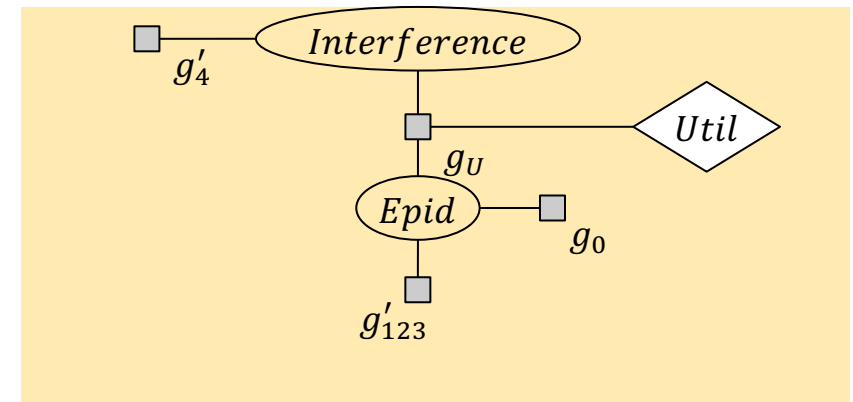
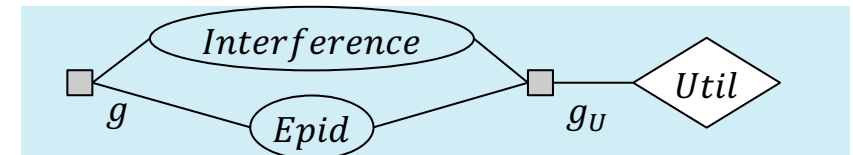
E	ϕ_0
<i>false</i>	10
<i>true</i>	01

I	ϕ'_4
<i>false</i>	0
<i>true</i>	1

I	E	$\phi'_{123} \cdot \phi_0 \cdot \phi'_4$
<i>false</i>	<i>false</i>	$3,268,147,904 \cdot 10 \cdot 0 = 0$
<i>false</i>	<i>true</i>	$0,506,261,573 \cdot 01 \cdot 0 = 0$
<i>true</i>	<i>false</i>	$3,268,147,904 \cdot 10 \cdot 1 = 30,268,147,904$
<i>true</i>	<i>true</i>	$0,506,261,573 \cdot 01 \cdot 1 = 00,506,261,573$

ϕ
0.000
0.000
0.984
0.016

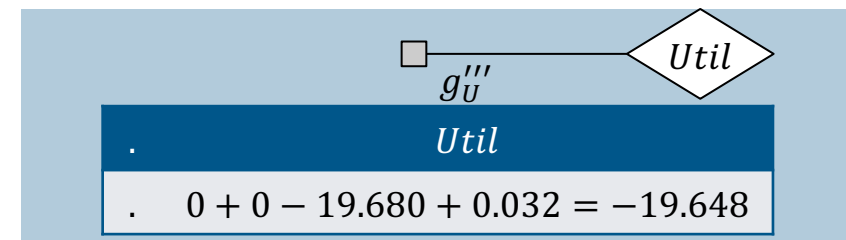
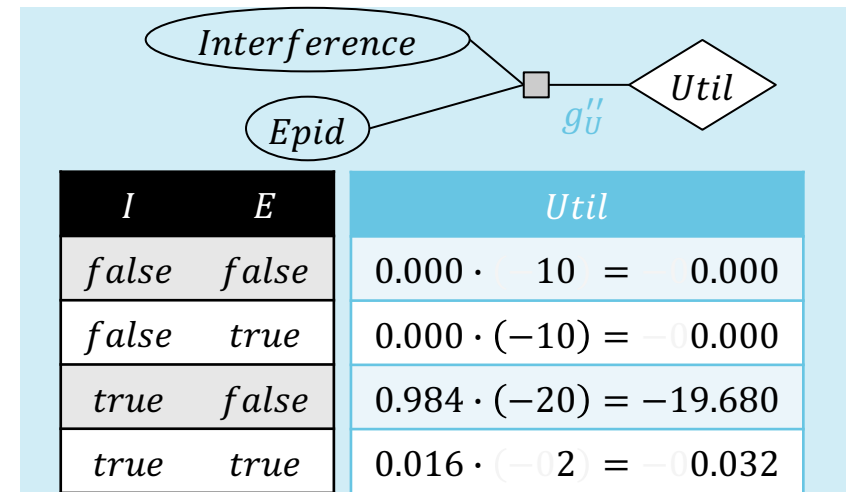
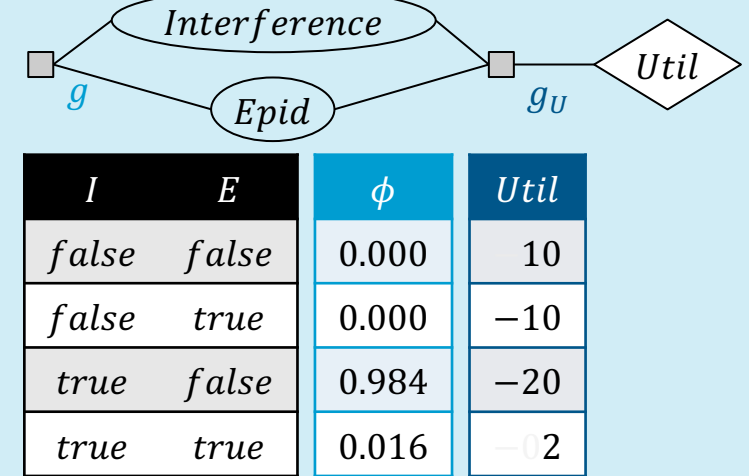
Result after normalising:
 $g = \phi(\text{Interference}, \text{Epid})$



EU Query: Example

- Result $\phi(Epid)$ for $P(Epid = e | \mathbf{d}_1)$ in G
- Expected utility of $\mathbf{d}_1 = \{ban\}$ in $G = \{g_0, g_1, g_2, g_3, g_4, g_U\}$

$$\begin{aligned}
 eu(\mathbf{d}_1) &= \sum_{i \in \text{ran}(Interference)} \sum_{e \in \text{ran}(Epid)} P(e, i | \mathbf{d}_1) \cdot \phi_U(e, i) \\
 &= \sum_{i \in \text{ran}(Interference)} \sum_{e \in \text{ran}(Epid)} \phi(e, i) \cdot \phi'_U(e, i) \\
 &= \sum_{i \in \text{ran}(Interference)} \sum_{e \in \text{ran}(Epid)} \phi''_U(Epid = e) \\
 &= \phi'''_U(.)
 \end{aligned}$$



Answering EU-Queries (with LVE)

- Given a decision model $G = \{g_i\}_{i=1}^n \cup \{g_U\}$, evidence e , and an action assignment \mathbf{d} (*)
 - Absorb e and \mathbf{d} in G
 - Calculate the posterior, $P(\mathbf{R}|\mathbf{e}, \mathbf{d})$, of the *Markov blanket of the utility node*
 - I.e., $\mathbf{R} = \text{rv}(g_U) \setminus \text{rv}(\mathbf{d}) \setminus \text{rv}(\mathbf{e})$ (remaining PRVs in g_U after previous step)
 - Using LVE: With \mathbf{R} as the query terms, eliminate all non-query terms in G , i.e., call $\text{LVE}(G \setminus \{g_U\}, \mathbf{R}, \emptyset)$
 - Evidence already absorbed, decisions made $\rightarrow e = \emptyset$ in the call
 - Calculate the expected utility by summing over the range values of \mathbf{R} :

(*) We need to talk about evidence and action assignments later.

$$eu(\mathbf{e}, \mathbf{d}) = \sum_{r \in \text{ran}(\mathbf{R})} P(r|\mathbf{e}, \mathbf{d}) \cdot \phi_U(r)$$

- Using LVE: Eliminate remaining PRVs in G
 - Result: parfactor mapping empty argument to a single value (U)

MEU Problem

- Given a decision model G and evidence e , **maximum Expected Utility (MEU) problem**:

- Find the action assignment that yields the highest expected utility in G
- Formally,

$$\text{meu}(G|e) = (d^*, eu(E, d^*))$$

$$d^* = \arg \max_{d \in \text{ran}(\mathbf{D})} eu(e, d)$$

Additive semantics with inner sum and outer max: Sum up utilities, then pick maximum
→ Max-sum algorithms

- For an exact solution, $\text{meu}(G|e)$ requires an algorithm to go through **all** $d \in \text{ran}(\mathbf{D})$
 - Size of $\text{ran}(\mathbf{D})$ **exponential** in $|\mathbf{D}|$

Alternative specification

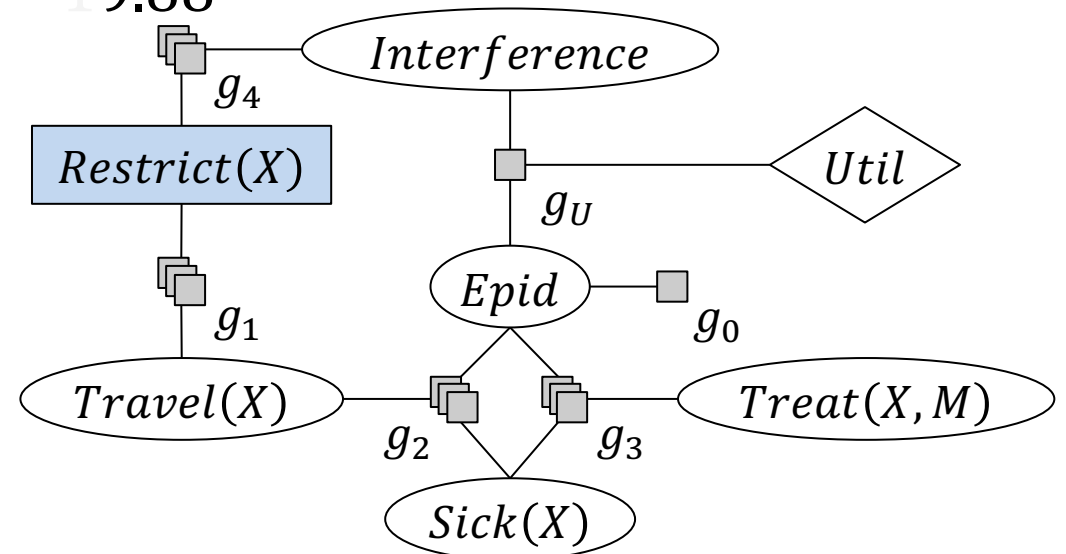
$$\text{meu}(G|e) = \left(\arg \max_{d \in \text{ran}(\mathbf{D})} eu(e, d), \max_{d \in \text{ran}(\mathbf{D})} eu(e, d) \right)$$

MEU Problem: Example

- Problem instance with $G = \{g_0, g_1, g_2, g_3, g_U\}$, $e = \emptyset$:

$$\text{meu}(G) = (\mathbf{d}^*, eu(\mathbf{d}^*)) \quad \mathbf{d}^* = \arg \max_{d \in \{d_1, d_2\}} eu(d)$$

- $\mathbf{d}_1 = \{ban\}$, $\mathbf{d}_2 = \{free\}$
 - Expected utility of $\mathbf{d}_1 = \{ban\}$: $eu(\mathbf{d}_1) = -19.648$
 - Expected utility of $\mathbf{d}_2 = \{free\}$: $eu(\mathbf{d}_2) = -19.88$
- Solution
 - $\mathbf{d}^* = \operatorname{argmax}_{d \in \{d_1, d_2\}} eu(d) = \mathbf{d}_2$
 - $\text{meu}(G) = (\mathbf{d}_2, 9.88)$
 - Decision that leads to maximum EU:
No travel restrictions



Lifted MEU

$$\text{meu}(G|e) = (d^*, eu(e, d^*))$$
$$d^* = \arg \max_{d \in \text{ran}(D)} eu(e, d)$$

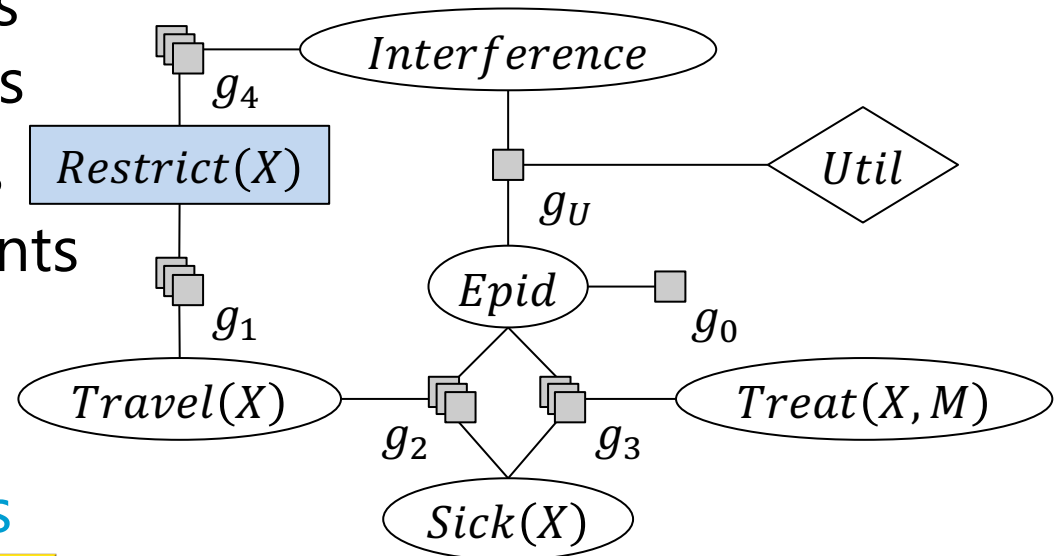
- In terms of semantics, $d \in \text{ran}(D)$ means
 - Grounding D and going through all possible combinations of assignments to $gr(D)$
- But: grounding is bad!
 - Combinatorial explosion: number of action assignments to test **exponential in size of $gr(D)$**
 - **Grounds** any parfactor in G containing a logvar of D
- Also: Grounding to full extent often unnecessary
 - Within **groups of indistinguishable constants**, the same decision will lead to its maximum influence in the MEU solution
 - Only need to test each assignment for complete group
- Thus: Test out all possible combinations of assignments w.r.t. the groups occurring in G
 - No longer exponential in the size of $gr(D)$!

Lifted MEU: Groups

$$\text{meu}(G|e) = (d^*, eu(e, d^*))$$

$$d^* = \arg \max_{d \in \text{ran}(D)} eu(e, d)$$

- In parameterised models without evidence (or evidence for complete domains), $d \in \text{ran}(D)$ means
 - Going through all possible combinations of assignments to D
 - One group per logical variable
- In models with evidence affecting parfactors containing decision PRVs, $d \in \text{ran}(D)$ means
 - Going through all possible combinations of assignments for each group of constants after evidence handling
 - Specifically, after shattering
- Effect: size exponential in number of groups



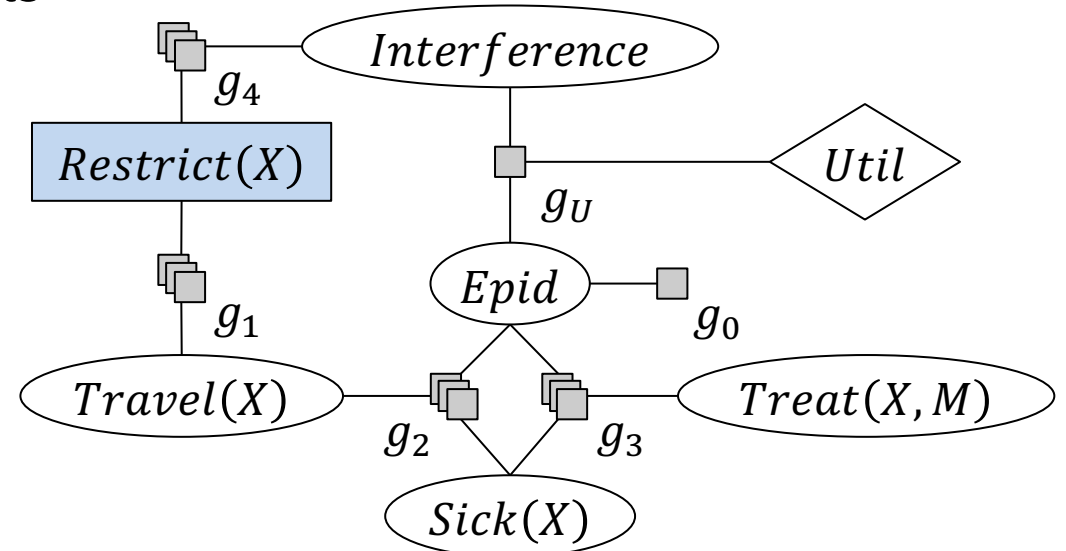
(*) Now is later.

Lifted MEU: Groups – Example

$$\text{meu}(G|e) = (d^*, eu(e, d^*))$$

$$d^* = \arg \max_{d \in \text{ran}(D)} eu(e, d)$$

- Decision model $G = \{g_0, g_1, g_2, g_3, g_4, g_U\}$
 - Decision PRV $Restrict(X)$ with range $\{ban, free\}$
 - Evidence $e = \{Sick(X') = true\}$, $\text{dom}(X') = \{x_1, \dots, x_{10}\}$
 - Overlap in domain of $X, X' \rightarrow$ Shattering duplicates g_1, g_2, g_3, g_4
 - For $\text{dom}(X') = \{x_1, \dots, x_{10}\}$, $\text{dom}(X'') = \{x_{11}, \dots, x_n\}$
 - Alternative: Duplicate + restrict constraints
- Action assignments
 - $R \triangleq Restrict, b \triangleq ban, f \triangleq free$
 - $d_1 = \{R(X'') = b, R(X') = b\}$
 - $d_2 = \{R(X'') = b, R(X') = f\}$
 - $d_3 = \{R(X'') = f, R(X') = b\}$
 - $d_4 = \{R(X'') = f, R(X') = f\}$



Answering EU-Queries for MEU

- Given a decision model $G = \{g_i\}_{i=1}^n \cup \{g_U\}$, evidence e , and an action assignment d for groups in G after shattering
 - Calculate the posterior, $P(\mathbf{R}|e, d)$, of the Markov blanket of the utility node
 - I.e., $\mathbf{R} = rv(g_U) \setminus rv(\mathbf{a}) \setminus rv(\mathbf{E})$ (remaining PRVs in g_u 's after previous step)
 - Using LVE: With \mathbf{R} as the query terms and e, d as evidence, eliminate all non-query terms in G , i.e., call

$$\text{LVE}(G \setminus \{g_U\}, \mathbf{R}, e \cup d)$$

- Calculate the expected utility by summing over the range values of \mathbf{R} :

$$eu(e, d) = \sum_{r \in \text{ran}(\mathbf{R})} P(r|e, d) \cdot \phi_U(r)$$

- Using LVE: Eliminate remaining PRVs in $\{g\} \cup \{g_U\}$, $g = \text{LVE}(G \setminus \{g_U\}, \mathbf{R}, e \cup d)$, i.e., call $\text{LVE}(\{g\} \cup \{g_U\}, \mathbf{R}, e \cup d)$
 - e, d not yet handled in g_U ; alternatively: absorb e, d at beginning in G
 - Result: parfactor mapping empty argument to a single value (U)

LVE for MEU Problems

function MEU-LVE($G = \{g_i\}_{i=1}^n \cup \{g_U\}, e$)

Absorb e in G

$d^* \leftarrow \emptyset$

$eu_{max} \leftarrow -\infty$

for each action assignment d in G **do**

$g \leftarrow \text{LVE}(G \setminus \{g_U\}, rv(g_U), d)$

▸ g normalised

$eu \leftarrow \text{LVE}(\{g_U, g\}, \emptyset, d)$

if $eu > eu_{max}$ **then**

$d^* \leftarrow d$

$eu_{max} \leftarrow eu$

return d^*

LVE-MEU

- Modify to save all assignments that lie within ε -margin

Structure in Multi-attribute Settings

- So far: Set of attributes without structure
 - Single utility functions mapping to one utility
 - Example: $\phi_U(\text{Interference}, \text{Epid})$
- Cases with structure:

1. Set of (distinguishable) attributes with structure

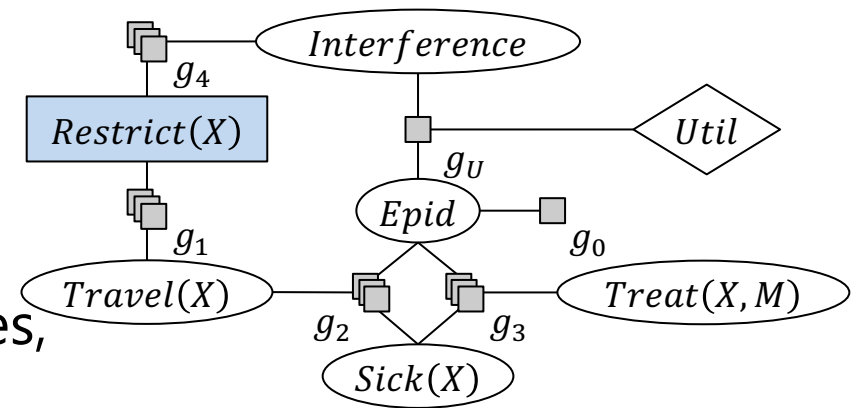
- Set of utility functions, mapping to interim utilities, combined into one overall utility

2. Set of indistinguishable attributes

- Utility parfactor mapping to an interim utility PRV, which is combined into one utility

3. Sets of distinguishable and indistinguishable attributes

- Set of utility parfactors and utility factors, combined into one utility
 - Considering structure requires a combination function \mathcal{E}



1. Set of Attributes with Structure

- Set of attributes that show MPI \rightarrow Utility function “factorises” into sets of functions over attributes, combined with a combination function \mathcal{E} , i.e.,

$$U(r_1, \dots, r_M) = \mathcal{E}[\phi_1(r_1), \dots, \phi_M(r_M)]$$

- I.e., each $\phi_i(r_i)$ maps to its own interim utility, U_i , combined into an overall utility U through \mathcal{E}
- More general: Each f_i has a set of random variables \mathbf{r}_i as input with $\mathbf{r} = \{r_1, \dots, r_M\} = \cup_{i=1}^m \mathbf{r}_i$
- Extended syntax: Decision model

$$G = \{g_i\}_{i=1}^n \cup \{g_u\}_{u=1}^m \cup \{\mathcal{E}\}$$

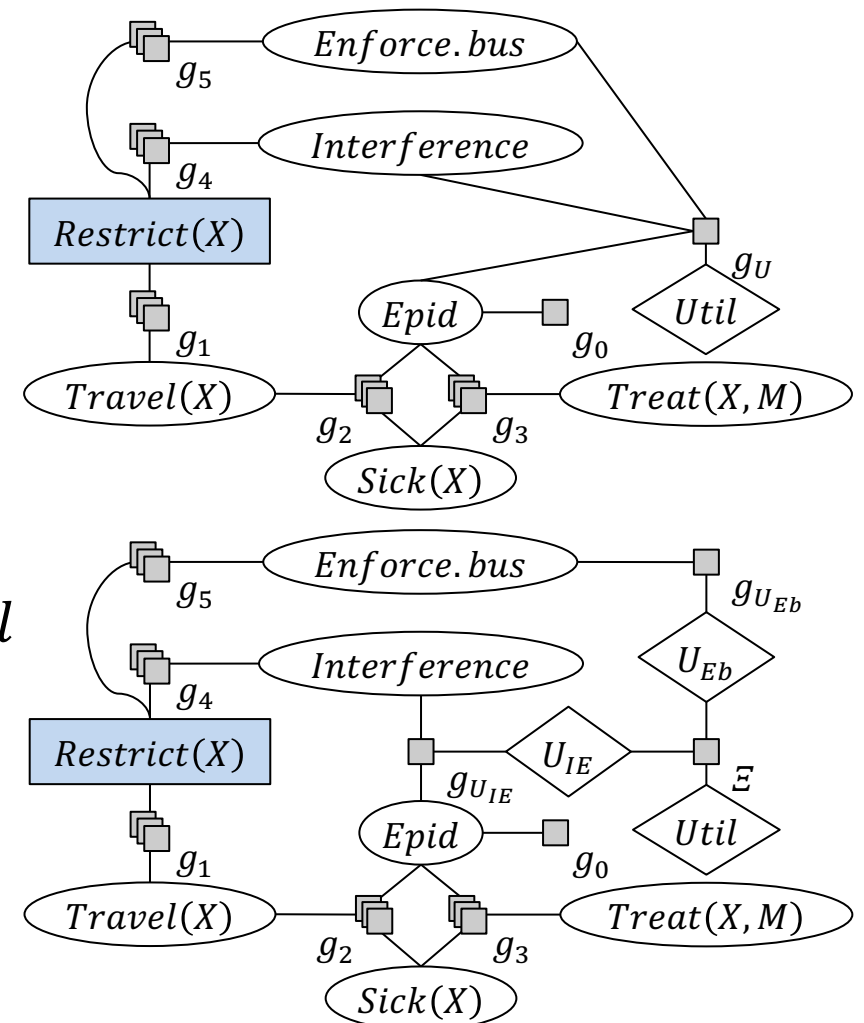
- Refer to submodel of potential parafactors by G_P and to submodel of utility factors by G_U
- $g_i = \phi_i(\mathcal{A}_i)_{|C_i}$ parafactors with (decision) PRVs as arguments
- $g_u = \phi_{U_u}(\mathcal{R}_u)$ utility *factors*, each mapping to a utility variable U_u
- \mathcal{E} a combination function, combining all U_u into one U , i.e.,

$$\phi_U(r_1, \dots, r_M) = \mathcal{E} \left[\phi_{U_1} \left(\pi_{\mathcal{R}_1}(r_1, \dots, r_M) \right), \dots, \phi_{U_m} \left(\pi_{\mathcal{R}_m}(r_1, \dots, r_M) \right) \right]$$

1. Set of Attributes with Structure: Example

- Example:

- $\phi_{U_{IE}}(Interference, Epid)$
utility factor over *Interference, Epid*
- $\phi_{U_{Eb}}(Enforce.bus)$
utility factor over *Enforce.bus*
 - (Effort it takes to enforce travel restriction on busses)
- Ξ a combination function, combining U_1, U_2 into $Util$
 - Could rewrite model using Ξ into a model containing only one utility factor g_U (shown above)
- $\phi_U(Interference, Epid, Enforce.bus)$
 $= \Xi[\phi_{U_{IE}}(Interference, Epid), \phi_{U_{Eb}}(Enforce.bus)]$



1. Set of Attributes with Structure: EU Query & MEU Problem

- Given a decision model $G = G_P \cup G_U \cup \{E\} = \{g_i\}_{i=1}^n \cup \{g_u\}_{u=1}^m \cup \{E\}$
 - Query for an **expected utility (EU)**: change in sum over $rv(G_U)$ instead of $rv(g_U)$

$$eu(\mathbf{e}, \mathbf{d}) = \sum_{\mathbf{v} \in \text{ran}(rv(G_U) \setminus E \setminus \mathbf{D})} P(\mathbf{v} | \mathbf{e}, \mathbf{d}) \cdot \mathbb{E} \left[\phi_{U_1} \left(\pi_{\mathcal{R}_1}(\mathbf{v}, \mathbf{e}, \mathbf{d}) \right), \dots, \phi_{U_m} \left(\pi_{\mathcal{R}_m}(\mathbf{v}, \mathbf{e}, \mathbf{d}) \right) \right]$$

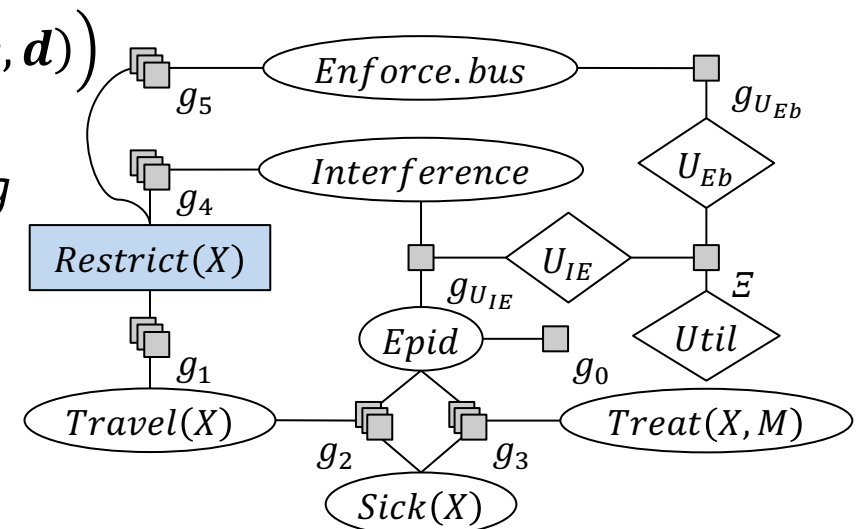
- If E addition, then

$$eu(\mathbf{e}, \mathbf{d}) = \sum_{\mathbf{v} \in \text{ran}(gr(rv(G_U) \setminus E \setminus \mathbf{D}))} P(\mathbf{v} | \mathbf{e}, \mathbf{d}) \cdot \sum_{g_u \in G_U} \phi_{U_u} \left(\pi_{\mathcal{R}_u}(\mathbf{v}, \mathbf{e}, \mathbf{d}) \right)$$

- Works like MULTIPLY, i.e., like a join, but with *summing* of utilities instead of multiplying of potentials

- MEU problem: *no changes*

$$\begin{aligned} \text{meu}(G | \mathbf{e}) &= (\mathbf{d}^*, eu(\mathbf{e}, \mathbf{d}^*)) \\ \mathbf{d}^* &= \operatorname{argmax}_{\mathbf{d} \in \text{ran}(\mathbf{D})} eu(\mathbf{e}, \mathbf{d}) \end{aligned}$$



1. Set of Attributes with Structure: Additive Join

- Operator:

Operator 1 Additive join of utility factors

Operator ADD

Inputs:

- (1) Utility factor $f_{u'} = \phi_{u'}(\mathcal{R}_{u'})$
- (2) Utility factor $f_{u''} = \phi_{u''}(\mathcal{R}_{u''})$

Output: Utility factor $\phi_u(\mathcal{R}_u)$ such that

- (1) $\mathcal{R}_u = \mathcal{R}_{u'} \bowtie \mathcal{R}_{u''}$ and
- (2) for each valuation $\mathbf{r} \in \text{ran}(\mathcal{R}_u)$ with $\mathbf{r}_{u'} = \pi_{\mathcal{R}_{u'}}(\mathbf{r})$ and $\mathbf{r}_{u''} = \pi_{\mathcal{R}_{u''}}(\mathbf{r})$

$$\phi_u(\mathbf{r}) = \phi_{u'}(\mathbf{r}_{u'}) + \phi_{u''}(\mathbf{r}_{u''})$$

Postcondition: $G_U \equiv G_U \setminus \{f_{u'}, f_{u''}\} \cup \text{ADD}(f_{u'}, f_{u''})$

- Example

$$\begin{aligned} & \phi_U(\text{Interference}, \text{Epid}, \text{Enforce. bus}) \\ &= \Xi[\phi_{U_{IE}}(\text{Interference}, \text{Epid}), \phi_{U_{Eb}}(\text{Enforce. bus})] \\ &= \phi_{U_{IE}}(\text{Interference}, \text{Epid}) + \phi_{U_{Eb}}(\text{Enforce. bus}) \\ &= \text{add}(g_{U_{IE}}, g_{U_{Eb}}) \end{aligned}$$

<i>I</i>	<i>E</i>	U_{IE}	<i>Eb</i>	U_{Eb}
false	false	10	false	0
false	true	-10	true	-10
true	false	-20		
true	true	-20		

<i>I</i>	<i>E</i>	<i>Eb</i>	U_{IE}	
false	false	false	10 + 0 = 10	
false	false	true	-10 - 10 = -20	U_{Eb}
false	true	false	-10 + 0 = -10	
false	true	true	-10 - 10 = -20	
true	false	false	-20 + 0 = -20	
true	false	true	-20 - 10 = -30	
true	true	false	-20 + 0 = -20	M
true	true	true	-20 - 10 = -30	

1. Set of Attributes with Structure: Simplification

- Assume (conditional) independence between the distributions $rv(f_u)$ given \mathbf{e}, \mathbf{d} , i.e., $P(\mathbf{v}|\mathbf{e}, \mathbf{d}) = \prod_{u'=1}^m P(\mathbf{r}_{u'}|\mathbf{e}, \mathbf{d})$

$$eu(\mathbf{e}, \mathbf{d}) = \sum_{\mathbf{v} \in \text{ran}(\mathbf{V})} P(\mathbf{v}|\mathbf{e}, \mathbf{d}) \cdot \mathbb{E}[\phi_{U_1}(\mathbf{r}_1), \dots, \phi_{U_m}(\mathbf{r}_m)]$$

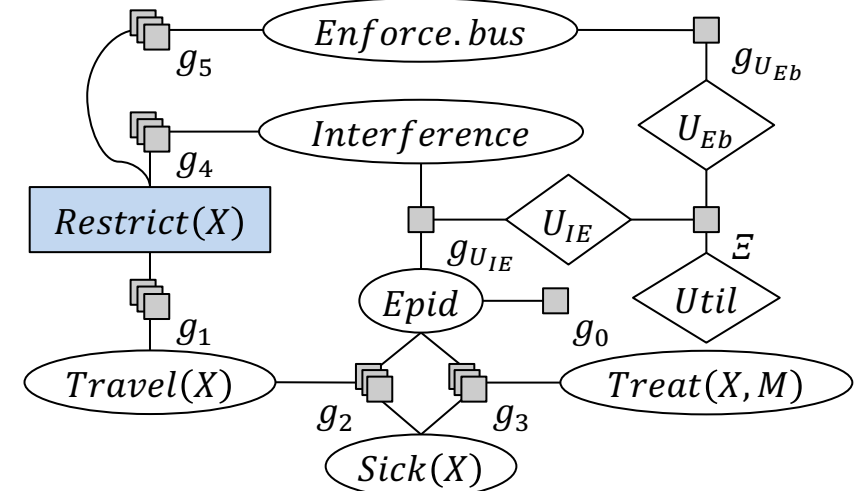
$$= \sum_{\mathbf{v} \in \text{ran}(\mathbf{V})} P(\mathbf{v}|\mathbf{e}, \mathbf{d}) \cdot \sum_{u=1}^m \phi_u(\mathbf{r}_u)$$

$$= \sum_{u=1}^m \sum_{\mathbf{r}_u \in \text{ran}(rv(g_u))} \underbrace{P(\mathbf{r}_u|\mathbf{e}, \mathbf{d})}_{\text{Query on } rv(f_u) \text{ for each utility factor}} \cdot \phi_u(\mathbf{r}_u)$$

Query on $rv(f_u)$ for each utility factor
 → Use multi-query algorithm like LJT

Only yields correct result under stochastic independence

- Idea similar to Boyen-Koller algorithm
- Preferential and stochastic independence do not follow from each other!



Derivation

$$\begin{aligned}
 eu(\mathbf{e}, \mathbf{d}) &= \sum_{v \in \text{ran}(V)} P(v|\mathbf{e}, \mathbf{d}) \cdot \sum_{u=1}^m \phi_u(\mathbf{r}_u) = \sum_{v \in \text{ran}(V)} \sum_{u=1}^m P(v|\mathbf{e}, \mathbf{d}) \cdot \phi_u(\mathbf{r}_u) = \sum_{u=1}^m \sum_{v \in \text{ran}(V)} P(v|\mathbf{e}, \mathbf{d}) \cdot \phi_u(\mathbf{r}_u) \\
 &= \sum_{u=1}^m \sum_{v \in \text{ran}(V)} \prod_{u'=1}^m P(\mathbf{r}_{u'}|\mathbf{e}, \mathbf{d}) \cdot \phi_u(\mathbf{r}_u) \\
 &= \sum_{u=1}^m \sum_{\mathbf{r}_1 \in \text{ran}(R_1)} \dots \sum_{\mathbf{r}_m \in \text{ran}(R_m)} P(\mathbf{r}_1|\mathbf{e}, \mathbf{d}) \cdot \dots \cdot P(\mathbf{r}_m|\mathbf{e}, \mathbf{d}) \cdot \phi_u(\mathbf{r}_u) \\
 &= \sum_{u=1}^m \sum_{\mathbf{r}_1 \in \text{ran}(R_1)} P(\mathbf{r}_1|\mathbf{e}, \mathbf{d}) \cdot \dots \cdot \sum_{\mathbf{r}_m \in \text{ran}(R_m)} P(\mathbf{r}_m|\mathbf{e}, \mathbf{d}) \cdot \phi_u(\mathbf{r}_u) \\
 &= \sum_{u=1}^m \sum_{\mathbf{r}_u \in \text{ran}(R_u)} P(\mathbf{r}_u|\mathbf{e}, \mathbf{d}) \cdot \phi_u(\mathbf{r}_u) \cdot \underbrace{\sum_{u'=1, u' \neq u}^m P(\mathbf{r}_{u'}|\mathbf{e}, \mathbf{d})}_{= 1} \\
 &= \sum_{u=1}^m \sum_{\mathbf{r}_u \in \text{ran}(R_u)} P(\mathbf{r}_u|\mathbf{e}, \mathbf{d}) \cdot \phi_u(\mathbf{r}_u) \quad \begin{array}{l} = 1 \\ \text{(probability distributions} \\ \rightarrow \text{sums to 1)} \end{array}
 \end{aligned}$$

1. Set of Attributes with Structure: Simplification – Example

- Example: $\mathbf{d}_1 = \{ban\}$

$$- P(E, I, Eb | \mathbf{d}) = P(E | \mathbf{d}) \cdot P(I | \mathbf{d}) \cdot P(Eb | \mathbf{d})$$

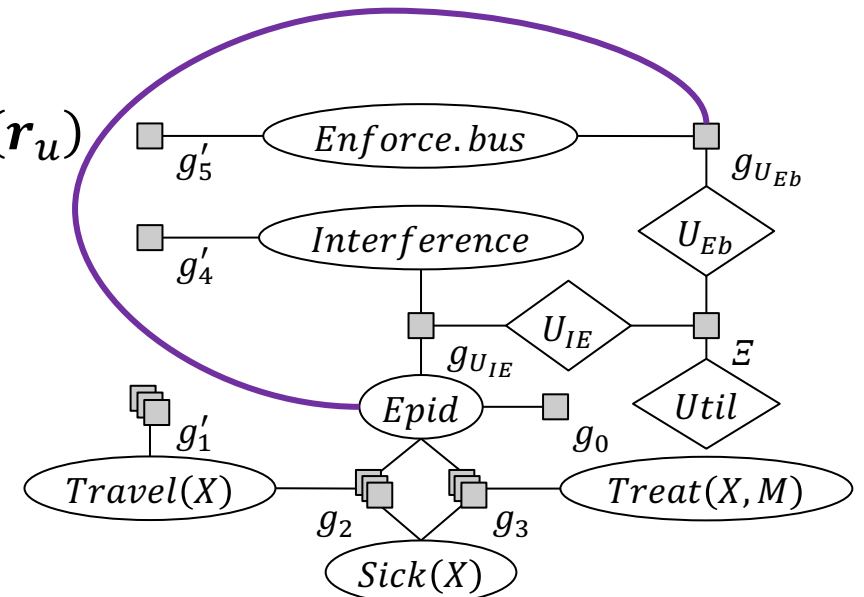
$eu(\mathbf{d}_1)$

$$= \sum_{eb \in \text{ran}(Eb)} \sum_{i \in \text{ran}(I)} \sum_{e \in \text{ran}(E)} P(eb, i, e | \mathbf{d}) \cdot \sum_{u=1}^2 \phi_u(\mathbf{r}_u)$$

$$= \sum_{eb \in \text{ran}(Eb)} \sum_{i \in \text{ran}(I)} \sum_{e \in \text{ran}(E)} P(eb | \mathbf{d}) \cdot P(i | \mathbf{d}) \cdot P(e | \mathbf{d}) \cdot \sum_{u=1}^2 \phi_u(\mathbf{r}_u)$$

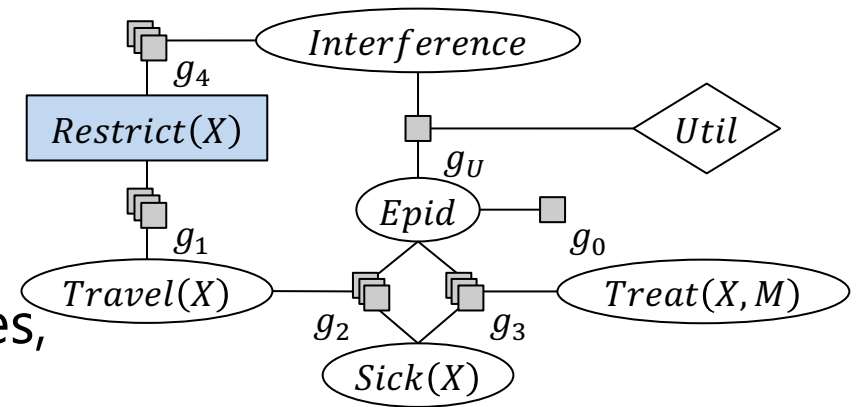
$$= \sum_{eb \in \text{ran}(Eb)} P(eb | \mathbf{d}) \cdot \phi_{Eb}(eb) + \sum_{i \in \text{ran}(I)} P(i | \mathbf{d}) \cdot \sum_{e \in \text{ran}(E)} P(e | \mathbf{d}) \cdot \phi_{IE}(i, e)$$

If adding *Epid* as an input to g_{UEb} ,
 $P(E, I, Eb | \mathbf{d}) \neq P(E, Eb | \mathbf{d}) \cdot P(E, I | \mathbf{d})$



Structure in Multi-attribute Settings

- So far: Set of attributes without structure
 - Single utility functions mapping to one utility
 - Example: $\phi_U(\text{Interference}, \text{Epid})$
- Cases with structure:



1. Set of (distinguishable) attributes with structure

- Set of utility functions, mapping to interim utilities, combined into one overall utility

2. Set of indistinguishable attributes

- Utility parfactor mapping to an interim utility PRV, which is combined into one utility

3. Sets of distinguishable and indistinguishable attributes

- Set of utility parfactors and utility factors, combined into one utility
 - Considering structure requires a combination function \bar{E}

2. Set of Indistinguishable Attributes

- Indistinguishable attributes R_1, \dots, R_M that show MPI \rightarrow Utility function "factorises" into a set of *indistinguishable* functions f_i over indistinguishable attributes

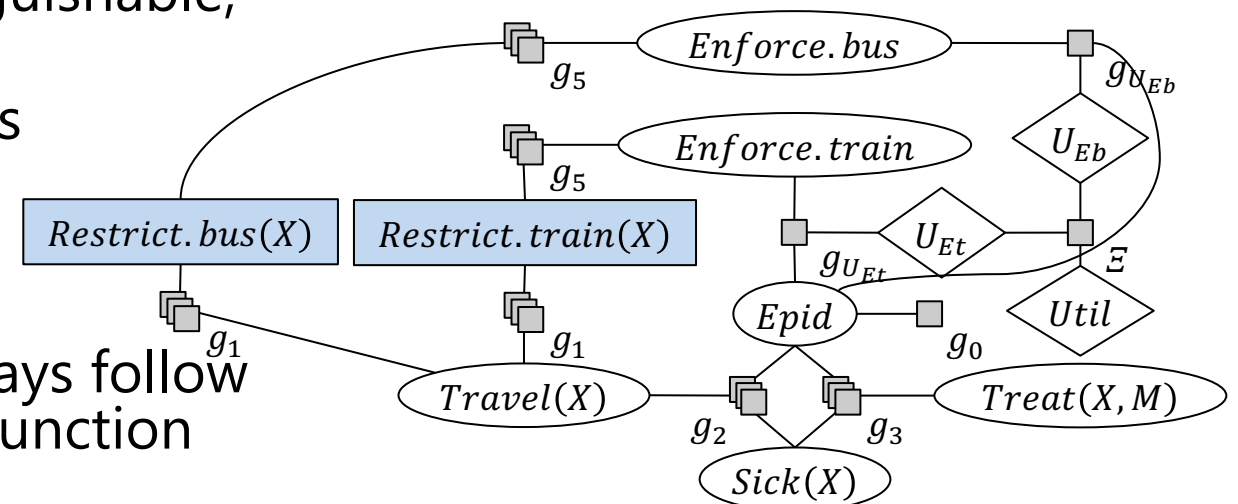
- Utility function:

$$U(r_1, \dots, r_M) = \mathbb{E}[\phi_1(r_1), \dots, \phi_M(r_M)] = \mathbb{E}[\phi_u(r_1), \dots, \phi_u(r_M)]$$

- All ϕ_i are ϕ_u , mapping to an interim utility variable U_i
- If \mathbb{E} addition, then $U(r_1, \dots, r_M) = M \cdot \phi_u(r_u)$

- *Precondition*: For the f_i to be indistinguishable, the R_i need to be indistinguishable

- Encode indistinguishable attributes as PRV $R(L)$, $|\text{dom}(L)| = M$
- Then, encode interim utilities U_i as utility PRV $U(L)$
- Logical variables of utility PRV always follow logical variables in PRVs of utility function

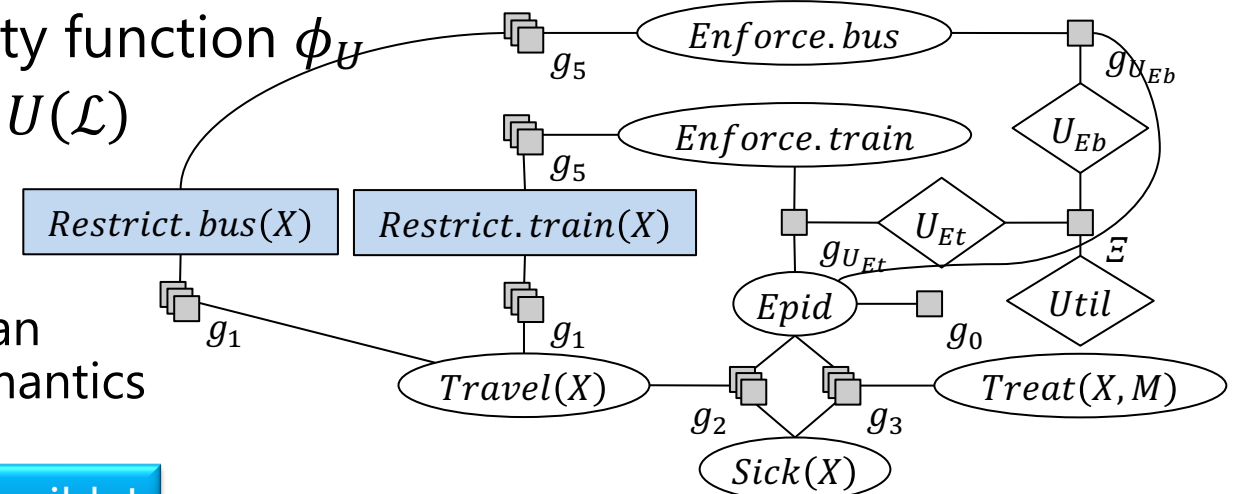
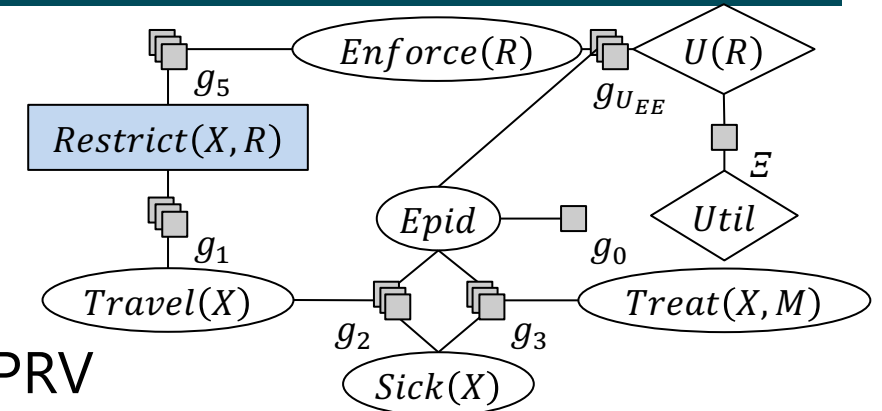


2. Set of Indistinguishable Attributes

- Extended syntax: Decision model

$$G = \{g_i\}_{i=1}^n \cup \{g_U\} \cup \{E\}$$

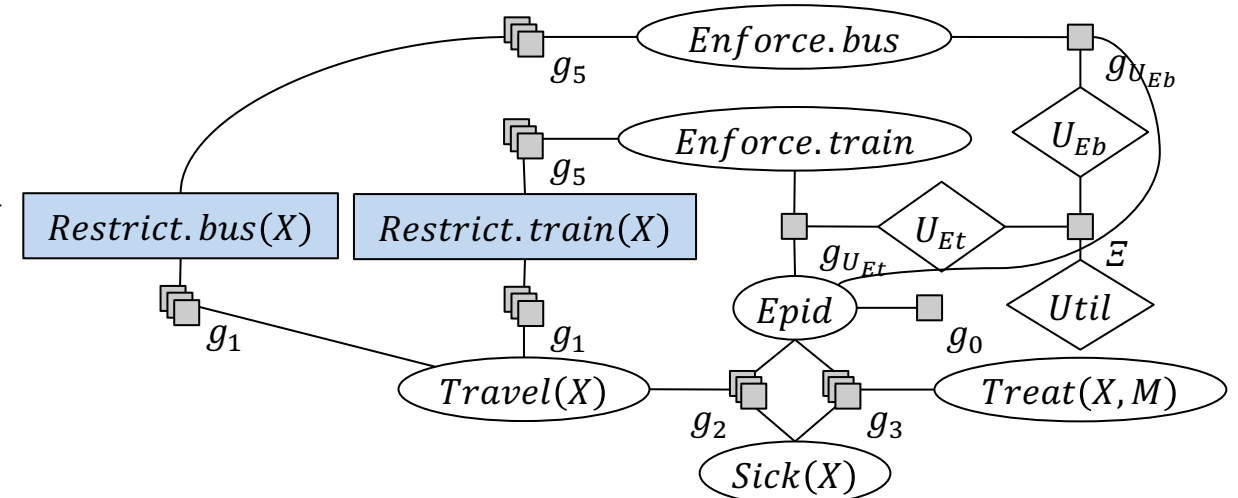
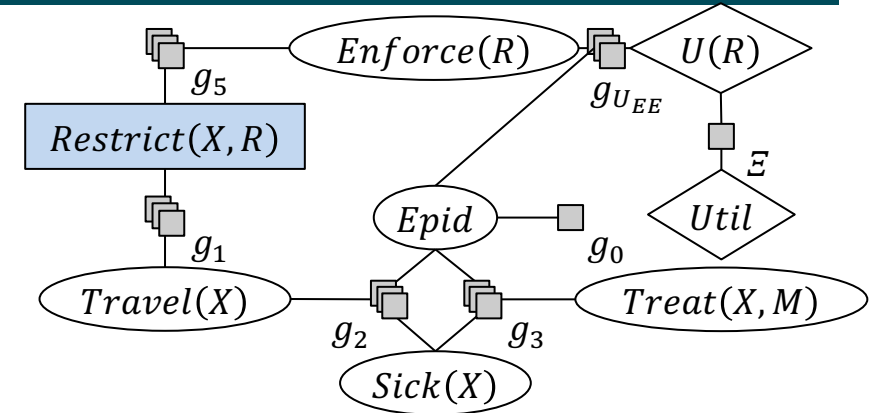
- $g_i = \phi_i(\mathcal{A}_i)_{|C_i}$ parfactors with (decision) PRVs as arguments
- $g_U = \phi_{U(\mathcal{L})}(\mathcal{A})$ a utility *parfactor* and $U(\mathcal{L})$ a utility PRV
 - $\mathcal{L} = \text{lv}(\mathcal{A})$ holds
 - $\text{gr}(g_U) = \{f_1, \dots, f_m\}$, all f_i with utility function ϕ_U
- E a combination function, combining $U(\mathcal{L})$ into one U in lifted way (for liftability)
 - Addition yields a multiplication
 - Compare multiplication leading to an exponentiation in multiplicative semantics



As of now, logical variables in utility model possible!

2. Set of Indistinguishable Attributes: Example

- Example:
 - Assume that effort for enforcing travel restrictions on busses and trains is identical
 - Ground:
 - Utility factor $\phi_{U_{Eb}}(Epid, Enforce.bus)$
 - Utility factor $\phi_{U_{Et}}(Epid, Enforce.train)$
 - Lifted:
 - Utility parfactor $\phi_{U(R)}(Epid, Enforce(R))$
 - T constraint with $\text{dom}(R) = \{train, bus\}$
 - Combination function: addition
 - Lifted: multiplication with $|\text{dom}(R)|$



2. Set of Indistinguishable Attributes: EU Query & MEU Problem

- Given a decision model $G = G_P \cup G_U \cup \{E\} = \{g_i\}_{i=1}^n \cup \{g_U\} \cup \{E\}$
 - Query for an **expected utility (EU)**: sum over $\text{gr}(\text{rv}(g_U))$

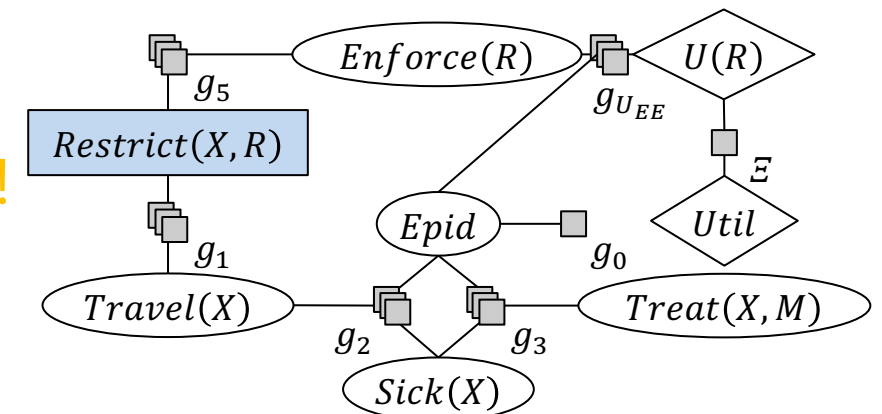
$$eu(\mathbf{e}, \mathbf{d}) = \sum_{v \in \text{ran}(\text{gr}(\text{rv}(G_U) \setminus E \setminus D))} P(\mathbf{v} | \mathbf{e}, \mathbf{d}) \cdot \mathbb{E} \left[\phi_{U_1} \left(\pi_{\mathcal{R}_1}(\mathbf{v}, \mathbf{e}, \mathbf{d}) \right), \dots, \phi_{U_m} \left(\pi_{\mathcal{R}_m}(\mathbf{v}, \mathbf{e}, \mathbf{d}) \right) \right]$$

- MEU problem: *no changes*

$$\text{meu}(G | \mathbf{e}) = (\mathbf{d}^*, eu(\mathbf{e}, \mathbf{d}^*))$$

$$\mathbf{d}^* = \underset{d \in \text{ran}(D)}{\text{argmax}} eu(\mathbf{e}, d)$$

- But: Given semantics, EU query calculation **not lifted!**
 → Can we avoid grounding?

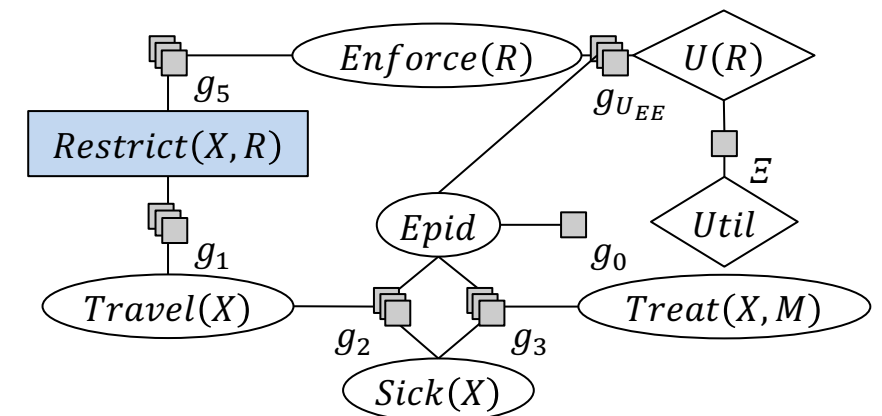


2. Set of Indistinguishable Attributes: Liftability

- Given a decision model $G = G_P \cup G_U \cup \{E\} = \{g_i\}_{i=1}^n \cup \{g_U\} \cup \{E\}$
 - Query for an **expected utility (EU)**: sum over $\text{gr}(\text{rv}(g_U))$

$$eu(\mathbf{e}, \mathbf{d}) = \sum_{\mathbf{v} \in \text{ran}(\text{gr}(\text{rv}(G_U) \setminus E \setminus D))} P(\mathbf{v} | \mathbf{e}, \mathbf{d}) \cdot \mathbb{E} \left[\phi_{U_1} \left(\pi_{\mathcal{R}_1}(\mathbf{v}, \mathbf{e}, \mathbf{d}) \right), \dots, \phi_{U_m} \left(\pi_{\mathcal{R}_m}(\mathbf{v}, \mathbf{e}, \mathbf{d}) \right) \right]$$

- Changes in calculations for $eu(\mathbf{e}, \mathbf{d})$ with $\text{rv}(G_U)$ now containing logical variables
 - $P(\mathbf{v} | \mathbf{e}, \mathbf{d})$ a parameterised query with $\mathbf{V} = \text{rv}(G_U)$
 - If query liftable, then \mathbf{V} as CRVs in answer → liftable
- But: logical variables in g_U not counted
 - If E addition: additive count-conversion for utility parafactors
 - Sum then over range of CRVs (include $Mul(h)$!)
 - Lifted calculations: Sum polynomial in domain sizes



2. Set of Indistinguishable Attributes: Additive Count-Conversion

- Operator:

Operator 2 Count-conversion for utility parafactors

Operator COUNT-CONVERT

Inputs:

- (1) Utility parafactor $g_u = \phi_{U(\mathbf{X})}(\mathcal{A})|_C$
- (2) logical variable $X \in lv(\mathcal{A})$ and $X \in \mathbf{X}$, to count in g_u

Preconditions:

- (1) There is exactly one atom $A_i \in \mathcal{A}$ with $X \in lv(A_i)$.
- (2) X is count-normalised w.r.t. $\mathbf{Z} = lv(\mathcal{A}) \setminus \{X\}$ in C .
- (3) For all counted logical variables $X^\#$ in g : $\pi_{X, X^\#}(C) = \pi_X(\pi_{\mathbf{X}}(C)) \times \pi_{X^\#}(\pi_{\mathbf{X}}(C))$.

Output: utility parafactor $\phi'_{U'}(\mathcal{A}')|_C$ such that

- (1) $U' = \#_X[U(\mathbf{X})]$,
- (2) $\mathcal{A}' = (A_1, \dots, A_{i-1}) \circ A'_i \circ (A_{i+1}, \dots, A_n)$, $A'_i = \#_X[A_i]$, and
- (3) for each valuation \mathbf{a}' to \mathcal{A}' with $\mathbf{a}'_i = h$,

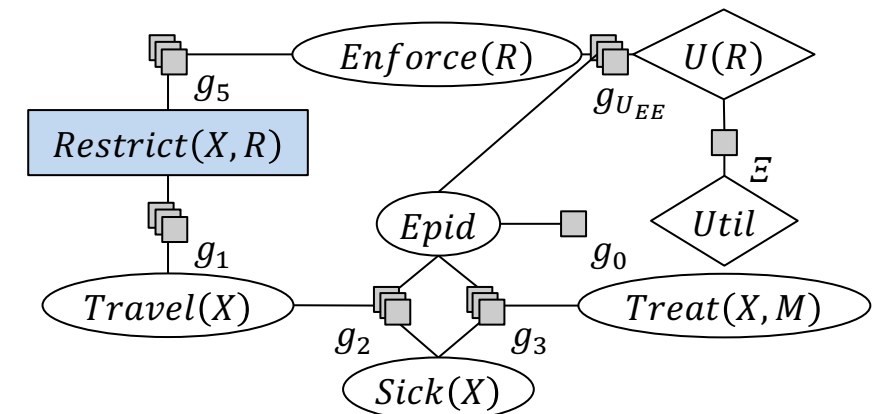
$$\phi'_{U'}(\mathbf{X})(\dots, a_{i-1}, h, a_{i+1}, \dots) = \sum_{a \in \text{ran}(A_i)} h(a) \phi_{U(\mathbf{X})}(\dots, a_{i-1}, a, a_{i+1}, \dots)$$

where h is a histogram $\{(a_i, n_i)\}_{i=1}^m$ with $m = |\text{ran}(A_i)|$, $a_i \in \text{ran}(A_i)$, $n_i \in \mathbb{N}$, and $\sum_{a_i \in \mathcal{R}(A_i)} h(a_i) = \text{ncount}_{X|\mathbf{Z}}(C)$, and $h(a_i) = n_i$.

Postcondition: $G_U \equiv G_U \setminus \{g_u\} \cup \text{COUNT-CONVERT}(g_u, X)$

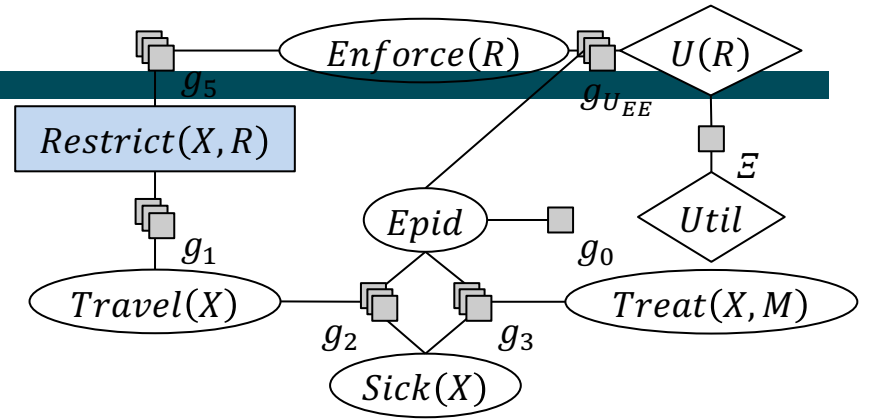
Compare multiply count-conversion:

$$\begin{aligned} & \phi'(\dots, a_{i-1}, h, a_{i+1}, \dots) \\ &= \prod_{a_i \in \text{ran}(A_i)} \phi(\dots, a_{i-1}, a_i, a_{i+1}, \dots)^{h(a_i)} \end{aligned}$$



E	$E(R)$	ϕ
false	false	10
false	true	4
true	false	8
true	true	5

E	$E(R)$	$\phi_{U(R)}$
false	false	5
false	true	0
true	false	-5
true	true	-10



E	$\#_R[E(R)]$	$\phi^\#$	ϕ^n
false	[0,2]	$4^0 \cdot 10^2 = 100$	0.263
false	[1,1]	$4^1 \cdot 10^1 = 40$	0.105
false	[2,0]	$4^2 \cdot 10^0 = 16$	0.042
true	[0,2]	$5^0 \cdot 8^2 = 64$	0.168
true	[1,1]	$5^1 \cdot 8^1 = 40$	0.105
true	[2,0]	$5^2 \cdot 8^0 = 40$	0.105

E	$\#_R[E(R)]$	$\phi'_{\#_R[U(R)]}$
false	[0,2]	$0 \cdot 0 + 2 \cdot 5 = 10$
false	[1,1]	$1 \cdot 0 + 1 \cdot 5 = 5$
false	[2,0]	$2 \cdot 0 + 0 \cdot 5 = 0$
true	[0,2]	$0 \cdot -10 + 2 \cdot -5 = -10$
true	[1,1]	$1 \cdot -10 + 1 \cdot -5 = -15$
true	[2,0]	$2 \cdot -10 + 0 \cdot -5 = -20$

$\phi^\# \cdot \phi'_{\#_R[U(R)]}$
$0.263 \cdot 10 = 2.630$
$0.105 \cdot 5 = 0.525$
$0.042 \cdot 0 = 0.000$
$0.168 \cdot -10 = -1.680$
$0.105 \cdot -15 = -1.575$
$0.105 \cdot -20 = -2.100$

$$eu = 1 \cdot 2.630 + 2 \cdot 0.525 + 1 \cdot 0 + 1 \cdot -1.68 + 2 \cdot -1.575 + 1 \cdot -2.1 = -3.25$$

$$\text{Sum of } \phi^\# \text{ potentials} = 1 \cdot 100 + 2 \cdot 40 + 1 \cdot 16 + 1 \cdot 64 + 2 \cdot 40 + 1 \cdot 40 = 380$$



2. Set of Indistinguishable Attributes: Simplification

- Assume all groundings are independent
 - $\forall \mathcal{R}(\mathbf{x}), \mathcal{R}(\mathbf{y}) \in \text{gr}(\text{rv}(g_U)) : (\mathcal{R}(\mathbf{x}) \perp \mathcal{R}(\mathbf{y}) | \mathbf{e}, \mathbf{d})$
- Then,

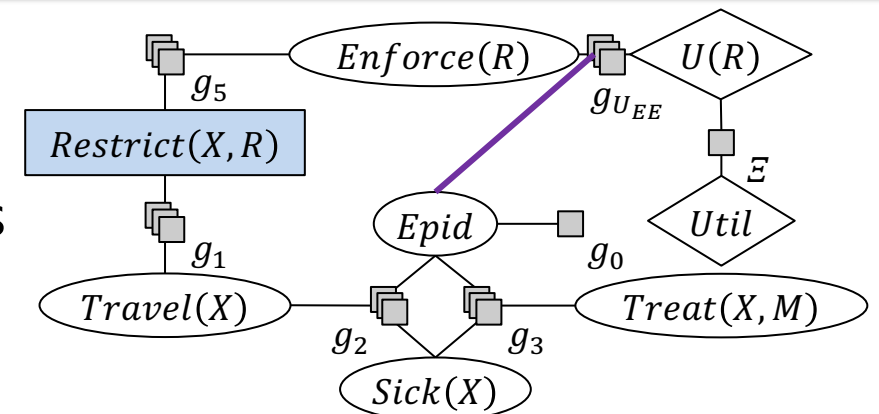
$$\begin{aligned}
 eu(\mathbf{e}, \mathbf{d}) &= \sum_{u=1}^m \sum_{\mathbf{a}_u \in \text{ran}(\text{rv}(g_U))} P(\mathbf{a}_u | \mathbf{e}, \mathbf{d}) \cdot \phi_u(\mathbf{a}_u) \\
 &= m \cdot \sum_{\mathbf{a}_u \in \text{ran}(\text{rv}(g_U))} P(\mathbf{a}_u | \mathbf{e}, \mathbf{d}) \cdot \phi_u(\mathbf{a}_u)
 \end{aligned}$$

- $P(\mathbf{a}_u | \mathbf{e}, \mathbf{d})$ a representative query, i.e., a query over $\mathbf{A}_u = \text{rv}(g_U)$ with a representative grounding \mathbf{x} of its logical variables $\mathbf{X} = \text{lv}(\mathbf{A}_u)$
- $m = |\text{gr}(g_U)|$

Lifted calculation:

- Sum *independent* of domain sizes m
- Multiplication with domain size in $O(\log m)$

Here, groundings are not independent because of *Epid*; without *Epid*, the groundings would be independent (of each other and anything else in the model)



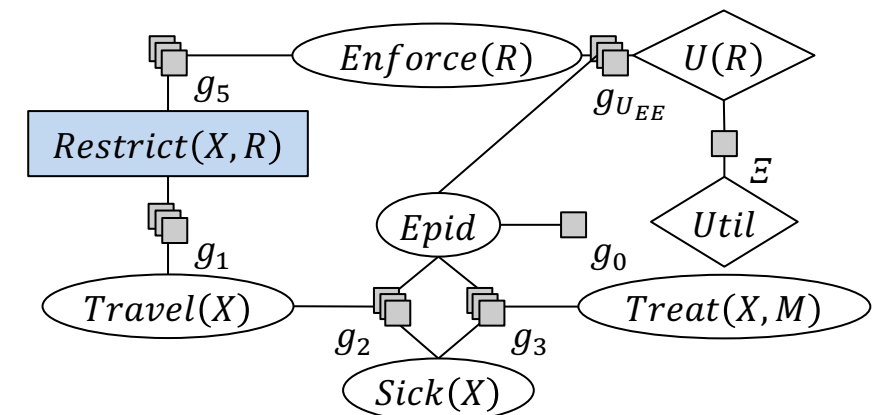
2. Set of Indistinguishable Attributes: MEU-LVE

- Implement ADD-COUNT-CONVERT operator
 - LVE with ADD operator and ADD-COUNT-CONVERT operator referred to as LVE^{addCC}
- Changes in MEU-LVE
 - Input: decision model $G = G_P \cup G_U = \{g_i\}_{i=1}^n \cup \{g_U\}$
 - In for-loop:

$g \leftarrow LVE(M \setminus G_U, rv(G_U), \mathbf{d})$ ▷ g normalised
 $eu \leftarrow LVE^{\text{addCC}}(G_U \cup \{g\}, \emptyset, \mathbf{d})$

- If \mathcal{E} not addition, need to implement (change LVE^{addCC} call)
- Count-converts the PRVs in g_U before multiplying with g and summing out the remaining variables
 - If PRVs in g_U not count-convertible → Ground logical variable and join partially grounded utility parafactors using ADD operator

If parameterised query *liftable*, then:
Complexity polynomial in M



2. Set of Indistinguishable Attributes: Logical Variables in Utility PRVs

- Definition says $\mathcal{L} = \text{lv}(\mathcal{A})$ holds for a utility parfactor $\phi_{U(\mathcal{L})}(\mathcal{A})$ a utility *parfactor* and $U(\mathcal{L})$ a utility PRV
- What about $\mathcal{L} \subset \text{lv}(\mathcal{A})$?
 - Given grounding semantics, *not valid* as combination not defined
 - Example: $\phi_{Util}(Restrict(X), Epid)$
 - Groundings:
 $\phi_{Util}(Restrict(alice), Epid), \phi_{Util}(Restrict(eve), Epid), \phi_{Util}(Restrict(bob), Epid)$
- What about $\mathcal{L} \supset \text{lv}(\mathcal{A})$?
 - Given grounding semantics, *valid* as only more utility factors occur
 - Example: $\phi_{Util(R,C)}(Enforce(R), Epid), |\text{dom}(C)| = 3$
 - Groundings: $\phi_{U(b,c_1)}(Enforce(b), Epid), \phi_{U(b,c_2)}(Enforce(b), Epid),$
 $\phi_{U(b,c_3)}(Enforce(b), Epid),$
 $\phi_{U(t,c_1)}(Enforce(t), Epid), \phi_{U(t,c_2)}(Enforce(t), Epid),$
 $\phi_{U(t,c_3)}(Enforce(t), Epid),$

2. Set of Indistinguishable Attributes: Eliminating Logical Variables

- Grounding a utility parfactor with additional logical variables in its utility PRV leads to copies of utility factors over the same inputs that can be combined based on \mathcal{E}
 - Eliminate beforehand as a first step to simplify a model
- Operator for eliminating additional logical variables in a utility PRV of a utility parfactor

Operator 4 Logical variable elimination in utility PRVs

Operator ELIM-LOG-VARS

Inputs:

- (1) Utility parfactor $g_u = \phi_{U(\mathbf{X})}(\mathcal{A})|_C$
- (2) Logical variables $\mathbf{Y} \subseteq \mathbf{X}$

Preconditions:

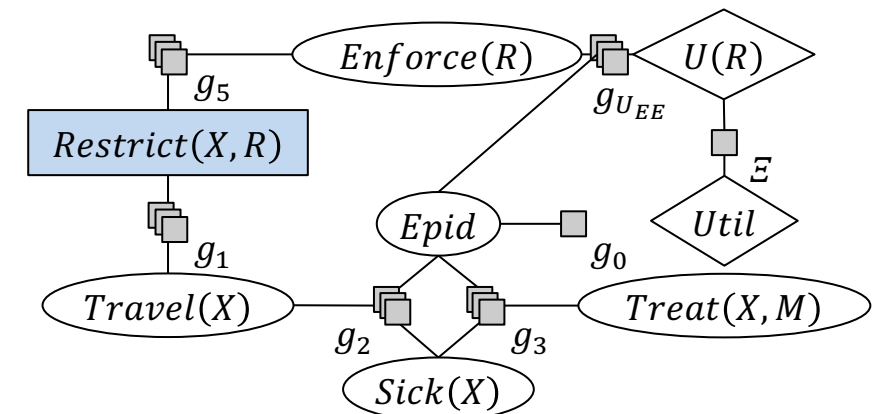
- (1) \mathbf{Y} do not occur in \mathcal{A} , i.e., $\mathbf{Y} \cap lv(\mathcal{A}) = \emptyset$.
- (2) \mathbf{Y} are count-normalised w.r.t. $lv(\mathcal{A})$ in C .

Output: utility parfactor $\phi'_{U(\mathbf{Z})}(\mathcal{A})|_{C'}$ such that

- (1) $\mathbf{Z} = \mathbf{X} \setminus \mathbf{Y}$,
- (2) $C' = C \setminus \mathbf{Y}$ (remove \mathbf{Y} and its constants from C), and
- (3) for each valuation \mathbf{a} to \mathcal{A} ,

$$\phi'_{U(\mathbf{Z})}(\mathbf{a}) = ncount_{\mathbf{Y}|\mathbf{Z}}(C) \cdot \phi_{U(\mathbf{X})}(\mathbf{a})$$

Postcondition: $G_U \equiv G_U \setminus \{g_u\} \cup \text{ELIM-LOG-VARS}(g_u, \mathbf{Y})$



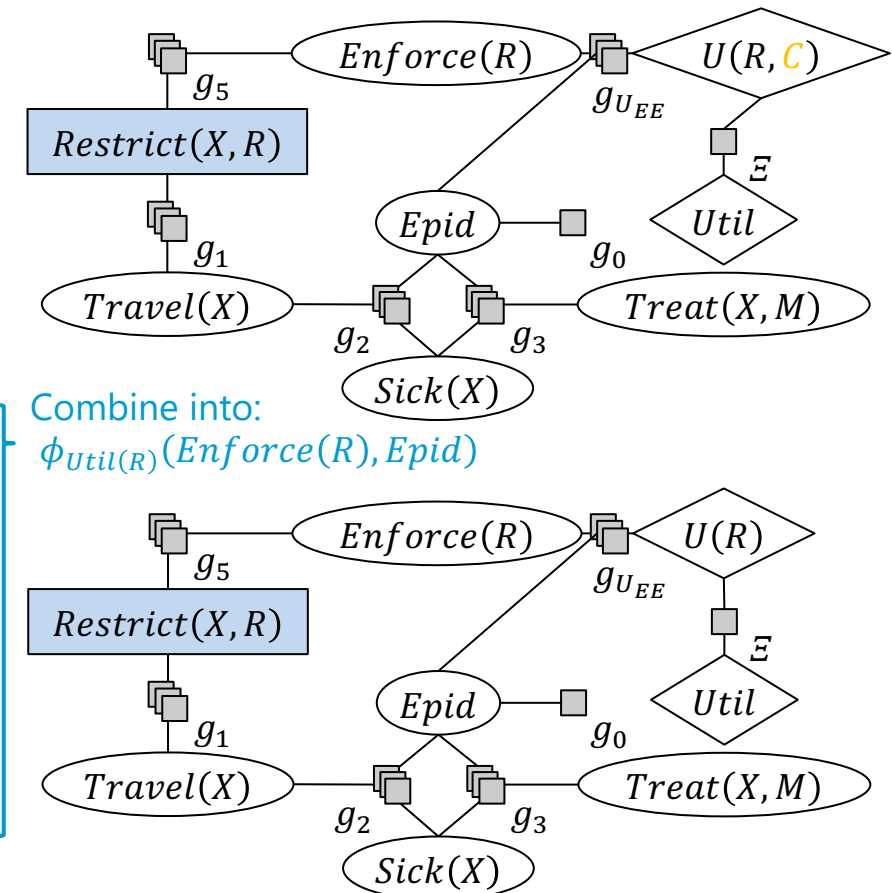
2. Set of Indistinguishable Attributes: Eliminating Logical Variables

- Example: $\phi_{Util(R,C)}(Enforce(R), Epid)$, $|\text{dom}(C)| = 3$
 - New utility parfactor: $\phi_{Util(R)}(Enforce(R), Epid)$
 - For all $en \in \text{ran}(Enforce(R))$, $ep \in \text{ran}(Epid)$:

$$\phi_{Util(R)}(en, ep) = 3 \cdot \phi_{Util(R,C)}(en, ep)$$
 - Ground comparison:
 - For all $en \in \text{ran}(Enforce(b))$, $ep \in \text{ran}(Epid)$:

$$\phi_{U(b,c_1)}(en, ep) + \phi_{U(b,c_2)}(en, ep) + \phi_{U(b,c_3)}(en, ep) = 3 \cdot \phi_{U(R,C)}(en, ep)$$
 - For all $en \in \text{ran}(Enforce(t))$, $ep \in \text{ran}(Epid)$:

$$\phi_{U(t,c_1)}(en, ep) + \phi_{U(t,c_2)}(en, ep) + \phi_{U(t,c_3)}(en, ep) = 3 \cdot \phi_{U(R,C)}(en, ep)$$



Structure in Multi-attribute Settings

- So far: Set of attributes without structure
 - Single utility functions mapping to one utility
 - Example: $\phi_U(\text{Interference}, \text{Epid})$

- Cases with structure:

1. Set of (distinguishable) attributes with structure

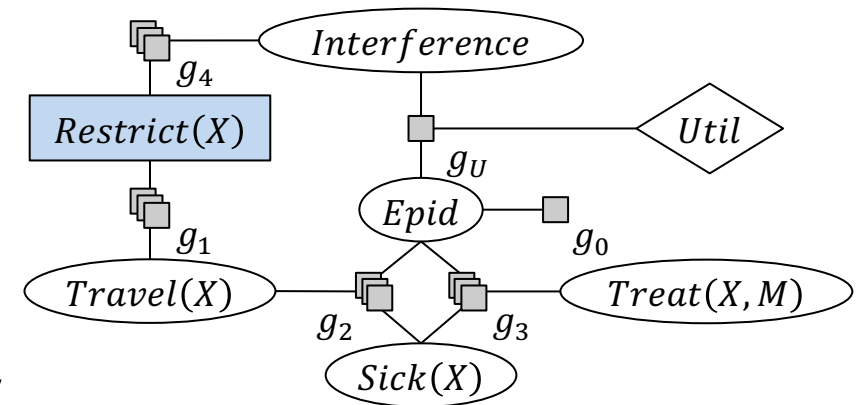
- Set of utility functions, mapping to interim utilities, combined into one overall utility

2. Set of indistinguishable attributes

- Utility parfactor mapping to an interim utility PRV, which is combined into one utility

3. Sets of distinguishable and indistinguishable attributes

- Set of utility parfactors and utility factors, combined into one utility
 - Considering structure requires a combination function \mathcal{E}



3. Sets of Distinguishable & Indistinguishable Attributes

- Full expressiveness in terms of syntax: Allows for a set of utility parfactors as utility model
- Full decision model:
 - Syntax

$$G = \{g_i\}_{i=1}^n \cup \{g_u\}_{u=1}^m \cup \{E\}$$

- $g_i = \phi_i(\mathcal{A}_i)|_{C_i}$ parfactor with (decision) PRVs as arguments
- $g_u = \phi_{U_u(\mathcal{L}_u)}(\mathcal{A}_u)|_{C_u}$ utility parfactor, mapping to a utility PRV $U_u(\mathcal{L}_u)$ with $\mathcal{L}_u = \text{lv}(\mathcal{A}_u)$
- E a combination function, combining all $U_u(\mathcal{L}_u)$ into one U
- Semantics: grounding semantics
 - Given an action assignment \mathbf{d} , full joint $P_{G_P}[\mathbf{d}]$ over grounding, multiplying, and normalising
 - EU queries sum over $\text{gr}(\text{rv}(G_U)) \rightarrow$ Lifiable parameterised query or simplification for lifiability
 - MEU problem: With \mathbf{D} the decision PRVs in G

$$\text{meu}(G|\mathbf{e}) = (\mathbf{d}^*, eu(\mathbf{e}, \mathbf{d}^*)) \quad \mathbf{d}^* = \underset{\mathbf{d} \in \text{ran}(\mathbf{D})}{\text{argmax}} eu(\mathbf{e}, \mathbf{d})$$

3. Sets of Distinguishable & Indistinguishable Attributes: Example

- Decision model $G = G_P \cup G_U \cup \{E\}$

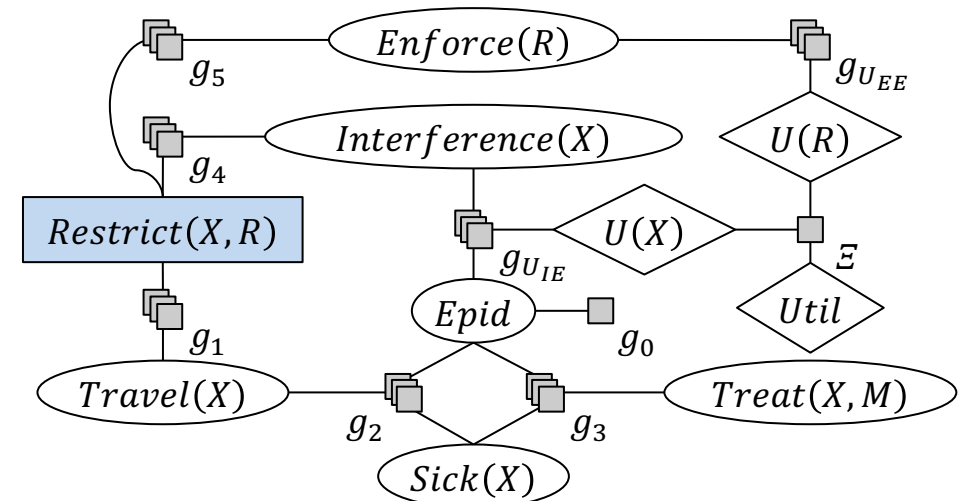
- $G_P = \{g_i\}_{i=0}^5$
 - $g_0 = \phi_0(Epid)$
 - $g_1 = \phi_1(Restrict(X, R), Travel(X))$
 - $g_2 = \phi_2(Epid, Sick(X), Travel(X))$
 - $g_3 = \phi_3(Epid, Sick(X), Treat(X, M))$
 - $g_4 = \phi_4(Restrict(X, R), Enforce(R))$
 - $g_5 = \phi_5(Restrict(X, R), Interf. (X))$

- $G_U = \{g_u\}_{u=0}$
 - $g_{UEE} = \phi_{U(R)}(Enforce(R))$
 - $g_{UIE} = \phi_{U(X)}(Interference(X), Epid)$

- E addition with additive operators for LVE

- In EU query

- Independences given $Restrict(X, R)$
 - Between utility parfactor PRVs \checkmark
 - Between groundings of $Enforce(R)$ \checkmark



MEU Problems: Alternative Solution Approach

- Solving an MEU problem in decision model G with $E(\mathbf{v})$ as short form for utility model:

$$\text{meu}(G|\mathbf{e}) = (\mathbf{d}^*, eu(\mathbf{e}, \mathbf{d}^*)), \mathbf{d}^* = \underset{\mathbf{d} \in \text{ran}(\mathbf{D})}{\text{argmax}} eu(\mathbf{e}, \mathbf{d}) = \underset{\mathbf{d} \in \text{ran}(\mathbf{D})}{\text{argmax}} \sum_{\mathbf{v} \in \text{ran}(\text{gr}(\text{rv}(G_U) \setminus E \setminus \mathbf{D}))} P(\mathbf{v}|\mathbf{e}, \mathbf{d}) \cdot E(\mathbf{v})$$

- So far: for each \mathbf{d} , set \mathbf{d} , eliminate all PRVs not in G_U , eliminate remaining PRVs
 - Advantage: Reduced model by setting \mathbf{d} (possible independences)
 - Disadvantage: possibly large $P(\mathbf{v}|\mathbf{e}, \mathbf{d})$ has to be computed
- Alternative: Compute a **maximum-a-posteriori (MAP) assignment** for the decision PRVs
 - Eliminate all non-decision PRVs in G_P by summing out, eliminate the decision PRVs by *maxing* out (replace sum operation by max-out operation)
 - Max-out: for each remaining world, pick the assignment with maximum value and store
 - Advantage: Does not require computing $P(\mathbf{v}|\mathbf{e}, \mathbf{d})$, easier to exploit factorisation
 - Disadvantage: Only a ranking (no true expected utility), no further independences through \mathbf{d}

Some References

- MEU in parfactor-based decision models
 - Warning: not as detailed as in these slides

Version using an early version of LVE, mashing early parfactor graphs and MLNs:

Udi Apsel and Ronan I. Brafman. Extended Lifted Inference with Joint Formulas. In: *UAI-11 Proceedings of the 27th Conference on Uncertainty in Artificial Intelligence*, 2011.

MEU-LVE: Marcel Gehrke, Tanya Braun, Ralf Möller, Alexander Waschkau, Christoph Strumann, and Jost Steinhäuser. Towards Lifted Maximum Expected Utility. In: *Proceedings of the First Joint Workshop on Artificial Intelligence in Health in Conjunction with the 27th IJCAI, the 23rd ECAI, the 17th AAMAS, and the 35th ICML*, 2018.

Marcel Gehrke, Tanya Braun, Ralf Möller, Alexander Waschkau, Christoph Strumann, and Jost Steinhäuser. Lifted Maximum Expected Utility. In: *Artificial Intelligence in Health*, 2019.

- Markov logic decision networks (MLDNs)
 - MLN + parameterised decisions + utility weights
 - Probability + utility weights per first-order formula
 - Use weighted model counting to solve MEU problem

MLDNs: Aniruddh Nath and Pedro Domingos. A Language for Relational Decision Theory. In: *Proceedings of the International Workshop on Statistical Relational Learning*, 2009.

MLDNs + WMC: Udi Apsel and Ronan I. Brafman. Lifted MEU by Weighted Model Counting. In: *AAAI-12 Proceedings of the 26th AAAI Conference on Artificial Intelligence*, 2012.

- Decision-theoretic Probabilistic Prolog (DTProbLog)
 - Utilities of DTProbLog programs combined into EU over theory defined by programs

DTProbLog: Guy Van den Broeck, Ingo Thon, Martijn van Otterlo, and Luc De Raedt. DTProbLog: A Decision-Theoretic Probabilistic Prolog. In: *AAAI-10 Proceedings of the 24th AAAI Conference on Artificial Intelligence*, 2010.

Interim Summary

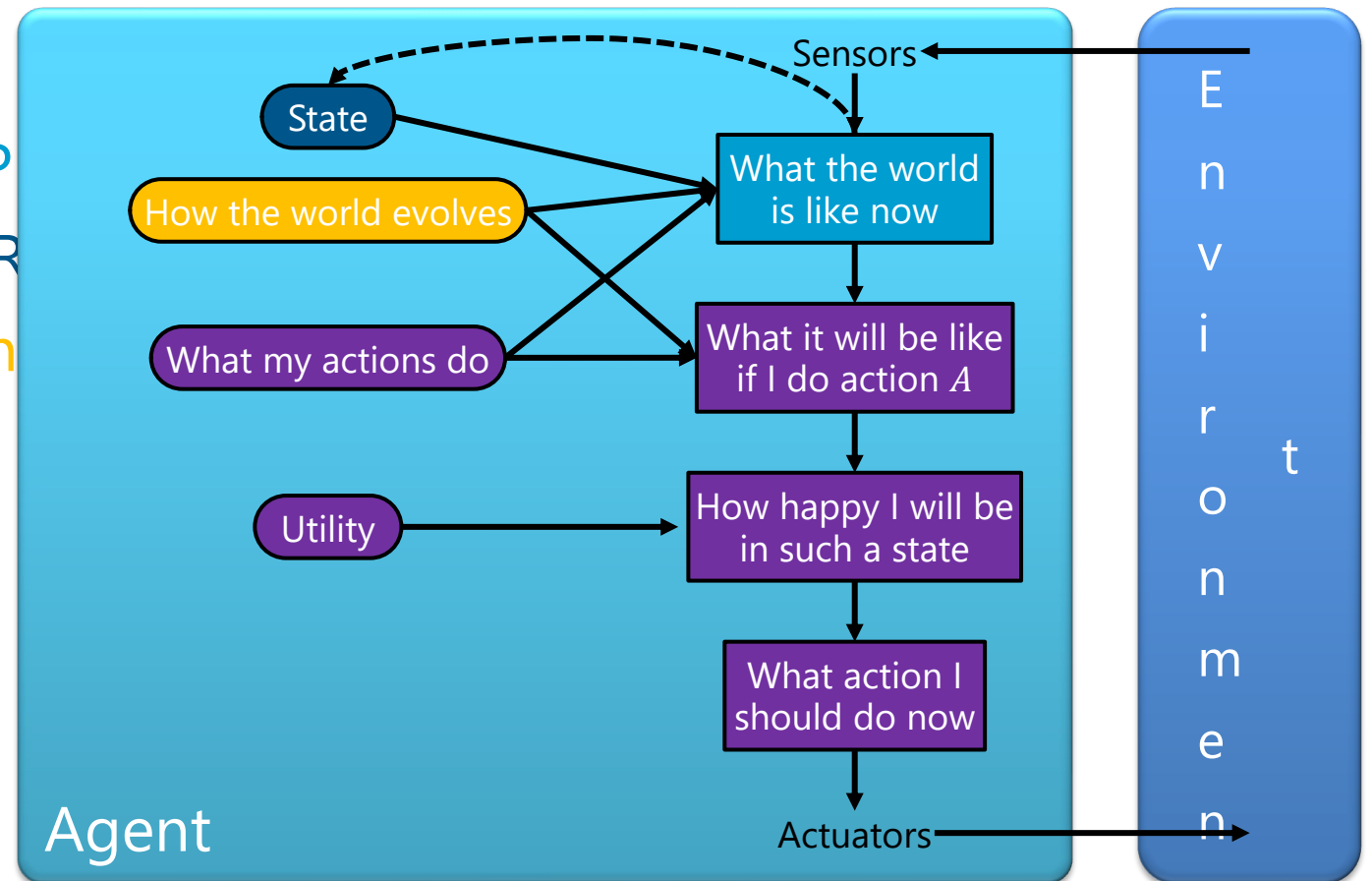
- Decision models
 - Probabilistic graphical model extended with decision and utility variables
- Parfactor-based version
 - Decision PRVs, utility PRVs, utility parfactors, combination function
 - Collective decisions for groups of indistinguishable constants
- EU queries, MEU problem
 - Find set of actions (decisions) that lead to maximum expected utility
 - MEU-LVE using calls to LVE and LVE operators to answer EU queries
 - Combination function addition → additive join + count-conversion

Contents in this Lecture Related to *Utility-based Agents*

- Further topics
 3. (Episodic) PRMs
 4. Lifted inference (in episodic PRMs)
 5. Lifted learning (of episodic PRMs)
 6. Lifted sequential PRMs and inference
 7. Lifted decision making

Sequential Decision Models

- Uncertainty modelled by probabilities
- Relational aspect using logical variables
- Temporal aspect by time indexing
- Decisions and effects by actions & utilities in a temporal model



E
n
v
i
r
o
n
m
e
n
t

Outline: 7. Lifted Decision Making

A. *Utility theory*

- Preferences, maximum expected utility (MEU) principle
- Utility function, multi-attribute utility theory

B. *Static decision making*

- Modelling, semantics, inference tasks
- Inference algorithm: LVE for MEU as an example

C. *Sequential decision making*

- Modelling, semantics, temporal MEU problem
- Inference algorithm: LDJT for MEU as an example
- Acting