Intelligent Agents Dynamic Epistemic Logic – Part 1

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Todays lecture based on

 The AAMAS 2019 Tutorial "EPISTEMIC REASONING IN MULTI-AGENT SYSTEMS", Part 4: Dynamic Epistemic Logic http://people.irisa.fr/Francois.Schwarzentruber/2019AAMAStutorial/



MODELING ACTIONS



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In the verification/model checking community







In philosophy and AI

Type of mechanism of actions is important

Type of mechanism	Example
Public /private announcement	She knows you hold 5 •
Public action	Play card <mark>5 </mark>
Private action	Secretely remove card 5 •
Belief revision	Revise believes (entailing $\neg p$) after being told p

- There is a dedicated logic for the first type of announcementes: PAL (Public announcement logic)
- What kind of formalism to use to handle all of them?



Dynamic Epistemic Logic (DEL)

	State	Action
Classical planning	has <mark>5</mark> ◊	pre: has5 ∘ post: has5 ∘≔ <i>false</i>
Logic DEL ^{1),2)} = Kripkean models of classical planning	$has 5 \diamond$ $\neg has 5 \diamond$	pre: has5 ∘ post: has5 ∘:= false pre: true post: -

- Action: remove 5 •
- blue agent does not know
- (Baltag et al., 1998)
 (van Ditmarsch et al, 2007)



Computing the next state: product update





Some syntactic specifications/logics

Logic	Example sentence
Game description language (Love et al. 2008), (Thielscher, 2017)	Agent a sees the game position
Flatland (Babiani et al, 2021), (Gasquet et al. 2014), (Gasquet et al, 2016),	Agent a sees agent b
Visibility atoms (Charrier et al, 2016)	Agent a sees truth value of p
Paying attention to public announcements (Bolander et al, 2016)	$B_a payAtt(b) \rightarrow [p!]B_a B_b p$
Asynchronous announcements (Knight et al, 2019)	[p!][read _a]K _a p
Epistemic gossip (Ditmarsch et al 2017)	[call _{ab}]K _a secret _b



Syntactic Specification



Models of DEL

Epistemic temporal models















Timeline

	1918	1930	1940	1950	1960	1970	1980	1990	2000	2010	
Log	modal logic giC	epistemic logic dynamic logic DEL									
Verification			-	LTL, CTL	ETL S	5 trategic re ATL	= = = = = = = easoning _ SL				
		Model checking BDD SAT works!									
AI		Planning			Conf	Conformant planning					
		Belief revision				MA-STRIPS dec-POMDP					
									GDL		



Timeline



EVENT MODELS



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Examples of actions

(Baltag et al. 1998)





Example (Private announcement of p to a)







Assume that agent *a* transfers a marble from a basket to a box - not seen by agent *b*

Example (Transfer marble from basket to box)





Formal Definition

Definition

- An event model $\mathcal{E} = (E, (R_a^E)_{a \in AGT}, pre, post)$ is a tuple where
 - $E = \{e, e', ...\}$ is a non-empty set of possible events
 - $R_a^{\mathcal{E}} \subseteq E \times E$ is an accessibility relation on *E* for agent *a*
 - $pre: E \to \mathcal{L}_{EL}$ is a precondition function
 - $post: E \times AP \rightarrow \mathcal{L}_{EL}$ is a postcondition function
- A pair (*E*, *e*) is called an action where *e* represents the actual event of (*E*, *e*)
- A pair (\mathcal{E}, E_0) , for $E_0 \subseteq E$, is a non-deterministic action. The set E_0 is the set of triggerable events.



Example (Deterministic action= single-pointed event model)

pre:
$$p$$

post: $p \coloneqq q$
 a
 b
pre: $true$
post: $-$
 a, b

Example (Non-deterministic action= multi-pointed event model)



Public Actions

Definition

An action is said to be public if the accessibility relations in the underlying event model are self-loops





Non-ontic actions

Definition

An action is said to be non – ontic if the postconditions are trivial: for all $e \in E$, for all propositions $p \in AP$: post(e, p) = p





Effect of a public announcement

Publicly announcing ϕ leads to keeping only the ϕ worlds.





Can try this out on several examples in Hintikka's world.



Example (Update Product) a, b $\begin{pmatrix} & \bullet \\ \bullet & \bullet \\$ a \bigcap pre: m_a b post: pre: **true** post: – a, b b b a (b a, b $\underbrace{\bullet}_{a} \xrightarrow{a} \underbrace{\bullet}_{a} \underbrace{\bullet}_{a} \underbrace{\bullet}_{b} \underbrace{\bullet}_{a} a, b$ b → a (👘 📀 b b b b a, b $(\begin{array}{c} & & \\ & & \\ & & \\ & & \\ \end{array} \right) \xrightarrow{a} \left(\begin{array}{c} & & \\ & & \\ & & \\ \end{array} \right) \xrightarrow{a} \left(\begin{array}{c} & & \\ & & \\ & & \\ \end{array} \right) \xrightarrow{a} \left(\begin{array}{c} & & \\ & & \\ & & \\ \end{array} \right) \xrightarrow{a} \left(\begin{array}{c} & & \\ & & \\ & & \\ \end{array} \right) \xrightarrow{a} \left(\begin{array}{c} & & \\ & & \\ & & \\ \end{array} \right) \xrightarrow{a} \left(\begin{array}{c} & & \\ & & \\ & & \\ \end{array} \right) \xrightarrow{a} \left(\begin{array}{c} & & \\ & & \\ & & \\ \end{array} \right) \xrightarrow{a} \left(\begin{array}{c} & & \\ & & \\ & & \\ \end{array} \right) \xrightarrow{a} \left(\begin{array}{c} & & \\ & & \\ & & \\ & & \\ \end{array} \right) \xrightarrow{a} \left(\begin{array}{c} & & \\ & & \\ & & \\ & & \\ \end{array} \right) \xrightarrow{a} \left(\begin{array}{c} & & \\ & &$



Formal Definition of Update Products

Definition

- Given
 - $\mathcal{M} = (W, \{R_a\}_{a \in AGT}, V)$
 - $\mathcal{E} = (E, (R_a^E)_{a \in AGT}, pre, post)$

(epistemic model) (event model)

- define the update product of *M* and *E* as the epistemic model $\mathcal{M} \otimes \mathcal{E} = (W^{\otimes}, \{R_a^{\otimes}\}_{a \in AGT}, V^{\otimes})$ where
 - $W^{\otimes} = \{(w, e) \in W \times E \mid \mathcal{M}, w \vDash pre(e)\}$
 - $R_a^{\otimes} = \{(w', e') \in W^{\otimes} \mid w R_a w' \text{ and } e R_a^{\varepsilon} e'\}$
 - $V^{\otimes}(w,e) = \{p \in AP \mid \mathcal{M}, w \models post(e,p)\}$

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Pointed update products

Definition

The successor state of an epistemic state (\mathcal{M}, w) by action (\mathcal{E}, e) is $(\mathcal{M}, w) \otimes (\mathcal{E}, e) = (\mathcal{M} \otimes \mathcal{E}, (w, e))$ if $(\mathcal{M}, w) \vDash pre(e)$, otherwise it is undefined.

Notation

- Write e for (\mathcal{E}, e)
- Write `*we*' for (*w*, *e*)
- Write $\mathcal{M} \otimes \mathcal{E}^n$ for $\mathcal{M} \otimes \mathcal{E} \otimes \mathcal{E} \dots \otimes \mathcal{E}$ (n-times)
- Write $we_1 \dots e_n \vDash \phi$ for $\mathcal{M} \otimes \mathcal{E}^n$, $we_1 \dots e_n \vDash \phi$,



Dynamic epistemic logic \mathcal{L}_{DELCK}

Definition

The language \mathcal{L}_{DELCK} extends \mathcal{L}_{ELCK} with dynamic (possibility) modalities $\langle \mathcal{E}, E_0 \rangle$ according to the following BNF:

 $\phi ::= \top | p | \neg \phi | (\phi \lor \phi) | K_a \phi | C_G \phi | < \mathcal{E}, E_0 > \phi$

Definition

The modelling relation \models for \mathcal{L}_{ELCK} is extended with the following clause:

 $\mathcal{M}, w \models \langle \mathcal{E}, \mathcal{E}_0 \rangle \phi$ iff there exists $e \in \mathcal{E}_0$ such that $\mathcal{M}, w \models pre(e)$ and $\mathcal{M} \otimes \mathcal{E}, (w, e) \models \phi$



Dual operator

Definition (Dual operator)

$[\mathcal{E}, \mathcal{E}_0]\phi \coloneqq \neg < \mathcal{E}, \mathcal{E}_0 > \neg \phi$

The induced semantics is $\mathcal{M}, w \models [\mathcal{E}, E_0] \phi$ iff for all $e \in E_0$ we have: If $\mathcal{M}, w \models pre(e)$ then $\mathcal{M} \otimes \mathcal{E}, (w, e) \models \phi$



Expressivity and Succinctness

Theorem (Baltag 98)

DEL and EL have the same expressivity

Proof idea: Remove dynamic operators $[\mathcal{E}, E]$ as demonstrated here for public announcements:

- Rembember $[\phi!]\psi$: if ϕ holds then after having anounced ϕ publicly, ψ holds.
- $[\phi!]p$: says the same as $(\phi \rightarrow p)$
- $[\phi!](\psi \land \chi)$: says the same as $([\phi!]\psi \land [\phi!]\chi)$
- $[\phi!] \neg \psi$: say
- $[\phi!]K_a\psi$:
- $[\phi!][\psi!]\chi$:

- says the same as $(\phi \rightarrow \neg [\phi!]\psi)$
- says the same as $(\phi \rightarrow K_a[\phi!]\psi)$
- says the same as $([\phi \land [\phi!]\psi!]\chi)$

Theorem (Lutz 2006)



Uhhh, a lecture with a hoepfully useful

APPENDIX



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Color Convention in this course

- Formulae, when occurring inline
- Newly introduced terminology and definitions
- Important results (observations, theorems) as well as emphasizing some aspects
- Examples are given with standard orange with possibly light orange frame
- Comments and notes
- Algorithms

