
Intelligent Agents

Dynamic Epistemic Logic – Part 1

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Today's lecture based on

- The AAMAS 2019 Tutorial „EPISTEMIC REASONING IN MULTI-AGENT SYSTEMS“, Part 4: Dynamic Epistemic Logic
<http://people.irisa.fr/Francois.Schwarzentruber/2019AAMAStutorial/>



MODELING ACTIONS



In the verification/model checking community



Action = an edge →



Action = an edge →
Epistemic =

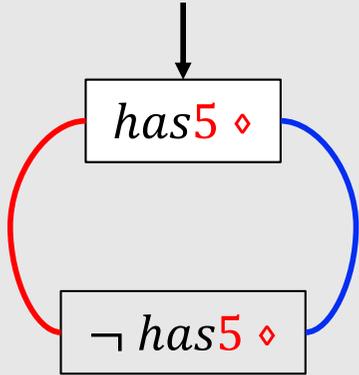
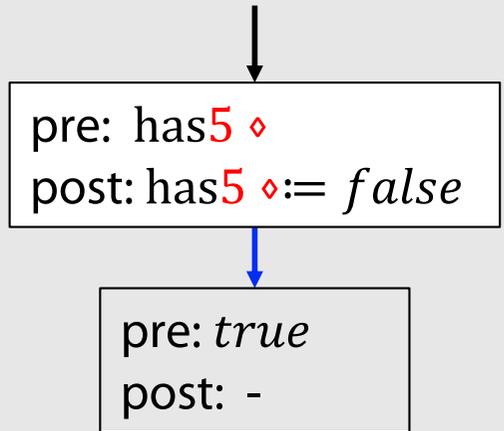
In philosophy and AI

Type of mechanism of actions is important

Type of mechanism	Example
Public/private announcement	She knows you hold 5 ♦
Public action	Play card 5 ♦
Private action	Secretely remove card 5 ♦
Belief revision	Revise believes (entailing $\neg p$) after being told p

- There is a dedicated logic for the first type of announcements: **PAL** (Public announcement logic)
- What kind of formalism to use to handle all of them?

Dynamic Epistemic Logic (DEL)

	State	Action
Classical planning		pre: has5 ♦ post: has5 ♦ := false
Logic DEL ^{1),2)} = Kripkean models of classical planning		

1) (Baltag et al., 1998)

2) (van Ditmarsch et al, 2007)

Note:

- Start states filled white
- Implicit self loops for red and blue agent

- Action: Privately announce to red agent removal of 5 ♦
- blue agent does not know

Computing the next state: product update

State	Action	Next State
(epistemic model)	(event model)	(updated epistemic model)

Some syntactic specifications/logics

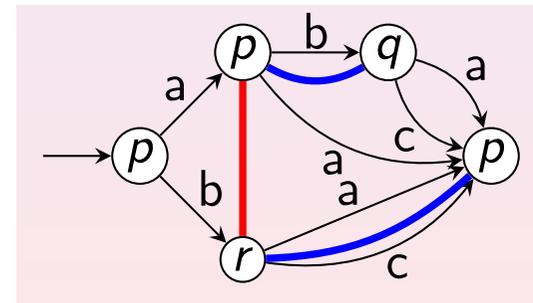
Logic	Example sentence
Game description language (Love et al. 2008), (Thielscher, 2017)	Agent a sees the game position
Flatland (Babiani et al, 2021), (Gasquet et al. 2014), (Gasquet et al, 2016),	Agent a sees agent b
Visibility atoms (Charrier et al, 2016)	Agent a sees truth value of p
Paying attention to public announcements (Bolander et al, 2016)	$B_a \text{payAtt}(b) \rightarrow [p!]B_a B_b p$
Asynchronous announcements (Knight et al, 2019)	$[p!][\text{read}_a]K_a p$
Epistemic gossip (Ditmarsch et al 2017)	$[\text{call}_{ab}]K_a \text{secret}_b$

From DEL to Epistemic Logics

Syntactic Specification



Models of DEL

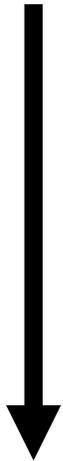


Epistemic temporal models

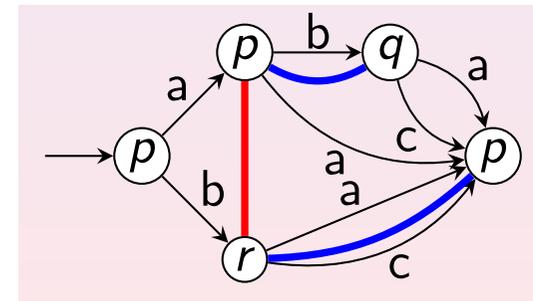
From DEL to Epistemic Logics

Syntactic Specification

- + Easy to specify
- + Succinct
- Ad-hoc languages
- Hand crafted semantics



Models of DEL

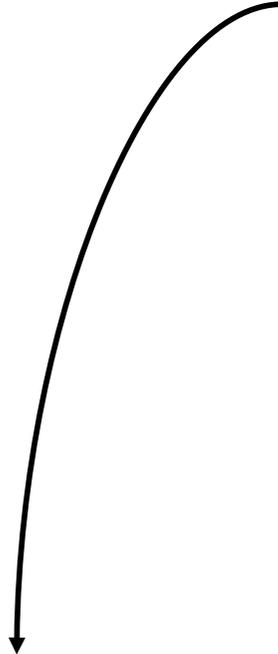


Epistemic temporal models

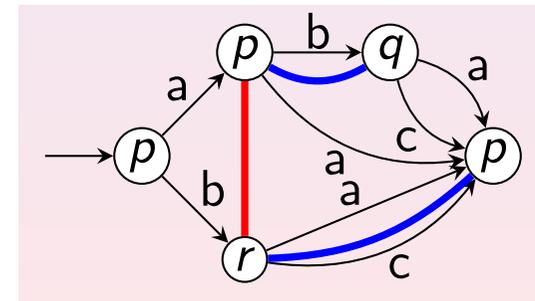
From DEL to Epistemic Temporal Logics

Syntactic Specification

- + Elegant Kripkean extension of classical planning
- + Succinct
- + Classification in terms of action types
- + Has probabilistic extension
- + Has extensions that encompass belief revision
- Perfect-recall only
- Synchronous only



Models of DEL



Epistemic temporal models

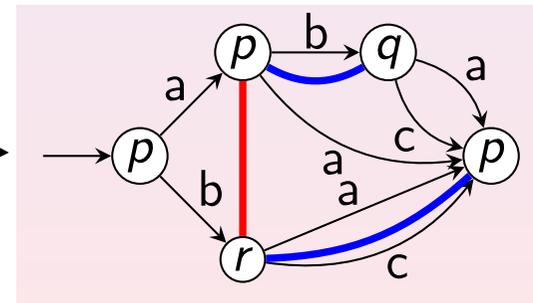
From DEL to Epistemic Temporal Logics

Syntactic Specification



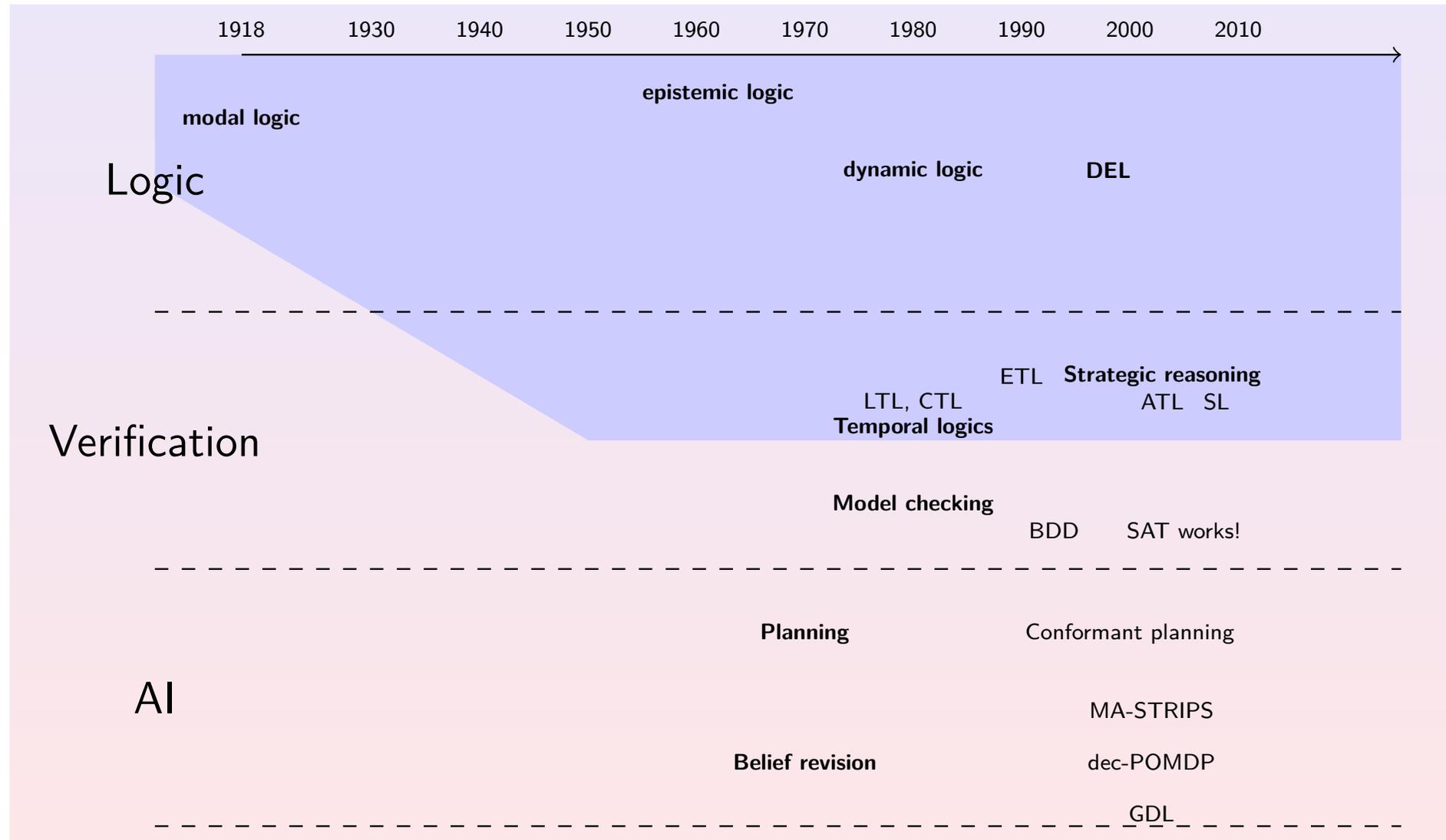
Models of DEL

- + Elegant
- + Allows for async/no perfect recall semantics
- Type of actions lost
- Not succinct (usually infinite)

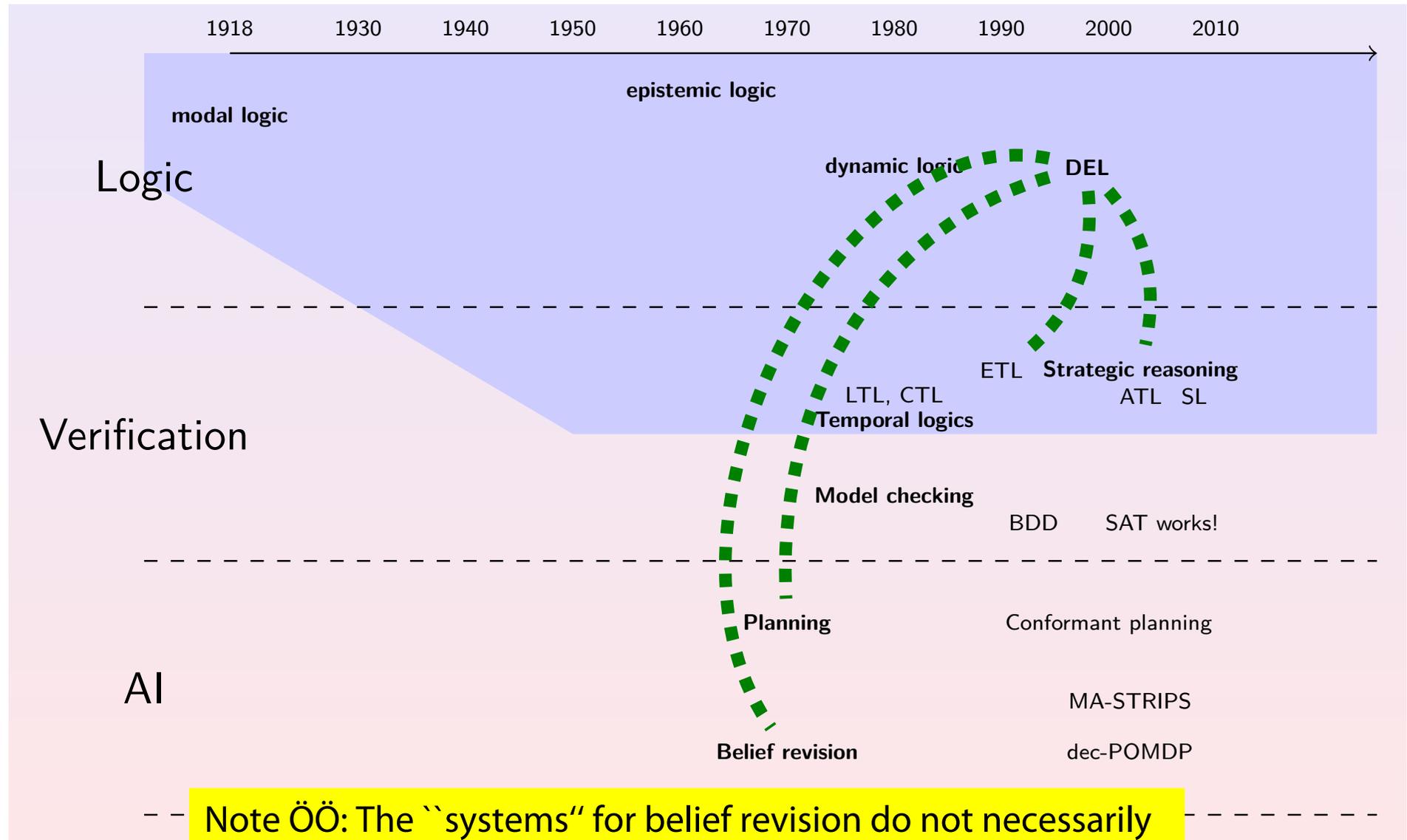


Epistemic temporal models

Timeline



Timeline



Note ÖÖ: The ``systems'' for belief revision do not necessarily reflect the classical approaches to belief revision

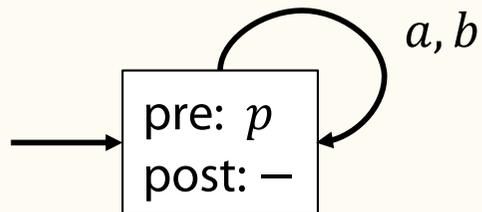
EVENT MODELS



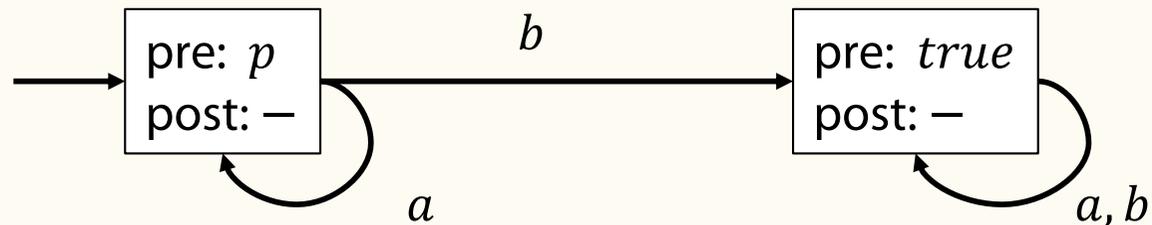
Examples of actions

(Baltag et al. 1998)

Example (public announcement of p)



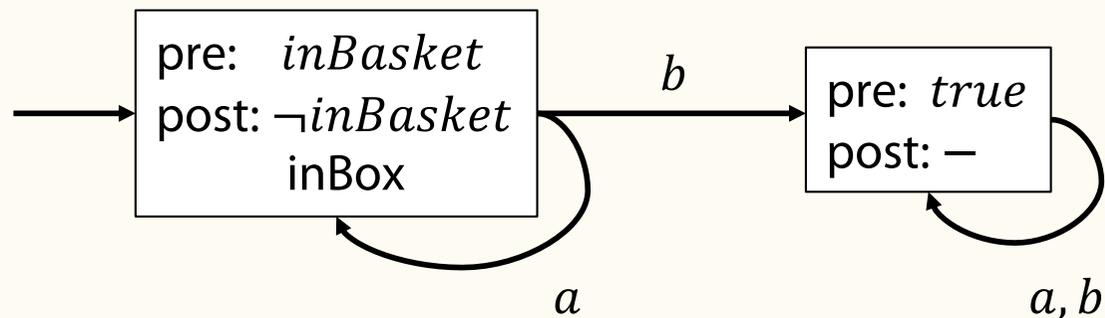
Example (Private announcement of p to a)



Examples of actions

Assume that agent a transfers a marble from a basket to a box - not seen by agent b

Example (Transfer marble from basket to box)

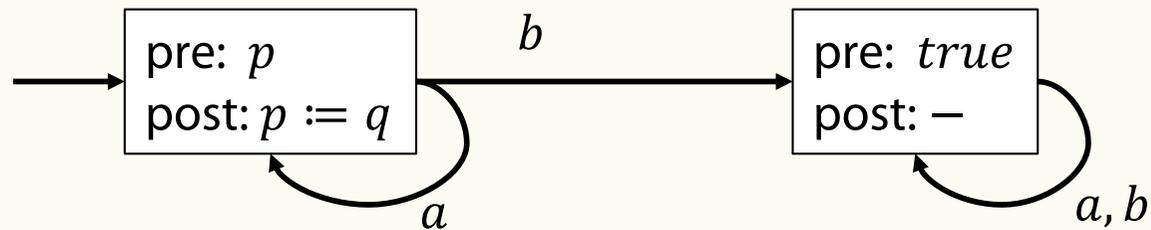


Formal Definition

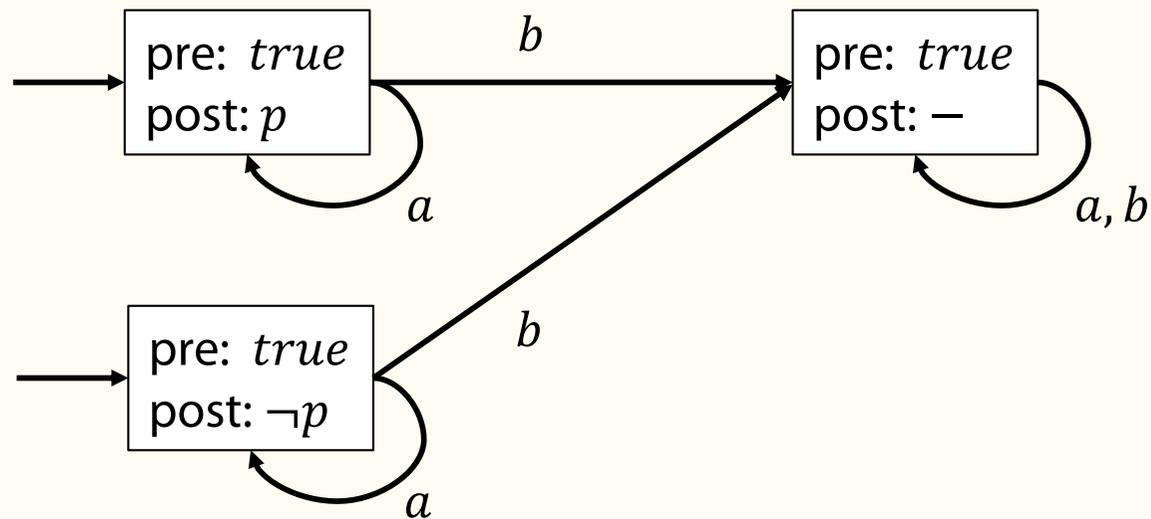
Definition

- An event model $\mathcal{E} = (E, (R_a^E)_{a \in AGT}, pre, post)$ is a tuple where
 - $E = \{e, e', \dots\}$ is a non-empty set of possible events
 - $R_a^E \subseteq E \times E$ is an accessibility relation on E for agent a
 - $pre: E \rightarrow \mathcal{L}_{EL}$ is a precondition function
 - $post: E \times AP \rightarrow \mathcal{L}_{EL}$ is a postcondition function
- A pair (\mathcal{E}, e) is called an **action** where e represents the actual event of (\mathcal{E}, e)
- A pair (\mathcal{E}, E_0) , for $E_0 \subseteq E$, is a **non-deterministic action**. The set E_0 is the set of **triggerable events**.

Example (Deterministic action = single-pointed event model)



Example (Non-deterministic action = multi-pointed event model)

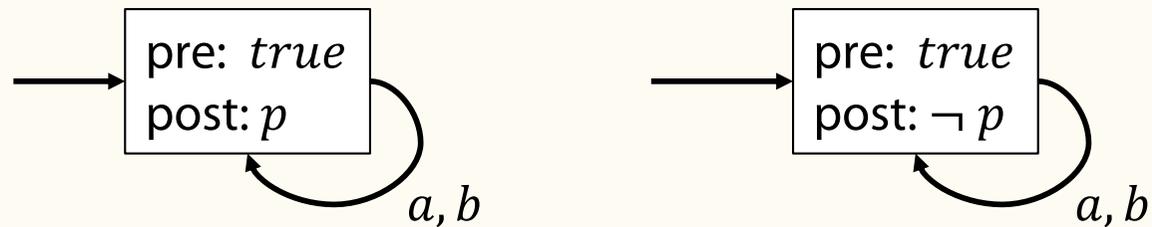


Public Actions

Definition

An action is said to be **public** if the accessibility relations in the underlying event model are self-loops

Example (public)

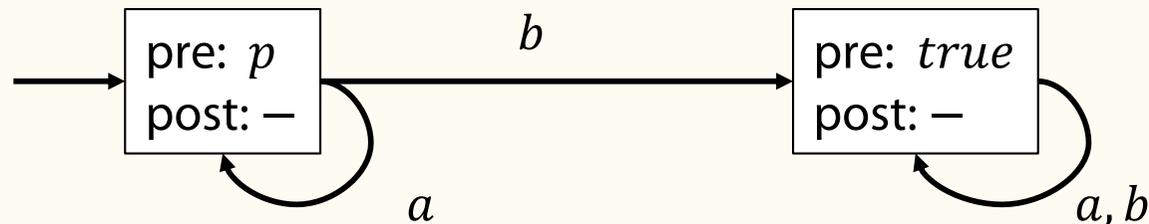


Non-ontic actions

Definition

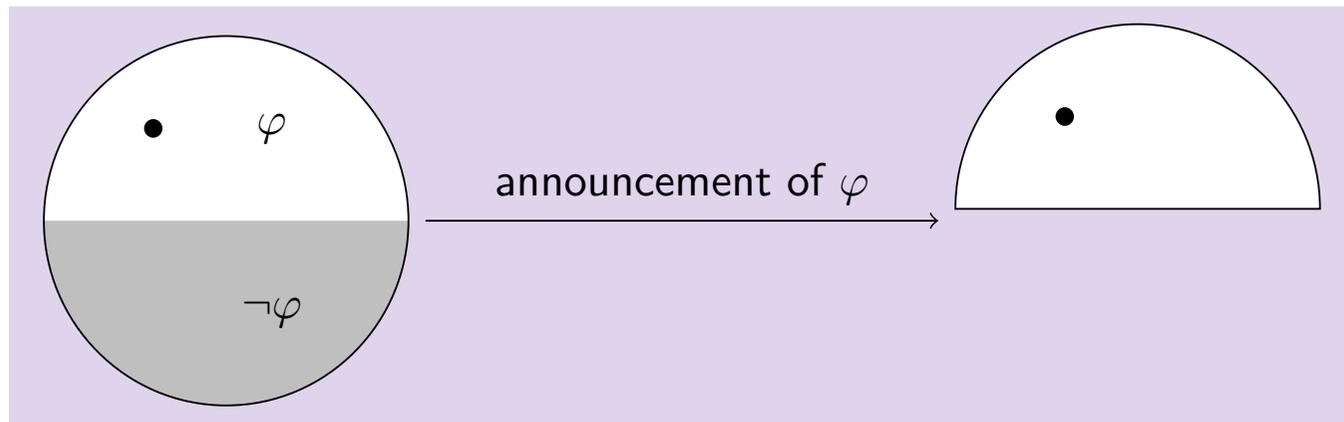
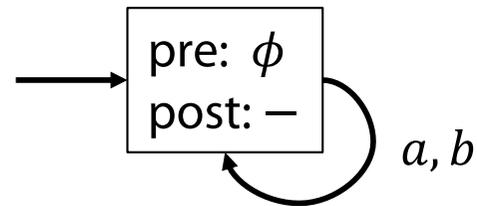
An action is said to be **non – ontic** if the postconditions are trivial:
for all $e \in E$, for all propositions $p \in AP$: $post(e, p) = p$

Example (non-ontic)



Effect of a public announcement

Publicly announcing ϕ leads to keeping only the ϕ worlds.



Can try this out on several examples in Hintikka's world.

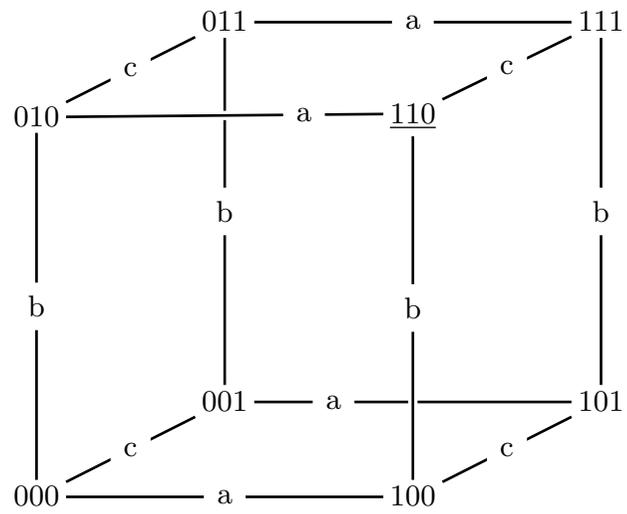
Muddy children Puzzle

„Three children (a,b,c) are playing in the mud. Father calls the children to the house, arranging them in a semicircle so that each child can clearly see every other child. “At least one of you has mud on your forehead”, says Father. The children look around, each examining every other child’s forehead. Of course, no child can examine his or her own. Father continues, “If you know whether your forehead is dirty, then step forward now”. No child steps forward. Father repeats himself a second time, “If you know whether your forehead is dirty, then step forward now”. Some (a,b) but not all of the children step forward. Father repeats himself a third time, “If you know whether your forehead is dirty, then step forward now”. All of the remaining children step forward. Explain why a,b stepped forward after two requests. (In general show: if m children are muddy then after m requests of the father those will step forward“

As promised we reconsider this puzzle in the context of **dynamic epistemic logic**

Muddy children: solution

- Children: Anne (a), Bill (b), Cath (c)
- Actual world: a, b muddy (m_a, m_b), c is not ($\neg m_c$)
- a argues:
 - $m_b, \neg m_c$
 - If $\neg m_a$ were the case, then b would see no one with mud on forehead and hence infer that m_b (due to the announcement of the father that someone has mud).
 - But b did not step forward so he does not know whether m_b
 - Therefore a steps forward next time
- b argues similarly



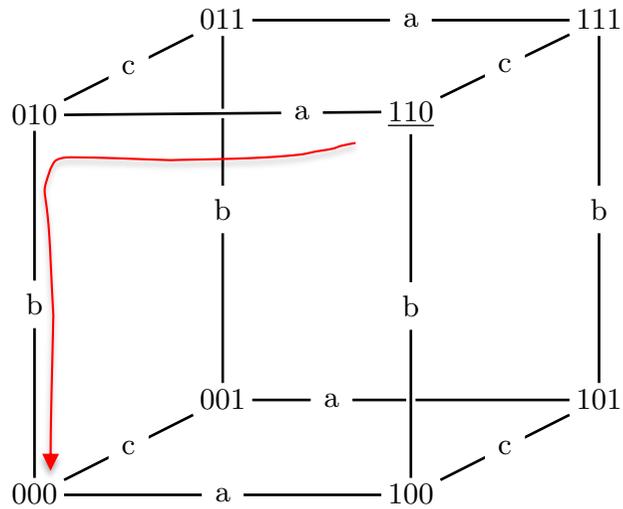
State 010 abbreviates

$\neg m_a \wedge m_b \wedge \neg m_c$, i.e.:

a has no mud;

b has mud;

c has no mud



State 010 abbreviates

$\neg m_a \wedge m_b \wedge \neg m_c$, i.e.:

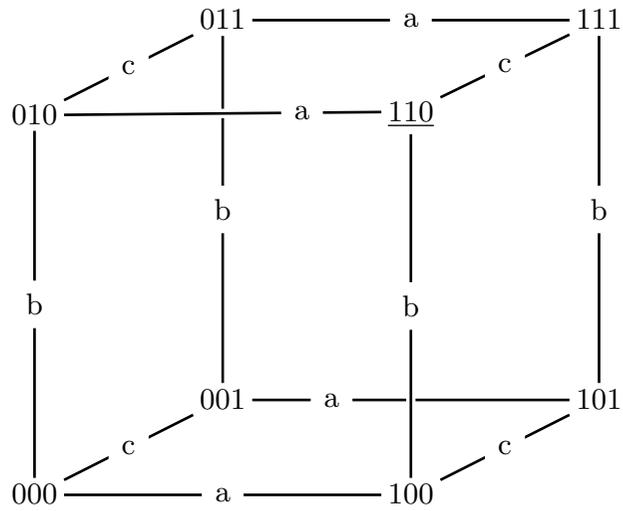
a has no mud;

b has mud;

c has no mud

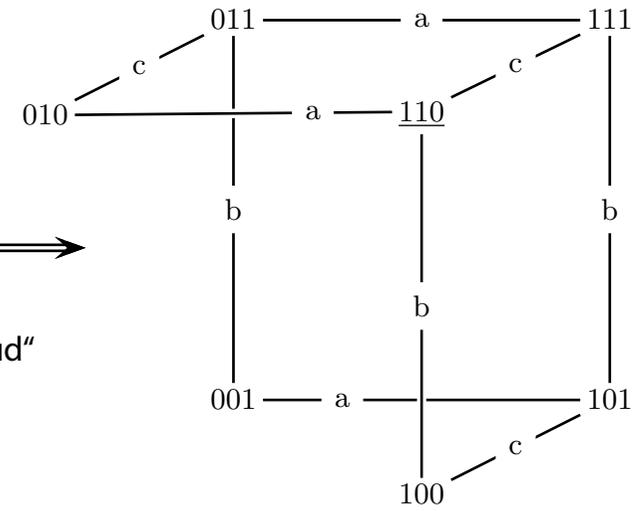
Actual state: 110

- Here, everybody knows that there is someone with mud on his face
- **But this is not common knowledge: *a* considers possible 010 where *b* considers 000 possible**

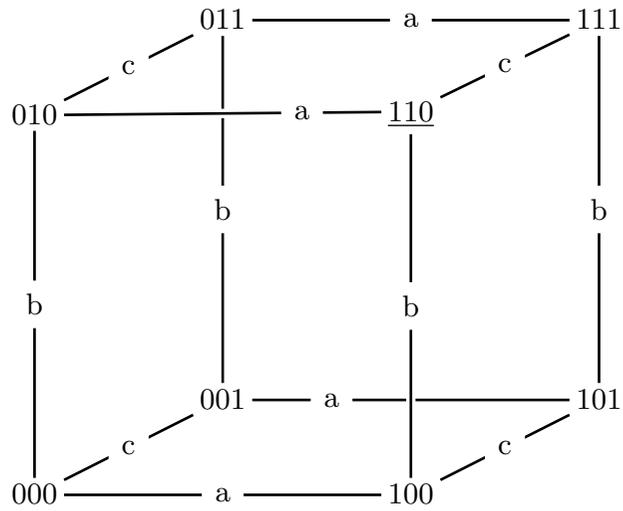


$\Longrightarrow m_a \vee m_b \vee m_c \Longrightarrow$

Father announces:
„One of you has mud“

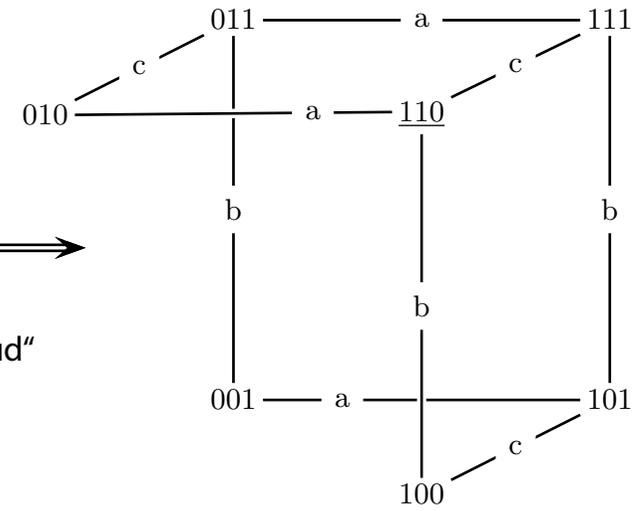


So world 000 gets eliminated



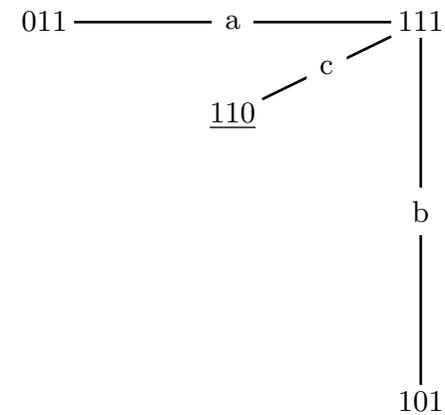
$$\Longleftrightarrow m_a \vee m_b \vee m_c \Longrightarrow$$

Father announces:
„One of you has mud“



No child steps forward:
 a, b, c : „I do not know whether
I have mud on my face“

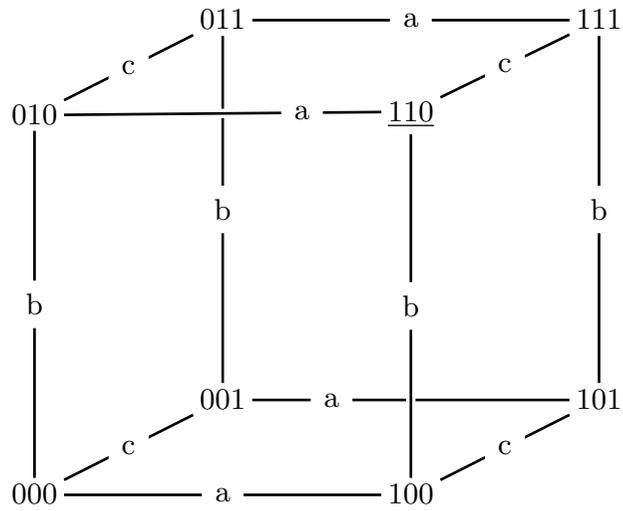
$$\neg(K_a m_a \vee K_a \neg m_a) \wedge \neg(K_b m_b \vee K_b \neg m_b) \wedge \neg(K_c m_c \vee K_c \neg m_c)$$



For example:

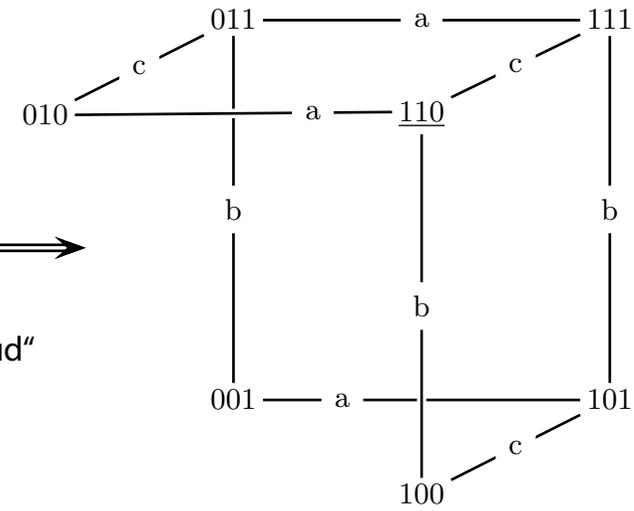
- $100 \models K_a m_a$
- Hence 100 gets eliminated





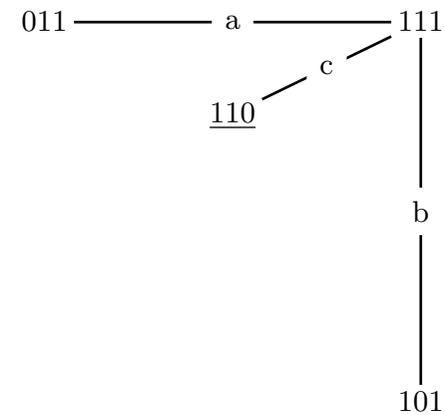
$\Longleftrightarrow m_a \vee m_b \vee m_c \Longrightarrow$

Father announces:
„One of you has mud“



No child steps forward:
 a, b, c : „I do not know whether
I have mud on my face“

$\neg(K_a m_a \vee K_a \neg m_a) \wedge \neg(K_b m_b \vee K_b \neg m_b) \wedge \neg(K_c m_c \vee K_c \neg m_c)$



110

$\Longleftarrow (K_a m_a \vee K_a \neg m_a) \wedge (K_b m_b \vee K_b \neg m_b)$

a and b step forward



Computing the next state: product update

State	Action	Next State
(epistemic model)	(event model)	(updated epistemic model)
	<pre>pre: has5 ♦ post: has5 ♦ := false</pre> <p style="text-align: center;">↓</p> <pre>pre: true post: -</pre>	

Formal Definition of Update Products

Definition

- Given
 - $\mathcal{M} = (W, \{R_a\}_{a \in AGT}, V)$ (epistemic model)
 - $\mathcal{E} = (E, (R_a^E)_{a \in AGT}, pre, post)$ (event model)
- define the **update product** of \mathcal{M} and \mathcal{E} as the epistemic model $\mathcal{M} \otimes \mathcal{E} = (W^\otimes, \{R_a^\otimes\}_{a \in AGT}, V^\otimes)$ where
 - $W^\otimes = \{(w, e) \in W \times E \mid \mathcal{M}, w \models pre(e)\}$
 - $R_a^\otimes = \{((w, e), (w', e')) \in W^\otimes \mid w R_a w' \text{ and } e R_a^E e'\}$
 - $V^\otimes((w, e)) = \{p \in AP \mid \mathcal{M}, w \models post(e, p)\}$

Pointed Update Products

Definition

The **successor state** of an epistemic state (\mathcal{M}, w) by action (\mathcal{E}, e) is

$$(\mathcal{M}, w) \otimes (\mathcal{E}, e) = (\mathcal{M} \otimes \mathcal{E}, (w, e))$$

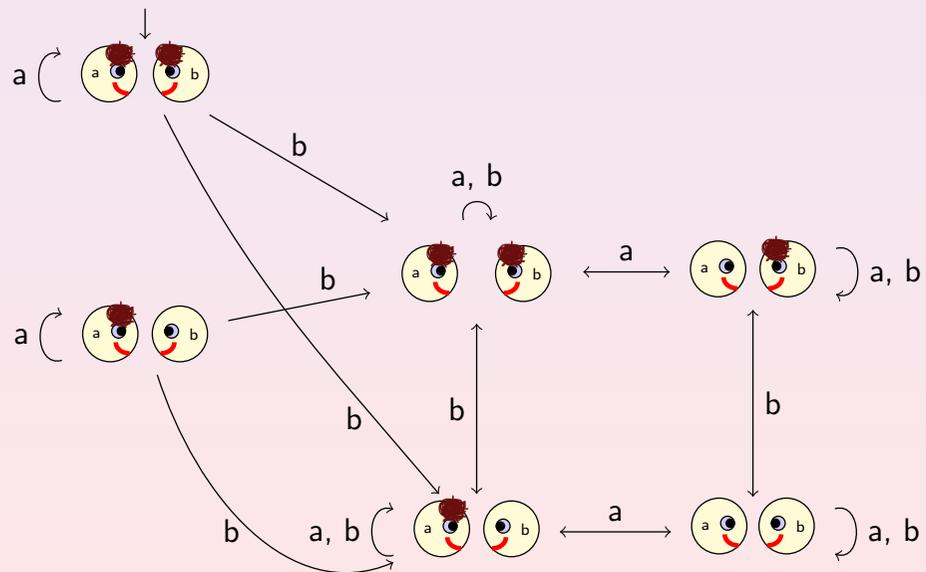
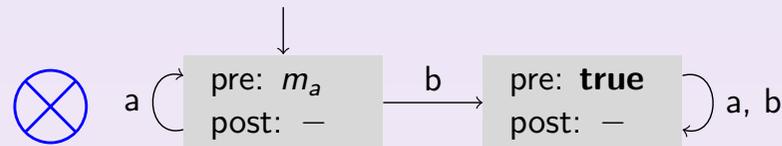
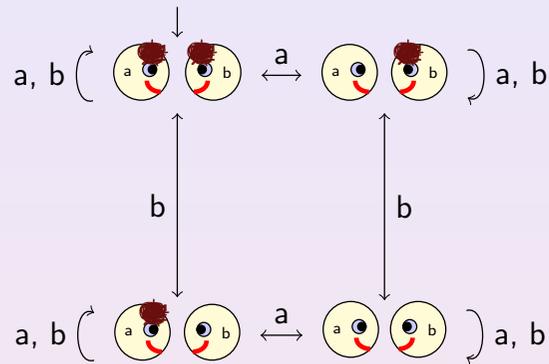
if $(\mathcal{M}, w) \models \text{pre}(e)$, otherwise it is undefined.

Notation

- Write e for (\mathcal{E}, e)
- Write $\text{'}we\text{'}$ for (w, e)
- Write $\mathcal{M} \otimes \mathcal{E}^n$ for $\mathcal{M} \otimes \mathcal{E} \otimes \mathcal{E} \dots \otimes \mathcal{E}$ (n-times)
- Write $we_1 \dots e_n \models \phi$ for $\mathcal{M} \otimes \mathcal{E}^n, we_1 \dots e_n \models \phi$,

Agent a gets private message about its mud

Example (Update Product)



Dynamic epistemic logic \mathcal{L}_{DELCK}

Definition

The language \mathcal{L}_{DELCK} extends \mathcal{L}_{ELCK} with dynamic (possibility) modalities $\langle \mathcal{E}, E_0 \rangle$ according to the following BNF:

$$\phi ::= \top \mid p \mid \neg\phi \mid (\phi \vee \phi) \mid K_a\phi \mid C_G\phi \mid \langle \mathcal{E}, E_0 \rangle \phi$$

Definition

The modelling relation \models for \mathcal{L}_{ELCK} is extended with the following clause:

$$\begin{aligned} \mathcal{M}, w \models \langle \mathcal{E}, E_0 \rangle \phi & \text{ iff there exists } e \in E_0 \text{ such that} \\ \mathcal{M}, w \models pre(e) & \text{ and } \mathcal{M} \otimes \mathcal{E}, (w, e) \models \phi \end{aligned}$$

Dual operator

Definition (Dual operator)

$$[\mathcal{E}, E_0]\phi := \neg \langle \mathcal{E}, E_0 \rangle \neg \phi$$

The induced semantics is

$\mathcal{M}, w \models [\mathcal{E}, E_0]\phi$ iff for all $e \in E_0$ we have:

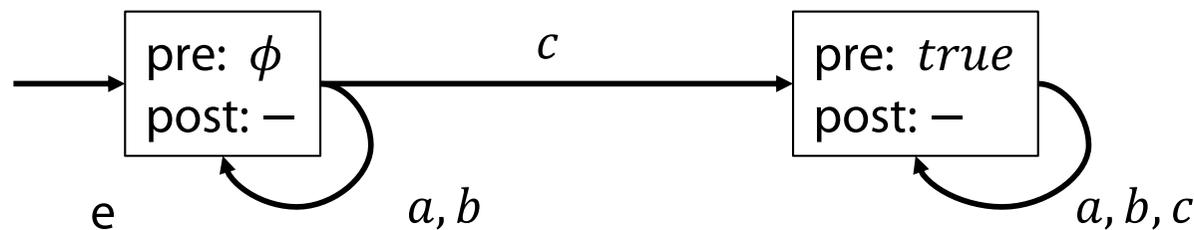
If $\mathcal{M}, w \models pre(e)$ then $\mathcal{M} \otimes \mathcal{E}, (w, e) \models \phi$

Wake-up: Group announcements

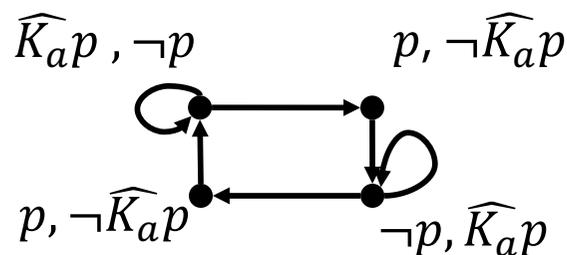
- Q: Consider the following secure group-announcements
 - Agents: $AGT = \{a, b, c\}$
 - ϕ announced publicly within group $\{a, b\}$;
 c does not even know about this announcement
- 1. How to model this kind of announcement?
- 2. Once can show that the announcement creates common knowledge for $\{a, b\}$ w.r.t. ϕ if ϕ is atomic. Give a counterexample for non-atomic ϕ
- 3. Model the fact that c does not know or even suspect that the announcement happened
- 4. How would you change the model of 1. to model that C is suspicious?

Answers

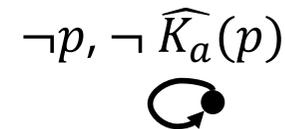
- This is the model $(\mathcal{E}, \{e\})$ of the secure announcement



- Creation of common knowledge means:
 $(\mathcal{M}, w) \models \langle \mathcal{E}, \{e\} \rangle C_{\{a,b\}} \phi$. This does not hold if,
 e.g., $\phi = \widehat{K}_a p$. Take the simplest case of one agent a .



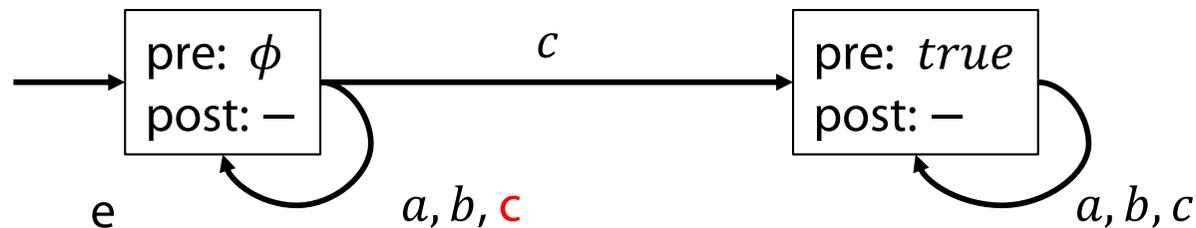
After public
announcement: $\widehat{K}_a p$



Answers

3. c does not know or even suspect that the announcement happened: $\models K_c \phi \leftrightarrow \langle \varepsilon, \{e\} \rangle K_c \phi$

4.



Expressivity and Succinctness

Theorem (Baltag 98)

DEL and EL have the same expressivity

Proof idea: Remove dynamic operators $[\mathcal{E}, E]$ as demonstrated here for public announcements:

- Remember
 $[\phi!]\psi$: if ϕ holds then after having announced ϕ publicly, ψ holds.
- $[\phi!]p$: says the same as $(\phi \rightarrow p)$
- $[\phi!](\psi \wedge \chi)$: says the same as $([\phi!]\psi \wedge [\phi!]\chi)$
- $[\phi!]\neg\psi$: says the same as $(\phi \rightarrow \neg[\phi!]\psi)$
- $[\phi!]K_a\psi$: says the same as $(\phi \rightarrow K_a[\phi!]\psi)$
- $[\phi!][\psi!]\chi$: says the same as $([\phi \wedge [\phi!]\psi!]\chi)$

Theorem (Lutz 2006)

DEL is more succinct

Uhhh, a lecture with a hopefully useful

APPENDIX



References

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Color Convention in this course

- Formulae, when occurring inline
- Newly introduced terminology and definitions 
- Important **results (observations, theorems)** as well as emphasizing some aspects 
- **Examples** are given with standard orange with possibly light orange frame 
- Comments and notes 
- Algorithms 